Dispersal Evolution: Bridging the gap between the two H's.

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W.D. HAMILTON (Hamilton & May 1977)



A. HASTINGS (Hastings 1983)





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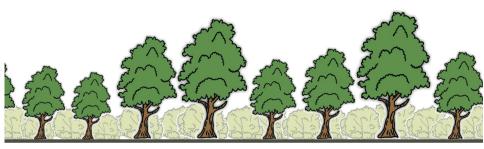


A. HASTINGS (Hastings 1983)

Competition between relatives

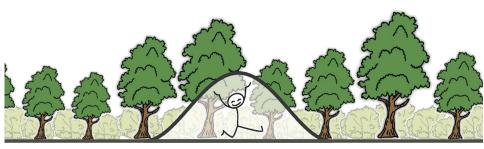
Spatial heterogeneities







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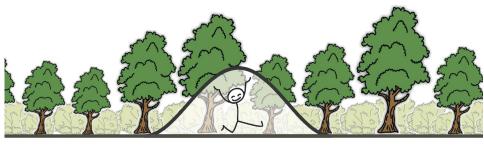




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Suppose that

- two (or more) distinct types of individuals are present
- that only differ in their dispersal behaviour (kernel).





Formally: The model equations

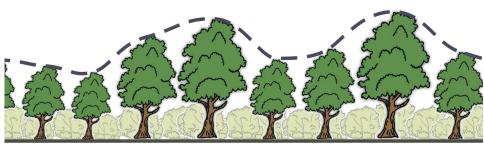
$$\partial_t N_T = -\partial_x J_T + N_T r,$$

$$\partial_t p_i = \frac{1}{N_T} \left(-\partial_x J_i + p_i \partial_x J_T \right).$$

- N_T ... density of the total population
- p_i ... frequency of dispersal strategy i
- r ... local growth rate
- J_i and J_T ... fluxes of type-*i* individuals and total flux









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The abundance of resources defines a carrying capacity κ .

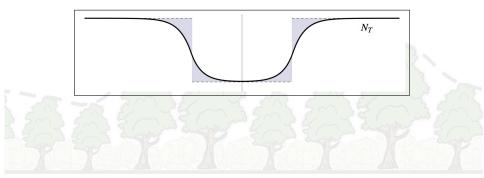
- No dispersal: Population density attains carrying capacity.
- Dispersal usually blurs out the population density profile.





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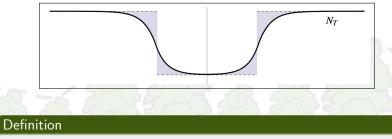
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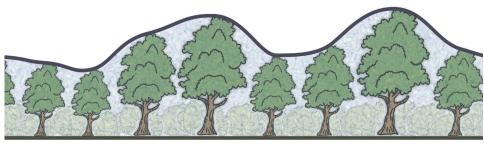
We call a dispersal strategy **balanced** if $N_T = \kappa$ is a stable solution of the population density dynamics (given that all individuals adopt the dispersal strategy).



Balanced dispersal is evolutionarily stable

Result 1

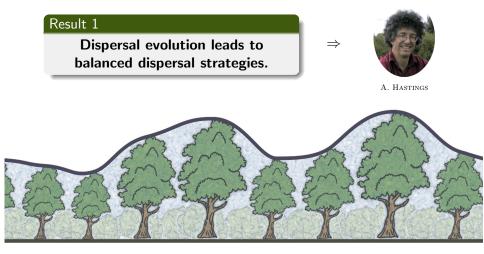
Dispersal evolution leads to balanced dispersal strategies.





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Consider two dispersal types, R and I, that are both balanced and let the variances of their dispersal kernels be V and V + v.





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Then, the "faster" type never decreases in total abundance, since

$$\partial_t \int N_I dx = \frac{v N_T}{2} \int (\partial_x p_I)^2 dx \ge 0.$$

Result 2

Within the class of balanced dispersal strategies, increased dispersal is selected for.



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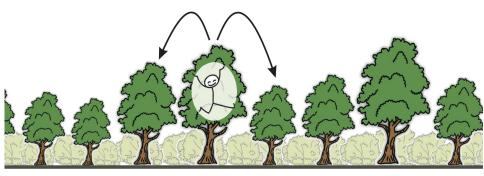
- Adding white noise with this variance causes the rate of increase to diverge $(\partial_t \int N_I dx \propto \Delta x)$.
- Numerical simulations (i.e., discretizations) show a gradual increase in numbers of the faster type.

Note

The continuous equations cannot quantify the selective advantage of increased dispersal in this case. Details of the spatial scale matter!



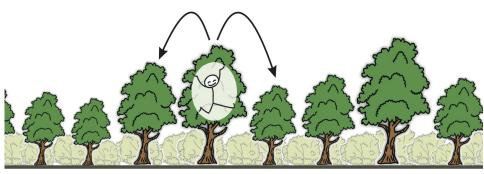
Discrete time and space





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+ stochastic sampling between generations.



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In the stochastic model, we are interested in the **expected change** in total abundance of the faster type.





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Result 3 (mathematical version)

$$\mathbb{E}\left[\Delta \mathcal{N}_{l}^{total}\right] = m \mathcal{N} \sigma_{p}^{2}(1-\rho),$$

where

- $\mathcal N$ is the number of individuals per patch,
- J is the number of patches in the habitat,
- *m* is the increase of migration rate of the faster type,
- σ_p^2 is the spatial type-frequency variance, and
- ρ is the correlation of type frequencies between adjacent patches.



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Remark I

Let P be the average frequency of the faster type, then

$$\mathbb{E}[\Delta P] \approx \frac{m}{4\mathcal{N}\mathcal{M}}P(1-P),$$

where \mathcal{M} is the base migration rate.



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• This is analogous to haploid selection with $s = \frac{m}{4MM}$.



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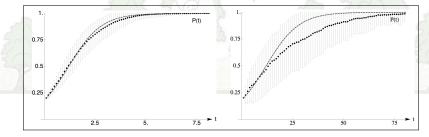
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- It can be used to compare with numerical simulations.

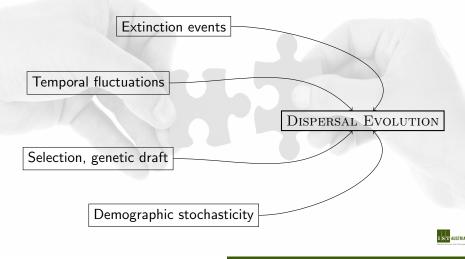




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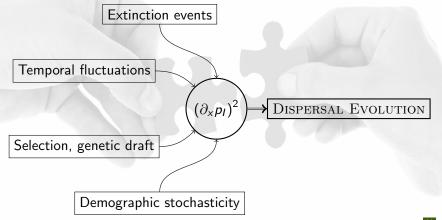
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- Within the class of balanced dispersal strategies, increased dispersal is selected for by, e.g., stochastic sampling. The emerging sampling variances directly translate into measures of relatedness.
- 3 Details of spatial scaling matter to quantify this effect. This shows a limitation to the use of continuous differential equations.
- The spatial variance of type frequencies can capture various stochastic factors that influence the evolution of dispersal. Does this unify different aspects of dispersal evolution?



Acknowledgements



NICK BARTON



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THANK YOU FOR YOUR ATTENTION!