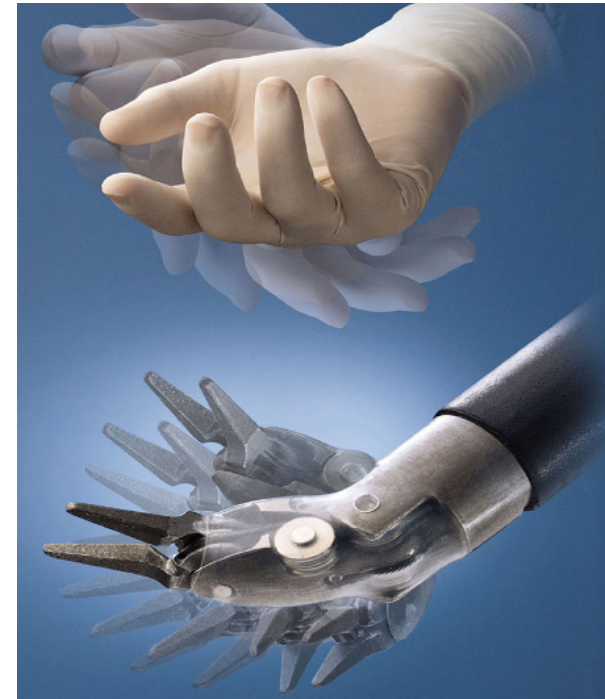


Automation of Surgical Tasks

Stefanie Speidel
University of Karlsruhe, Germany



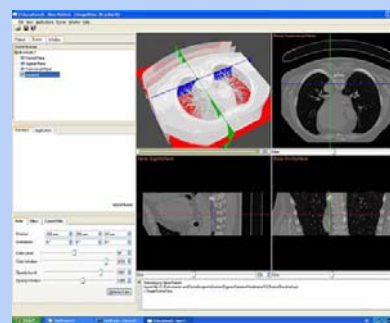
Source: Intuitive Surgical



Source: Intuitive Surgical

CSE

- Institute of Computer Science and Engineering
Chair Prof. Dillmann (30 Researchers, 4 Admin Staff)
- Research Areas:
 - Humanoid Robots
 - Adaptive Systems
 - Mobile Platforms
 - Augmented Reality
 - Walking Machines
 - Diagnosis and Inspection
 - Interactive Learning
 - Medical Modeling and Simulation





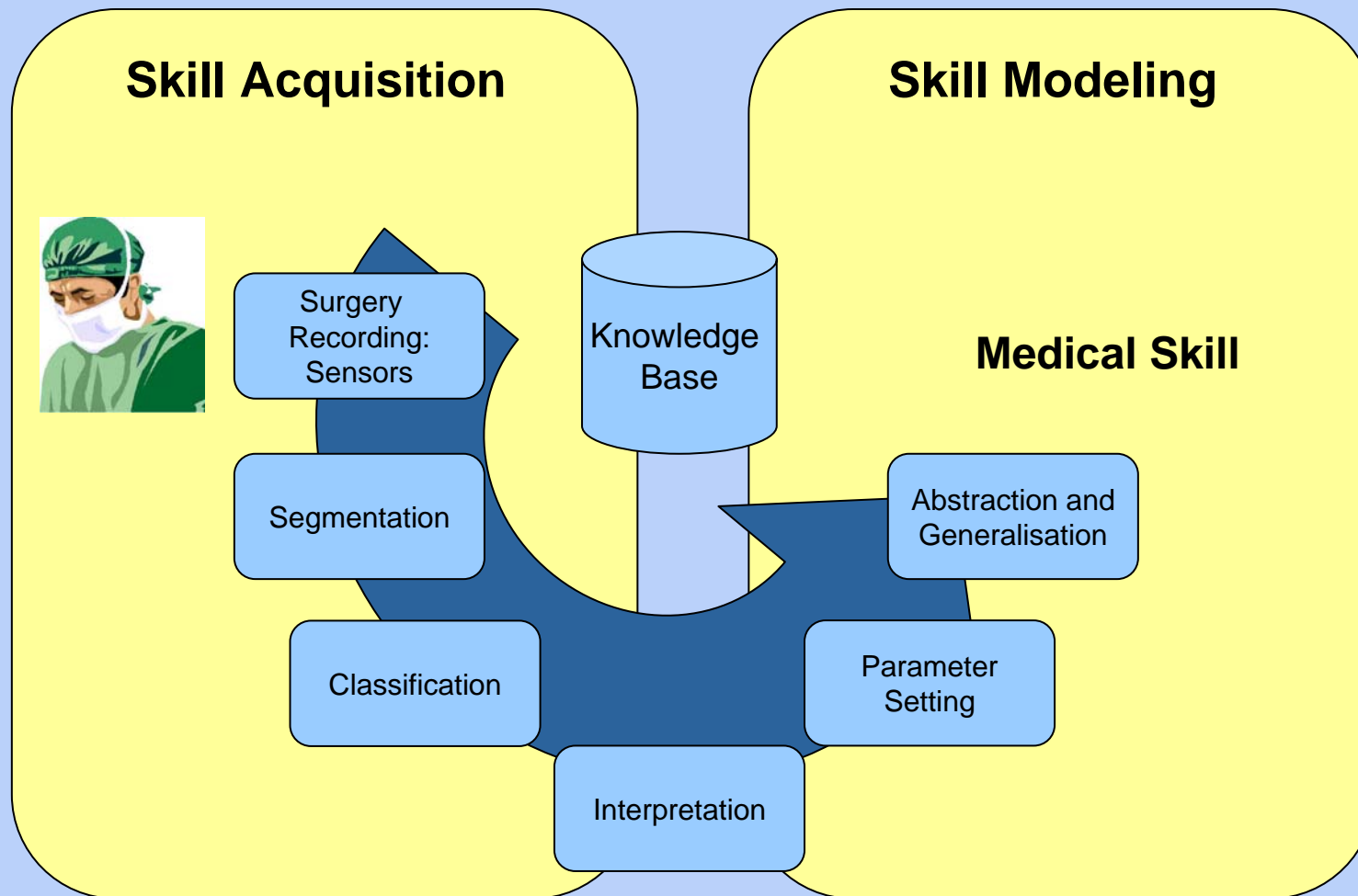
Research Training Group: Intelligent Surgery

- Cooperation between the University of Heidelberg, University of Karlsruhe and German Cancer Research Center (DKFZ)



- Development of new computer-based methods for the future workplace in visceral surgery
- Projects:
 - Perioperative Data Management
 - Planning of Surgical Interventions
 - Navigation
 - Telemanipulation
 - Man-Machine-Interface

Programming by Demonstration in Medicine



Application

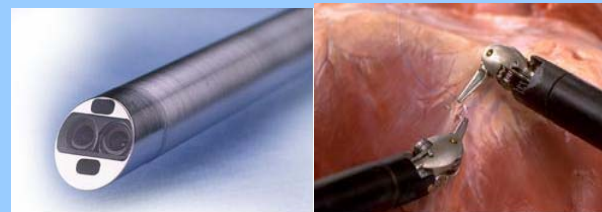
- DaVinci Surgical System

Console



Source: Intuitive Surgical

Manipulator



Source: Intuitive Surgical

Skill Acquisition

- Objective: Segmentation/Classification of Surgery Sequences

Sensors



Image
Enhancement



Navigation



Segmentation



Classification



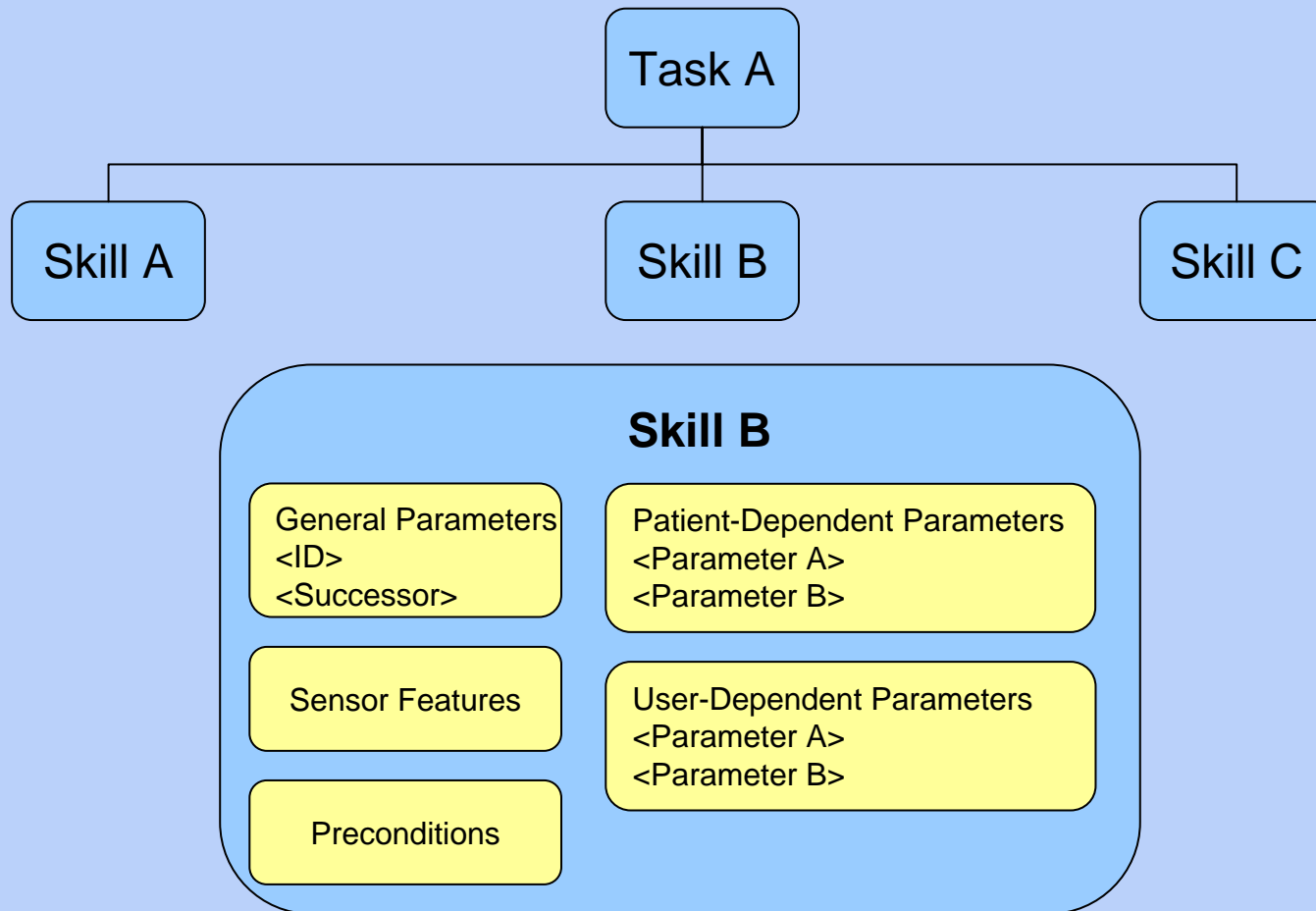
Surgeon
Evaluation



Skill/Task

Skill Modeling

- Objective: Technical Presentation and Description of Surgical Tasks



Thank you for your attention !

