

# Modular Multiplication and Base Extensions in Residue Number Systems

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## Abstract

*We present a new RNS modular multiplication for very large operands. The algorithm is based on Montgomery's method adapted to residue arithmetic. By choosing the moduli of the RNS system reasonably large, an effect corresponding to a redundant high-radix implementation is achieved, due to the carry-free nature of residue arithmetic. The actual computation in the multiplication takes place in constant time, where the unit of time is a few simple residue operations. However, it is necessary twice to convert values from one residue system into another, operations which take  $\mathcal{O}(n)$  time on  $\mathcal{O}(n)$  processors, where  $n$  is the number of moduli in the RNS systems. Thus these conversions are the bottlenecks of the method, and any future improvements in RNS base conversions, or the use of particular residue systems, can immediately be applied.*

## 1. Introduction

Many cryptosystems [16, 5, 11] employ modular multiplications and exponentiation on very large numbers (possibly one or two thousand bits), and various algorithms have been proposed [3, 9, 23, 21, 20, 12]. Most of them use redundant (possibly high-radix) standard number systems and Montgomery's modular multiplication [10]. On the other hand the Residue Number System (RNS) is also of particular interest, because of the parallel and carry free nature of its arithmetic [19, 22].

Note that the Montgomery modular multiplication takes place in a modified residue system, where

operands and results contain an extra factor  $M$ , for some suitably chosen value of  $M$ . Mapping in and out of this residue system is simple, and its cost may be amortized over many multiplications, when these are used for modular exponentiation. However, if applied to RSA encryption [1] as well as decryption (i.e., both ends using the same RNS system), we may just as well assume that the message itself is considered the RNS representation of a number, thus mapping in and out of the RNS system is not necessary. This is particularly interesting for the Fiat-Shamir authentication protocol [5, 11], where only modular multiplications are used (no exponentiation). We shall thus not further discuss the implications of using this modified residue system.

We have previously [1, 2] proposed two RNS versions of the Montgomery algorithm for modular multiplication. To compute  $A * B \bmod N$ , an intermediate value  $Q$  is to be determined such that  $A * B + Q * N$  is a multiple of  $M$ , the product of the moduli of the RNS base. The quotient  $Q$  was computed digit-wise in a Mixed Radix System (MRS). The result of one pass of the algorithm was then obtained in an auxiliary RNS base, using  $\mathcal{O}(n)$  (the size of the RNS base) RNS computations. The first version was a direct translation of the classical Montgomery algorithm for weighted representations to RNS. We just used MRS as a weighted system associated with the RNS. The second version then was an improvement of the first: we showed that a MRS representation of  $A$  was not necessary and that we could precompute some values to reduce the complexity of the algorithm.

Here we propose to compute  $Q$  with a single parallel RNS calculation in one RNS base, but to be able to divide out the factor  $M$  it is neces-

sary to convert  $Q$  into an auxiliary RNS base, such that we can evaluate the result of the algorithm,  $R = (A * B + Q * N) * M^{-1}$ , in the auxiliary RNS base. The major costs now lie in conversions from one base into another. Two such  $\mathcal{O}(n)$ -time parallel conversion algorithms are described, where the first and classical one based on [17] unfortunately cannot be employed for the conversion of  $Q$ . But it can be used to convert the result  $R$  back into the original base, allowing it to be used as an operand for another multiplication. For the first conversion it turns out to be sufficient to allow an offset to be present in the residue, i.e., it need not be properly modulo reduced, it just has to belong to the correct residue class. Then using the above mentioned method for converting back to the original system removes the un-wanted offset. Any other base extension algorithm (without extra modulus) may be appropriate. Note that for regularity purposes, we want base conversions which can be executed on simple cells (the  $n$  residue “channels”), which excludes the use of  $\mathcal{O}(\log(n))$ -time algorithms where multi-operand addition in a cell is performed in a tree structure.

Section 2 introduces the notation used in the residue and the mixed radix systems employed. In Section 3 the Montgomery algorithm is briefly introduced and its adaption to the RNS system is discussed, together with a brief proof of correctness. Section 4 then introduces the two conversion algorithms and their use for our new modular multiplication algorithm. Section 5 combines the basic RNS multiplication with the conversions, and finally Section 6 contains some conclusions.

## 2. The Residue Number Systems

We begin with a short summary of the RNS system, and introduce our terminology:

- The vector  $\{m_1, m_2, \dots, m_n\}$  forms a set of moduli, called the RNS-base  $\mathcal{B}_n$ , where the  $m_i$ 's are mutually prime.
- $M$  is the value of the product  $\prod_{i=1}^n m_i$ .
- The vector  $\{x_1, \dots, x_n\}$  is the RNS representation of  $X$ , a positive integer less than  $M$ , where

$$x_i = |X|_{m_i} = X \bmod m_i$$

Due to the Chinese Remainder Theorem, any  $X$  less than  $M$  has one and only one RNS-representation. Addition and multiplication modulo  $M$  can be implemented in parallel in linear space ( $\mathcal{O}(n)$  channels), and performed in one single step

without any carry propagation, by defining  $+_{RNS}$  and  $\times_{RNS}$  as component-wise operations [8, 19, 22]:

$$A +_{RNS} B \sim |a_j + b_j|_{m_j}, \text{ for } j \in \{1, \dots, n\}$$

$$A \times_{RNS} B \sim |a_j \times b_j|_{m_j}, \text{ for } j \in \{1, \dots, n\}.$$

We also define “exact division”,  $A \div_{RNS} B$ , assuming that  $B$  divides  $A$ ,  $\text{gcd}(B, M) = 1$ :

$$R = A \div_{RNS} B \sim \hat{r}_j \text{ for } j \in \{1, \dots, n\}$$

where  $\hat{r}_j$  is computed as:

$$\hat{r}_j = \left| a_j \times (B)_{m_j}^{-1} \right|_{m_j}, \quad (1)$$

where  $(X)_{m_j}^{-1}$  denotes the inverse of  $X$  modulo  $m_j$  for  $X$  and  $m_j$  relatively prime.

We shall also introduce an auxiliary base  $\tilde{\mathcal{B}}_{\tilde{M}} = \{\tilde{m}_1, \tilde{m}_2, \dots, \tilde{m}_{\tilde{n}}\}$  with  $\tilde{M} = \prod_{i=1}^{\tilde{n}} \tilde{m}_i$ , where  $\tilde{M}$  is coprime to  $M$ . In this system the RNS representations of an integer  $X$  is:

$$X_{RNS} = \{\tilde{x}_1, \tilde{x}_2, \dots, \tilde{x}_{\tilde{n}}\}$$

and we shall assume that  $\tilde{M} > M$ .

## 3. The RNS algorithm

Based on the original M-reduce algorithm by Montgomery [10] we want to compute the modular product,  $ABM^{-1} \bmod N$ , for given  $A, B, N$  and  $M$ , where  $N < M$  and  $M$  is chosen such that reductions modulo  $M$  are “easy”, which will be the case when  $M$  is the product of the moduli of the RNS system used. As we shall see below, to be able to perform the computations in RNS arithmetic, we will have to use two RNS systems as also used in [1, 2, 15, 7]. Hence the operands  $A$  and  $B$  must be available in both systems. And when for exponentiations the result of a multiplication may be used again as input for other multiplications, the result should also be delivered in both systems.

In the M-reduce algorithm we compute an intermediate value  $Q$ ,  $Q < M$ , such that:  $A * B + Q * N$  is a multiple of  $M$ . Then in RNS the representation of  $A * B + Q * N$  in  $\mathcal{B}_n$  is composed only of zeros. As we have  $Q < M$ ,  $Q$  can be easily obtained in the RNS base  $\mathcal{B}_n$ . For  $i = 1..n$ , we have  $(a_i * b_i + q_i * n_i) \bmod m_i = 0$ , and thus deduce that for  $i = 1..n$  we have:

$$q_i = (-a_i * b_i) * (n_i)_{m_i}^{-1} \bmod m_i. \quad (2)$$

But note that since  $A * B + Q * N$  is a multiple of  $M$ , it cannot be represented in the system with base  $\mathcal{B}_n$ . Hence to compute the final result  $R = (A * B + Q * N) * M^{-1}$  it is necessary to compute

its value in an RNS system using another base  $\tilde{\mathcal{B}}_{\tilde{n}}$ , and thus not only to have  $A, B$  and  $N$  available in  $\tilde{\mathcal{B}}_{\tilde{n}}$ , but also to convert  $Q$  into that system. Hence we obtain the following algorithm:

**Algorithm 1** *RNS Modular Multiplication*

**Stimulus:** *A residue base  $\mathcal{B}_n$ ,  $\{m_1, m_2, \dots, m_n\}$ , where  $M = \prod_{i=1}^n m_i$*

*A residue base  $\tilde{\mathcal{B}}_{\tilde{n}}$ ,  $\{\tilde{m}_1, \tilde{m}_2, \dots, \tilde{m}_{\tilde{n}}\}$ , where  $\tilde{M} = \prod_{i=1}^{\tilde{n}} \tilde{m}_i$*

*where  $\gcd(M, \tilde{M}) = 1$  and  $M < \tilde{M}$*

*A modulus  $N$  expressed in RNS in the two bases, with  $\gcd(N, M) = 1$ ,*

*and  $0 < 2N < M$*

*Integer  $A$  given in RNS in the two RNS bases*

*Integer  $B$  given in RNS in the two RNS bases with  $A * B < M * N$*

**Response:** *A ninteger  $R < 2N$  expressed in the two RNS bases such that*

$$R \equiv ABM^{-1} \pmod{N}$$

**Method:**  *$Q \leftarrow (-A \times_{RNS} B) \times_{RNS} N^{-1}$  in  $\mathcal{B}_n$*

*Conversion of the representation of  $Q$  from  $\mathcal{B}_n$  to  $\tilde{\mathcal{B}}_{\tilde{n}}$*

$$R \leftarrow (A \times_{RNS} B +_{RNS} Q \times_{RNS} N) \times_{RNS} M^{-1} \text{ in } \tilde{\mathcal{B}}_{\tilde{n}}$$

*Conversion of the representation of  $R$  from  $\tilde{\mathcal{B}}_{\tilde{n}}$  to  $\mathcal{B}_n$*

Since  $Q < M$  and  $AB < MN$  it follows that  $R < 2N$ , and it is easy to see that the result  $R$  satisfies  $R \equiv ABM^{-1} \pmod{N}$ . With this version of Montgomery's algorithm, base conversions are the major operations of the algorithm, as the two RNS computations can be performed in parallel on all the individual residues.

**Remarks:**

The direct construction of the result  $AB \pmod{N}$  (say for the Fiat-Shamir Algorithm) needs a second pass of the algorithm with  $R$  and  $(M^2 \pmod{N})$  (a precomputed value) as inputs. With  $A, B < N$ , as  $R < 2N < M$  and  $(M^2 \pmod{N}) < N$ , all the conditions of the algorithm are satisfied. But if we want to use this algorithm for exponentials, we must note that it is necessary to require  $4N < M$ , since the repeated squarings requires results of the algorithm to be used as operands, and thus  $A$  and  $B$  will only be bounded by  $2N$ .

## 4. Base conversion

All conversions of RNS representations from one base  $\mathcal{B}_n$  into another  $\tilde{\mathcal{B}}_{\tilde{n}}$ , satisfying  $\gcd(M, \tilde{M}) = 1$ ,

where  $M, \tilde{M}$  are the products of the moduli of the systems, must in some way or other implicitly calculate the value of the numbers represented. For our purpose here we want conversion algorithms, which can be executed on a set of simple processors available for the RNS computations (the "channels").

### 4.1. Using an extra modulus

We consider  $X_{RNS} = \{x_1, x_2, \dots, x_n\}$  represented in the system  $\mathcal{B}_n$  with  $X \in [0, M[$  and construct  $X$  using the Chinese Remainder Theorem (CRT) [8] by the following expression:

$$X = \left( \sum_{i=1}^n x_i |M_i|_{m_i}^{-1} M_i \right) \pmod{M} \quad (3)$$

where  $M_i = \frac{M}{m_i}$ , and  $|M_i|_{m_i}^{-1}$  is the inverse of  $M_i$  modulo  $m_i$ . Thus we have:

$$(x_i |M_i|_{m_i}^{-1} M_i) \pmod{m_j} = \begin{cases} x_i & \text{if } j = i \\ 0 & \text{else} \end{cases}$$

The normal use of this method is to reconstruct the integer value of  $X$  in a classical number system. Now if we only want to obtain the residue of  $X$  modulo  $\tilde{m}_i$ , we could use the expression (3). But the modulo- $M$  reduction gives some problems evaluating the residues modulo  $\tilde{m}_i$ . However, an alternative form of the CRT allow us to write

$$\sum_{i=1}^n \left| x_i |M_i|_{m_i}^{-1} \right|_{m_i} M_i = X + \alpha M \quad (4)$$

for some value of  $\alpha$  where  $0 \leq \alpha < n$ .

In 1989 Shenoy et Kumaresan [17], proposed to use an extra modulus  $m_x$  to evaluate  $\alpha$ :

$$\alpha = \left| |M|_{m_x}^{-1} \left( \sum_{i=1}^n \left| x_i |M_i|_{m_i}^{-1} \right|_{m_i} M_i \right) - |X|_{m_x} \right|_{m_x} \quad (5)$$

Thus it is now possible to compute  $\tilde{x}_j = |X|_{\tilde{m}_j}$  by

$$\tilde{x}_j = \left| \sum_{i=1}^n \left| x_i |M_i|_{m_i}^{-1} \right|_{m_i} M_i \right|_{\tilde{m}_j} - \left| \alpha M \right|_{\tilde{m}_j} \right|_{\tilde{m}_j} \quad (6)$$

for  $j = 1, \tilde{n}$ . Observing that the constants  $|M_i|_{m_i}^{-1}$ ,  $|M_i|_{m_x}$ ,  $|M|_{m_x}^{-1}$ ,  $|M|_{\tilde{m}_j}$  and  $|M_i|_{\tilde{m}_j}$  can be precomputed, then  $\alpha$  and  $\tilde{x}_j$  are evaluated with  $n+1$  multiplications and  $n$  additions. The only dependence on  $\alpha$  is in the last multiplication and addition to compute  $\tilde{x}_j$ . Thus, in parallel using  $\max(n, \tilde{n}) + 1$  channels,  $\alpha$  and all the  $\tilde{x}_j$  can be evaluated in  $n+2$  multiplications and  $n+1$  addition steps.

Note that the value of  $\alpha$  is bounded by  $n$ , which in practice is much smaller than the other moduli

$m_i, i = 1..n$ . Hence the extra channel computing  $\alpha$  can operate with a modulus  $m_x \geq n$  smaller than the rest, possibly even a power of 2.

As  $\alpha < n$ , the term  $|\alpha M|_{m_j}^{-1}$  in (6) and the product by  $|M|_{m_x}^{-1}$  in (5) could be read from tables, thus only  $n$  multiplications will be needed.

However, a major drawback of this method is that, to compute  $\alpha$ , one must know one extra residue,  $|X|_{m_x}$ , which cannot be computed by (2) for  $Q$  in our algorithm, since  $(|A|_{m_x}|B|_{m_x} + |Q|_{m_x}|N|_{m_x}) \bmod m_x$  is unknown. But if an extra residue for  $R$  can be computed by some means then this algorithm can be used to convert the representation of  $R$ .

## 4.2. Allowing an offset in the residue

Considering again equation (4), it expresses which residue class modulo  $M$  that  $X$  belongs to, and when applied to  $Q$  we may not need to know the value of  $\alpha$  to proceed. Thus by the CRT

$$\hat{Q} = \sum_{i=1}^n \left| q_i |M_i|_{m_i}^{-1} \right|_{m_i} M_i = Q + \alpha M \quad (7)$$

for some value of  $\alpha$  where  $0 \leq \alpha < n$ .

When  $\hat{Q}$  has been computed it is possible to compute  $\hat{R}$  as

$$\begin{aligned} \hat{R} &= (AB + \hat{Q}N)M^{-1} = (AB + QN + \alpha MN)M^{-1} \\ &= (AB + QN)M^{-1} + \alpha N \end{aligned}$$

so that  $\hat{R} \equiv R \equiv ABM^{-1} \pmod{N}$ , which is sufficient for our purpose. Also, assuming that  $AB < NM$  we find that  $\hat{R} < (n+2)N$  since  $\alpha < n$ .

Given the residue representations of  $A, B$  and  $N$  in the system  $\mathcal{B}$ , it is thus possible to compute the residue representation of  $Q$  in  $\mathcal{B}$  by (2), and by (7) to convert it into the representation of  $\hat{Q}$  in the other residue system  $\tilde{\mathcal{B}}$ , including possibly an extra residue. In this system  $\hat{R}$  can now be computed, and finally converted back to the system  $\mathcal{B}$  using the method of Shenoy and Kumaresan. For applications like in RSA where many modular multiplications are needed, it is not necessary to have the intermediate results perfectly reduced, it is sufficient at the very end of the computation to find the value of  $\alpha$ . But the value of  $N$  has to be bounded  $(n+2)^2N < M$ , since this together with  $AB < NM$  assures  $\hat{R} < (n+2)N$ . For single multiplications the first Montgomery pass can be performed using (4) obtaining  $\hat{R} < (n+2)N$  with  $\hat{R} = ABM^{-1} \bmod N + \beta N$ . For the second pass the inputs are  $\hat{R}$  and  $M^2 \bmod N$ , and if an algorithm with exact conversions is used then an  $R$  is found satisfying  $R < 2N$ .

## 5. The RNS multiplication algorithm

Figure 1 describes the execution of our algorithm, illustrating the time and area complexities. Although it is possible to use maximal parallelism in the form of  $n + \tilde{n} + 1$  channels,  $\max(n, \tilde{n}) + 1$  will be sufficient most of the time. The only place where more processors could be employed is to perform the computation of the product  $AB$  in the system  $\tilde{\mathcal{B}}$ , so that it is available when  $\hat{Q}$  has been converted. The time complexity is approximately  $2(n + \tilde{n})T$ , where  $T$  is the time for one table look-up plus one modular multiply-add operation. For applications in cryptology, say with  $N \sim 2^{1024}$ , it is possible to choose  $n = \tilde{n} = 33$ , where each channel is realized by a very simple 32-bit processor, i.e., a total of 34 processors. Each processor has to be able to compute additions and multiplications, modulo some specific 32-bit primes, and to store some 32-entry look-up tables of 32-bit constants.

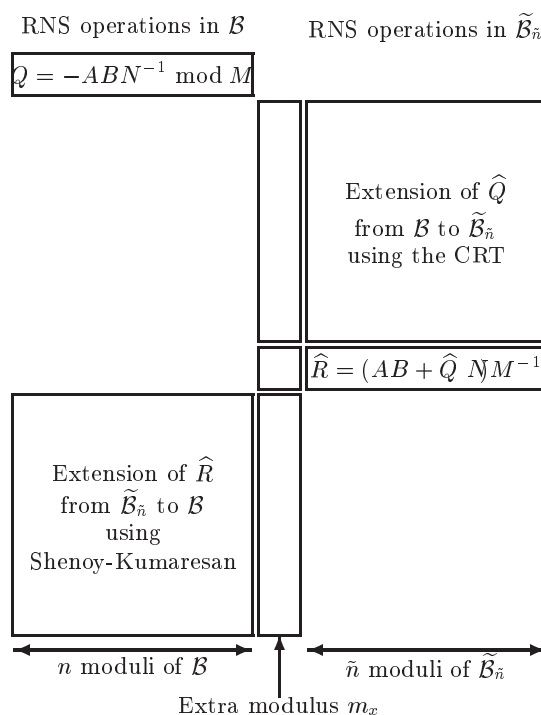


Figure 1. Evaluation of  $A \times B \times M^{-1}$  in RNS

**Example** We consider the systems  $\mathcal{B}_5 = \{3, 7, 13, 19, 29\}$ ,  $\tilde{\mathcal{B}}_5 = \{5, 11, 17, 23, 31\}$ , the extra modulus  $m_e = 8$  and operands  $A, B$  and  $N$ . Thus, we have  $M = 150423$  and  $\tilde{M} = 666655$ .

	In $\mathcal{B}_n$					$m_x$	In $\tilde{\mathcal{B}}_n$					Base 10
	3	7	13	19	29		5	11	17	23	31	
$A$	1	3	9	14	25	2	1	8	2	5	5	26386
$B$	1	5	1	9	25	3	1	1	1	21	19	72931
$N$	1	2	6	11	27	7	2	7	9	14	19	14527

The computation of  $A \times B \times M^{-1} \bmod N$  is detailed as shown in the following table.



The trick in Montgomery modular multiplication is to substitute difficult modular reductions (say by a 32-bit prime) by simpler reductions, here by  $2^{32}$ . This is done by mapping operands into another residue system, so with  $m$  prime let

$$\text{for } 0 \leq a < m \text{ let } [a]_m = a2^{32} \bmod m$$

then it is easy to see that

$$[a + b]_m = |[a]_m + [b]_m|_m$$

where the outer reduction is an ordinary reduction modulo  $m$ .

Multiplication in this system can be performed by Montgomery's M-reduce algorithm:

**Algorithm 2** *M-reduce* ( $ef$ )

**Stimulus:** *A n inte get such that  $0 \leq t < rm$ . Integer constants  $m, r, m', r^{-1}$  such that  $\gcd(m, r) = 1, r > m > 2$  and  $rr^{-1} - mm' = 1$ .*

**Response:** *A n inte gen,  $u = (tr^{-1}) \bmod m$ .*

**Method:**  $q := ((t \bmod r)m') \bmod r;$   
 $u := (t + qm) \text{ div } r;$   
*if  $u \geq m$  then  $u := u - m$ ;*

Thus with  $r = 2^{32}$ , since  $\text{M-reduce}([a]_m[b]_m) = ab2^{32} \bmod m = [ab]_m$ , the product  $[ab]_m$  can be computed with 3 ordinary 32-bit multiplications and 1 or 2 ordinary additions, given suitable constants. Mapping into and out of this residue system is performed by M-reduce, multiplying with constants  $|r^2|_m$ , respectively 1.

## 6. Conclusions

With this new approach to modular multiplication in RNS, we observe that base extension is a key operation. All the complexity is due to this transformation. Shenoy and Kumaresan proposed an efficient method based on the CRT, by which a logarithmic time complexity can be obtained with  $n^2$  processors. Utilizing  $n$  parallel RNS channels the algorithm can be implemented in  $n + 1$  steps, using one additional channel for an extra residue.

But since such an extra residue cannot be obtained for the quotient  $Q$ , and if the computation is to be performed on the set of parallel RNS processors, some other mechanism must be employed. In [15] and [7] various fixed-point computations were used to obtain approximations to  $\alpha$  in (4), and in that way perform the base conversion of both  $Q$  and  $R$ . We realized that the conversion of  $Q$  need not be "exact", an "approximation"  $\hat{Q}$  is sufficient to obtain an  $\hat{R}$  in the same residue class as the result  $R$ .

Compared to other number systems, RNS can be considered a real parallel system. Our method is easily implementable with processors connected by a bus, where communication is reduced to at most one broadcast per step.

If modular multiplication is implemented on processors which do not support arithmetic on the full data-width (say 1024 bits), we believe that an RNS implementation is preferable to a high-radix implementation. Given a number of smaller (say 32-bit) processors, parallelism is easier to exploit in RNS with  $\mathcal{O}(n)$  processors, than in a redundant ordinary radix system. And it is not necessary to employ the full  $n + \tilde{n} + 1$  processors for maximal parallelism, or almost as good,  $\max(n, \tilde{n}) + 1$ , any number will do, even a single processor.

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