

DYNAMIC DISTANCE HEREDITARY GRAPHS USING SPLIT DECOMPOSITION

Emeric Gioan

CNRS - LIRMM - Université Montpellier II, France

December 17, 2007

Joint work with C. Paul (CNRS - LIRMM)

Dynamic graph representation problem:

Given a representation $R(G)$ of a graph G and a edge or vertex modification of G (insertion or deletion) update the representation $R(G)$.

Dynamic graph representation problem:

Given a representation $R(G)$ of a graph G and a edge or vertex modification of G (insertion or deletion) update the representation $R(G)$.

When restricted to a certain graph family \mathcal{F} , the algorithm should:

- 1 check whether the modified graph still belongs to \mathcal{F} ;
- 2 if so, update the representation;
- 3 otherwise output a certificate (e.g. a forbidden subgraph).

Dynamic graph representation problem:

Given a representation $R(G)$ of a graph G and a edge or vertex modification of G (insertion or deletion) update the representation $R(G)$.

When restricted to a certain graph family \mathcal{F} , the algorithm should:

- 1 check whether the modified graph still belongs to \mathcal{F} ;
- 2 if so, update the representation;
- 3 otherwise output a certificate (e.g. a forbidden subgraph).

Some keys of the problem

Need of a canonical representation (decomposition techniques...)
and need of an incremental (dynamic) characterization.

Some known results

	vertex modification	edge modification
proper intervals	$O(d + \log n)$ [HSS02]	$O(1)$ [HSS02]
cographs	$O(d)$ [CoPeSt85]	$O(1)$ [SS04]
permutations	$O(n)$ [CrPa05]	$O(n)$ [CrPa05]
distance hereditary	$O(d)$ [GPa07]	$O(1)$ [CoT07]
intervals	$O(n)$ [Cr07]	$O(n)$ [Cr07]

HSS = Hell, Shamir, Sharan

CoPeSt = Corneil, Perl, Stewart

SS = Shamir, Sharan

CrPa = Crespelle, Paul

GPa = Gioan, Paul

CoT = Corneil, Tedder

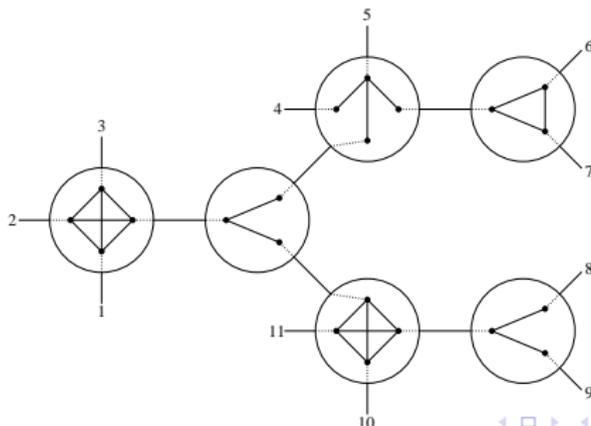
Cr = Crespelle

- 1 Revisiting split decomposition
- 2 Vertex modification of DH graphs
- 3 Relations with other works

Graph labelled tree

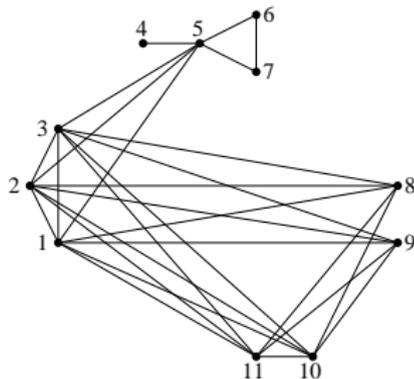
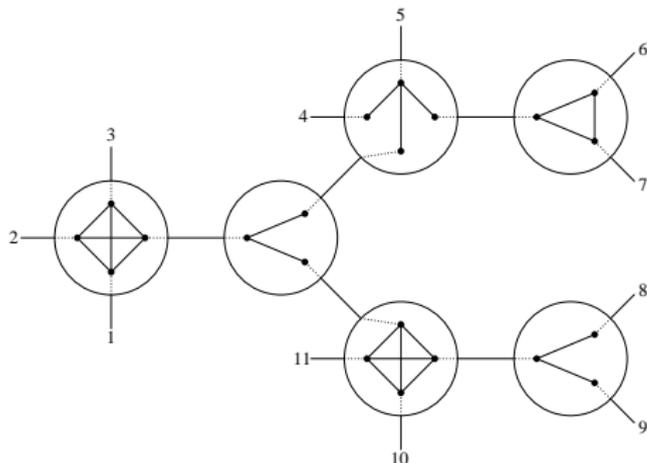
A *graph-labelled tree* is a pair (T, \mathcal{F}) with T a tree and \mathcal{F} a set of graphs such that:

- each (internal) node v of degree k of T is labelled by a graph $G_v \in \mathcal{F}$ on k vertices
- there is a bijection ρ_v from the tree-edges incident to v to the vertices of G_v



Given a graph labelled tree (T, \mathcal{F}) , the *accessibility graph* $G_S(T, \mathcal{F})$ has the leaves of T as vertices and

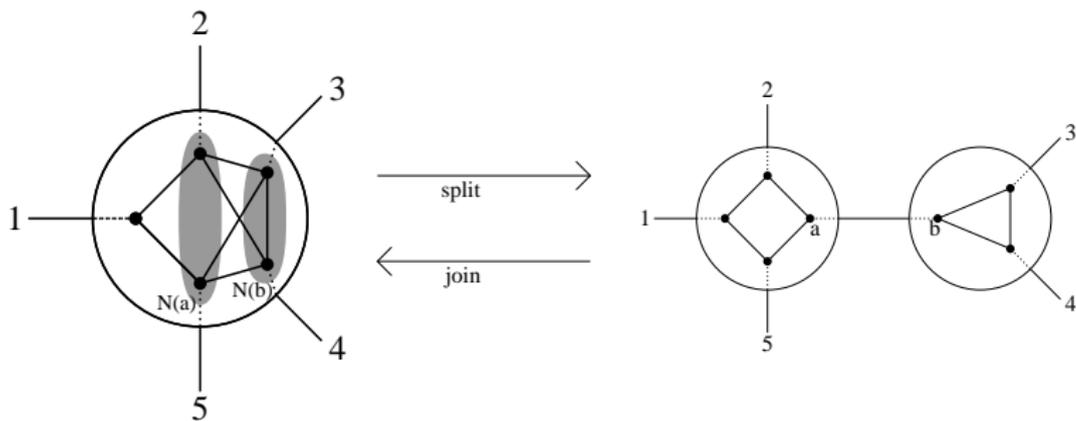
- $xy \in E(G_S(T, \mathcal{F}))$ if and only if $\rho_v(uv)\rho_v(vw) \in E(G_v)$,
 \forall tree-edges uv, vw on the x, y -path in T



Split

A *split* is a bipartition (A, B) of the vertices of a graph $G = (V, E)$ such that

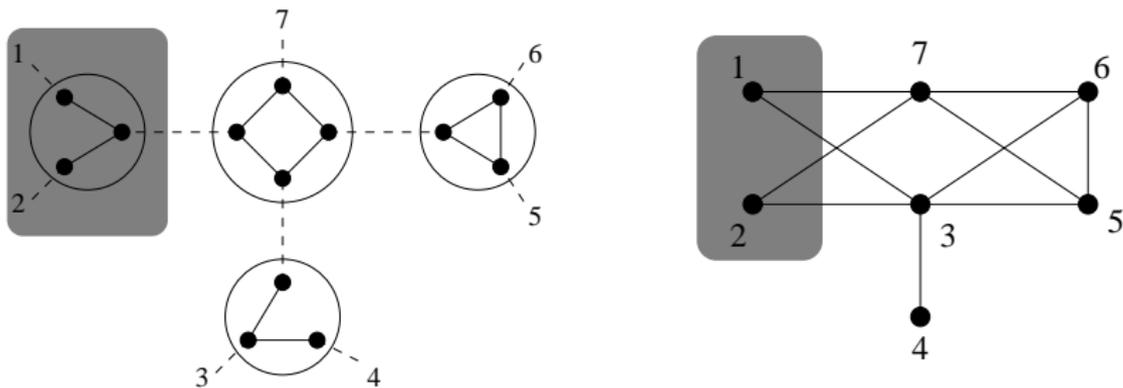
- $|A| \geq 2, |B| \geq 2$;
- for $x \in A$ and $y \in B, xy \in E$ iff $x \in N(B)$ and $y \in N(A)$.



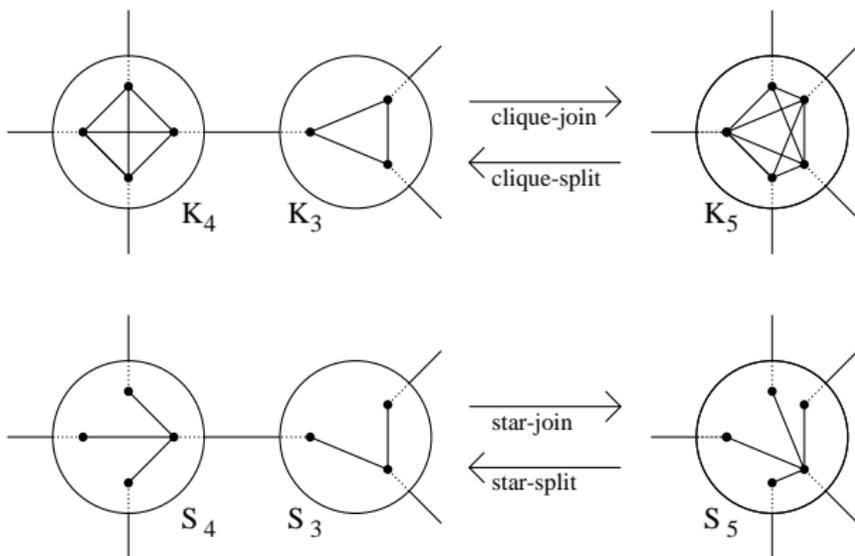
Split

A *split* is a bipartition (A, B) of the vertices of a graph $G = (V, E)$ such that

- $|A| \geq 2, |B| \geq 2$;
- for $x \in A$ and $y \in B, xy \in E$ iff $x \in N(B)$ and $y \in N(A)$.



A graph is *prime* if it has no split.
 The stars and cliques are called *degenerate*.



Split decomposition [Cunningham'82 reformulated]

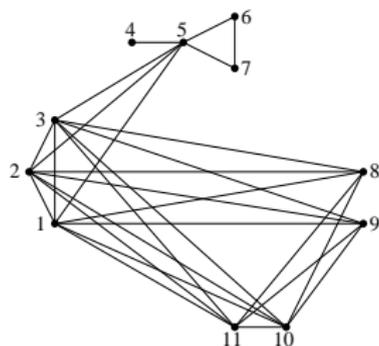
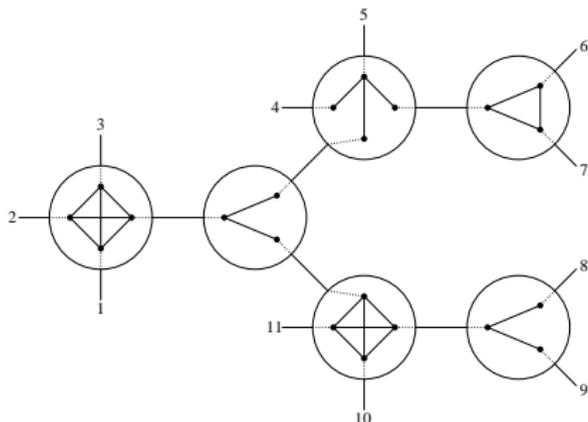
For any connected graph G , there exists a unique graph-labelled tree (T, \mathcal{F}) with a minimum number of nodes such that

- 1 $G = G_S(T, \mathcal{F})$,
- 2 any graph of \mathcal{F} is prime or degenerate for the split decomposition.

→ We note $(T, \mathcal{F}) = ST(G)$ the *split tree* of G

Distance hereditary graph

A graph is *distance hereditary* if and only if it is totally decomposable for the split decomposition, i.e. its split tree is labelled by cliques and stars.



An intersection model for DH graphs [Gioan and Paul '07]

The *accessibility set* of a leaf a in a clique-star labelled tree is the set of paths (a, b) with b a leaf accessible from a .

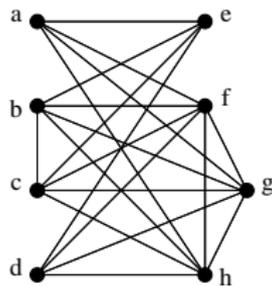
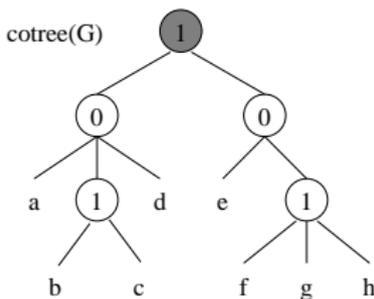
A distance hereditary graph is the intersection graph of a family of accessibility sets of leaves in a set of clique-star labelled trees.

answers a question by Spinrad

Particular case of cographs

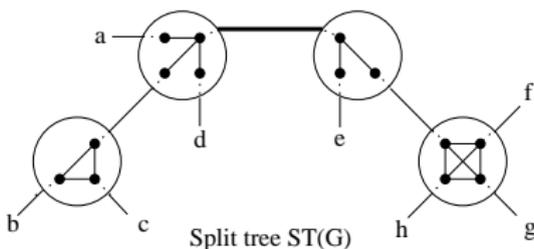
The cographs form the particular case where the centers of all stars are directed towards a **root** of the split tree.

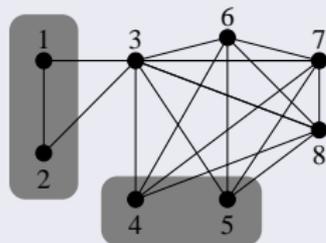
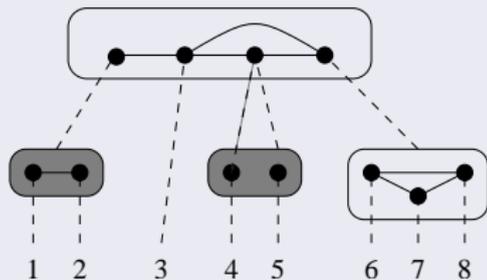
$1 = \text{clique}$
 $0 = \text{stable}$



Cograph G

$1 = \text{clique}$
 (except root)
 $0 = \text{star}$
 (towards root)





Modules

A subset of vertices M of a graph $G = (V, E)$ is a **module** iff

$$\forall x \in V \setminus M, \text{ either } M \subseteq N(x) \text{ or } M \cap N(x) = \emptyset$$

Split decomposition

Degenerate graphs

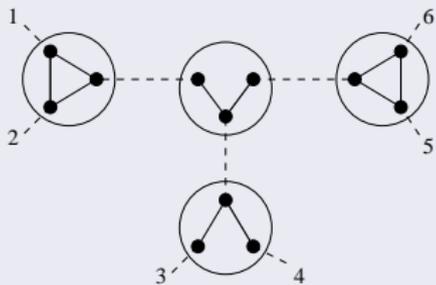
- cliques and stars

Totally decomposable graphs

- Distance hereditary graphs

Unrooted tree decomposition

- [Cunningham 82]



Modular decomposition

Degenerate graphs

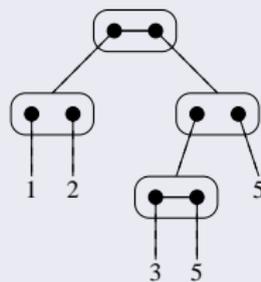
- cliques and stables

Totally decomposable graphs

- Cographs

Rooted tree decomposition

- [Gallai 67]



- 1 Revisiting split decomposition
- 2 Vertex modification of DH graphs
- 3 Relations with other works

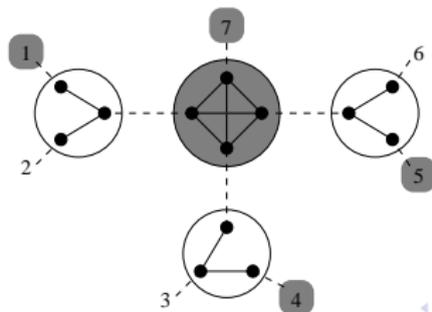
Theorem (Gioan and Paul 07)

Let $G = (V, E)$ be a distance hereditary (DH) graph. It can be tested in

- $O(|S|)$ whether $G + (x, S)$, with $x \notin E$ and $N(x) = S$, is a DH graph;
- $O(|S|)$ whether $G - x$, with $S = N(x)$, is a DH graph;

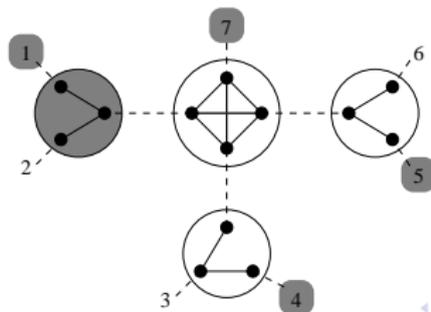
Let (T, \mathcal{F}) be a graph-labelled tree, and S be a subset of leaves of T . A node u of $T(S)$ is:

- **fully-accessible** by S if any subtree of $T - u$ contains a leaf of S ;



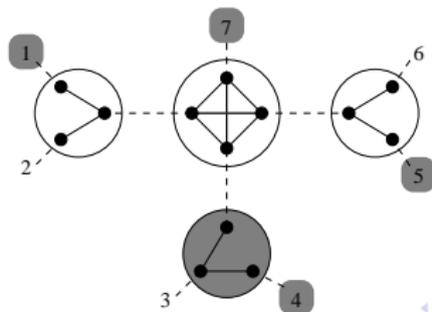
Let (T, \mathcal{F}) be a graph-labelled tree, and S be a subset of leaves of T . A node u of $T(S)$ is:

- **fully-accessible** by S if any subtree of $T - u$ contains a leaf of S ;
- **singly-accessible** by S if it is a star-node and exactly two subtrees of $T - u$ contain a leaf $l \in S$ among which the subtree containing the neighbor v of u such that $\rho_u(uv)$ is the centre of G_u ;



Let (T, \mathcal{F}) be a graph-labelled tree, and S be a subset of leaves of T . A node u of $T(S)$ is:

- **fully-accessible** by S if any subtree of $T - u$ contains a leaf of S ;
- **singly-accessible** by S if it is a star-node and exactly two subtrees of $T - u$ contain a leaf $l \in S$ among which the subtree containing the neighbor v of u such that $\rho_u(uv)$ is the centre of G_u ;
- **partially-accessible** otherwise



Theorem (DH incremental characterization [Gioan, Paul '07])

Let G be a connected DH graph and $ST(G) = (T, \mathcal{F})$ be its split tree. Then $G + (x, S)$ is a DH graph if and only if:

- 1 At most one node of $T(S)$ is partially-accessible.

Theorem (DH incremental characterization [Gioan, Paul '07])

Let G be a connected DH graph and $ST(G) = (T, \mathcal{F})$ be its split tree. Then $G + (x, S)$ is a DH graph if and only if:

- 1 At most one node of $T(S)$ is partially-accessible.
- 2 Any clique node of $T(S)$ is either fully or partially-accessible.

Theorem (DH incremental characterization [Gioan, Paul '07])

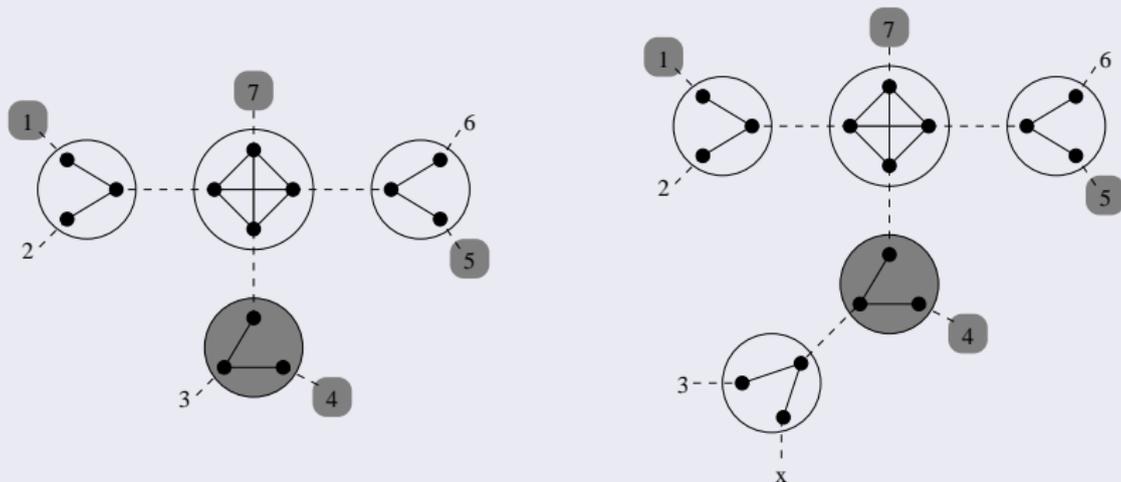
Let G be a connected DH graph and $ST(G) = (T, \mathcal{F})$ be its split tree. Then $G + (x, S)$ is a DH graph if and only if:

- 1 At most one node of $T(S)$ is partially-accessible.
- 2 Any clique node of $T(S)$ is either fully or partially-accessible.
- 3 If there exists a partially-accessible node u , then any star node $v \neq u$ of $T(S)$ is oriented towards u if and only if it is fully-accessible.

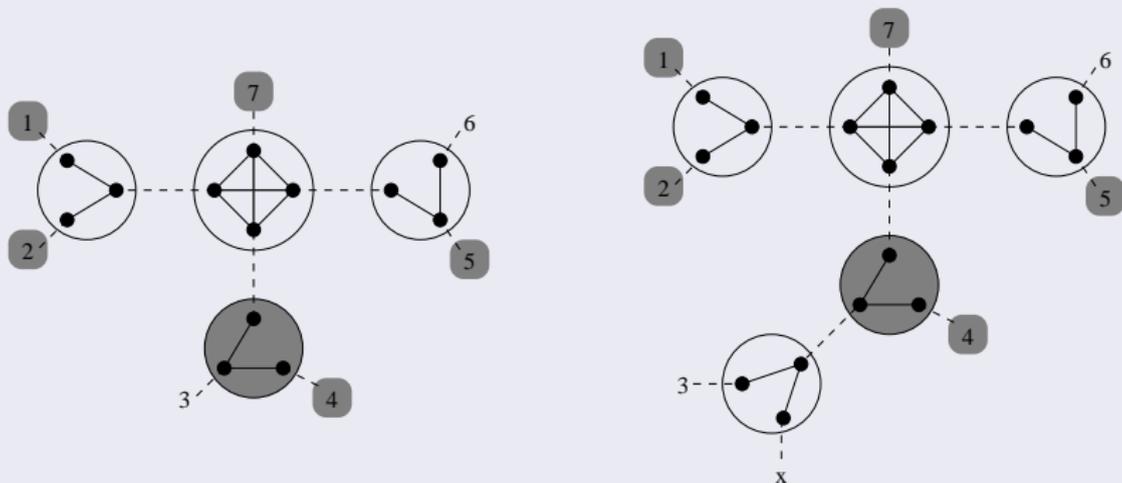
Theorem (DH incremental characterization [Gioan, Paul '07])

Let G be a connected DH graph and $ST(G) = (T, \mathcal{F})$ be its split tree. Then $G + (x, S)$ is a DH graph if and only if:

- 1 At most one node of $T(S)$ is partially-accessible.
- 2 Any clique node of $T(S)$ is either fully or partially-accessible.
- 3 If there exists a partially-accessible node u , then any star node $v \neq u$ of $T(S)$ is oriented towards u if and only if it is fully-accessible.
- 4 Otherwise, there exists a tree-edge e of $T(S)$ towards which any star node of $T(S)$ is oriented if and only if it is fully-accessible.



The insertion fails: the two singly-accessible nodes are oriented towards the partially-accessible node !



The insertion succeeds: in $G_S(T, \mathcal{F})$, we have $N(x) = S$

Insertion algorithm

- 1 Extract $T(S)$ (require an arbitrary orientation of $ST(G)$);

Insertion algorithm

- 1 Extract $T(S)$ (require an arbitrary orientation of $ST(G)$);
- 2 Check the accessibility-type of the nodes and look for an insertion node or edge;

Insertion algorithm

- 1 Extract $T(S)$ (require an arbitrary orientation of $ST(G)$);
- 2 Check the accessibility-type of the nodes and look for an insertion node or edge;
- 3 Insert the node by either subdividing the insertion edge, or splitting the insertion node, or attaching x to the insertion node.

Insertion algorithm

- 1 Extract $T(S)$ (require an arbitrary orientation of $ST(G)$);
- 2 Check the accessibility-type of the nodes and look for an insertion node or edge;
- 3 Insert the node by either subdividing the insertion edge, or splitting the insertion node, or attaching x to the insertion node.

Complexity

- 1 $O(|N(x)|)$ dynamic recognition

Insertion algorithm

- 1 Extract $T(S)$ (require an arbitrary orientation of $ST(G)$);
- 2 Check the accessibility-type of the nodes and look for an insertion node or edge;
- 3 Insert the node by either subdividing the insertion edge, or splitting the insertion node, or attaching x to the insertion node.

Complexity

- 1 $O(|N(x)|)$ dynamic recognition
- 2 linear time static recognition

- 1 Revisiting split decomposition
- 2 Vertex modification of DH graphs
- 3 Relations with other works

Edge modification of DH graphs

Theorem (Corneil and Tedder 06)

Let $G = (V, E)$ be a distance hereditary (DH) graph. It can be tested in

- $O(1)$ whether $G + e$, with $e \notin E$, is a DH graph;
- $O(1)$ whether $G - e$, with $e \in E$, is a DH graph.

Edge modification of DH graphs

Another approach for this result [GP 07]

A simple algorithm for this result is given by graph-labelled trees: consider the word between the two leaves x and y where $e = xy$ with K a clique, L resp. R a star with center towards x resp. y , and S otherwise.

edge insertion \longrightarrow	
\longleftarrow edge deletion	
$(R)SS(L)$	$(R)LR(L)$
$(R)SK(L)$	$(R)LK(L)$
$(R)KS(L)$	$(R)KR(L)$
$(R)S(L)$	$(R)K(L)$

Vertex modification of cographs

Theorem (Corneil, Pearl and Stewart '85)

Let $G = (V, E)$ be a cograph. It can be tested in

- $O(|S|)$ whether $G + (x, S)$, with $x \notin E$ and $N(x) = S$, is a cograph
- $O(|S|)$ whether $G - x$, with $S = N(x)$, is a cograph

Vertex modification of cographs

Theorem (Cograph incremental characterization [CPS'85])

Let G be a cograph and $MD(G) = (T, \mathcal{F})$ be its modular decomposition tree. Then $G + (x, S)$ is a cograph if and only if:

- 1 At most one node of $T(S)$ is partially-accessible.
- 2 Any series node of $T(S)$ is either fully or partially-accessible.
- 3 If a partially-accessible node u exists, then a parallel node $v \neq u$ of $T(S)$ is a descendant of u if and only if it is fully-accessible.
- 4 Otherwise, a tree-edge $e = uw$ of $T(S)$ exists such that a parallel node $v \neq u$ of $T(S)$ is a descendant of u if and only if it is fully-accessible.

Another approach for this result [GP 07]

This result is equivalent to test the insertion/deletion in DH graphs, with the supplementary condition that the split tree is rooted.

Edge modification of cographs

Theorem (Sharan and Shamir '04)

Let $G = (V, E)$ be a cograph. It can be tested in

- $O(1)$ whether $G + e$, with $e \notin E$, is a cograph
- $O(1)$ whether $G - e$, with $e \in E$, is a cograph

Another approach for this result [GP 07]

This result is equivalent to test the insertion/deletion in DH graphs, with the supplementary condition that the split tree is rooted.

THANKS!