

Parallel Manipulators: From kinematics and control theory to running prototypes

PKM 2016 Schedule

	8:45 – 10:15 (1.5h)	10:15 - 10:45	10:45-12.15 (1.5h)	12:15 - 14:15	14:15 – 15:45 (1.5h)	15:45 - 16:15	16:15 – 18:15 (2h)
Monday	Kinematics	Coffee break	Dynamics	Lunch	Introduction to ADAMS/Simulink	Coffee break	Introduction to ADAMS/Simulink
	Lecture Speaker : S. Caro		Lecture Speaker : S. Briot		Simulation lab 1		Simulation lab 2
Tuesday	Kinematics	Coffee break	Control	Lunch	Project	Coffee break	Project
	Plenary lecture Speaker : M. Husty		Lecture Speaker : A. Chemori		Simulation lab / Experiments Lab		Simulation lab / Experiments Lab
Wednesday	Dynamics & Control	Coffee break	Design	Lunch	Industrial Issues	Coffee break	Social event
	Plenary lecture Speaker : A. Müller		Lecture Speaker : O. Company		Plenary Lecture Speaker : M. Bouri		
Thursday	Advanced Control	Coffee break	Cable-Driven Parallel Robots	Lunch	Project	Coffee break	Project
	Lecture Speaker : A. Chemori		Lecture Speaker : M. Gouttefarde		Simulation lab / Experiments Lab		Simulation lab / Experiments Lab
Friday	Cable-Driven Parallel Robots	Coffee break	Performance indices	Lunch	Round table Animated by: S. Caro & S. Briot	Farewell Reception	
	Plenary lecture Speaker : J-P. Merlet		Lecture Speaker : S. Krut				