

DISTANCE HEREDITARY GRAPHS CHARACTERIZATIONS AND RECOGNITION

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Part of the results are joint work with
E. Gioan

Some characterizations

An incremental recognition algorithm

About intersection models

Definition and examples

A graph $G = (V, E)$ is **distance hereditary (DH)** if in every **connected induced subgraph** $H = G[S]$ the distance between any two vertices x and y of S is the same in H than in G .

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- ▶ Cographs (i.e. P_4 free graphs) are DH graphs

Examples of non DH graphs

- ▶ The cycles of length at least 5 are not DH graphs
- ▶ The **house**, the **gem** and the **domino** are not DH graphs

Some characterizations (1)

Theorem: A graph is a DH graph iff it does not contains as induced subgraph the **hole**, the **house**, the **gem** and the **domino**.

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Theorem: A graph is a DH graph iff it can be built up from a single vertex by a sequence of the following operations:

1. Add a **pendant vertex** y to a vertex x of graph
2. Add a **false twin** y to a vertex x : i.e. $N(x) = N(y)$
3. Add a **true twin** y to a vertex x : i.e. $N(x) \cup \{x\} = N(y) \cup \{y\}$

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Theorem: Let G be a connected graph. The following assertions are equivalent

1. G is a DH graph
2. every cycle of length at least 5 in G has **two crossing chords**

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3. for every four vertices $u, v, w,$ and $x,$ at least two of the three sums of distances $d(u, v) + d(w, x), d(u, w) + d(v, x),$ and $d(u, x) + d(v, w)$ are equal to each other

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4. G has **rankwidth 1**
5. G is totally decomposed by the **split decomposition**

Some characterizations (3)

Theorem [Bandelt, Muller'86]

Let G be a connected graph and L_1, \dots, L_k be the distance layout from an arbitrary vertex v of G . Then G is a DH graph iff the following conditions are verified for any $1 \leq i \leq k$:

1. If x and y belong to the same connected component of $G[L_i]$, then $N_{i-1}(x) = N_{i-1}(y)$

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3. If $x \in N_{i-1}(u)$ and $y \in N_{i-1}(u)$ are in different connected components X and Y of $G[L_{i-1}]$, then $X \cup Y \subseteq N(u)$ and $N_{i-2}(x) = N_{i-2}(y)$

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5. If $x \in N_{i-1}(u)$ and $y \in N_{i-1}(u)$ are in the same connected component C of $G[L_{i-1}]$, then the vertices of C non-adjacent to u are either adjacent to both x and y or none of them

The recognition problem (1)

Theorem [Hammer and Maffray'90, Damiand,Habib and P.'05]

The recognition problem of DH graph can be solved in linear time.

- ▶ compute a BFS of the graph
- ▶ examine the structure of the distance layers
- ▶ prune the vertices to get a pendant/twin elimination ordering

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Theorem [Gioan, P.'07]

There exists a linear time **fully dynamic** recognition algorithm for the DH recognition problem

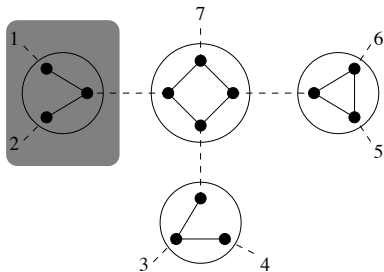
- ▶ the insertion of a new vertex x costs $O(|N(x)|)$
- ▶ the deletion of a vertex x costs $O(|N(x)|)$

→ based on the split decomposition characterization

Split decomposition (1)

A **graph-labelled tree (GLT)** is a pair (T, \mathcal{F}) with T a tree and \mathcal{F} a set of graphs such that:

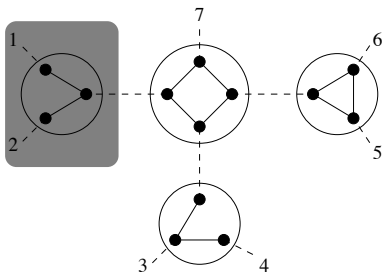
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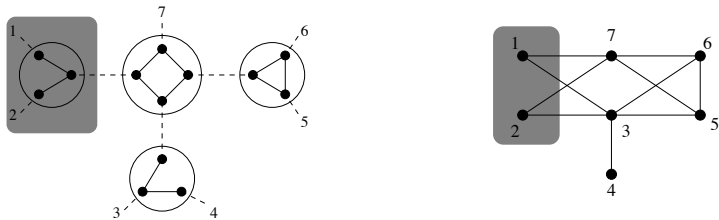
- ▶ each node v of degree k of T is labelled by a graph $G_v \in \mathcal{F}$ on k vertices
- ▶ there is a bijection ρ_v from the tree-edges incident to v to the vertices of G_v



Split decomposition (2)

Given a GLT (T, \mathcal{F}) , the **accessibility graph** $G_S(T, \mathcal{F})$ has

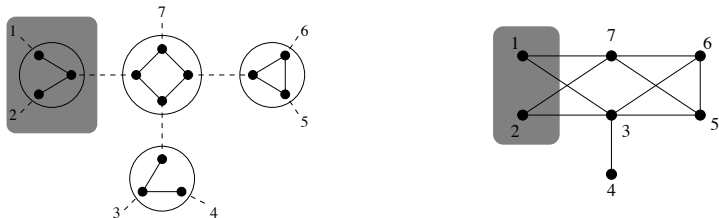
- ▶ its vertices in one-to-one correspondence with the leaves of T



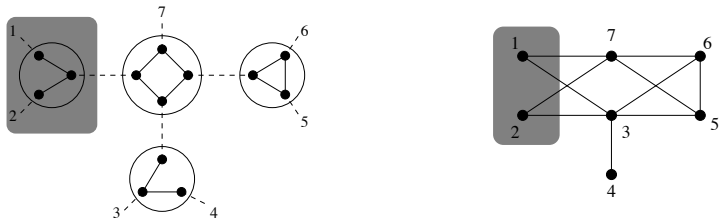
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- ▶ its vertices in one-to-one correspondence with the leaves of T
- ▶ $xy \in E(G_S(T, \mathcal{F}))$ iff $\rho_v(uv)\rho_v(vw) \in E(G_v)$,
 \forall tree-edges uv, vw on the x, y -path in T



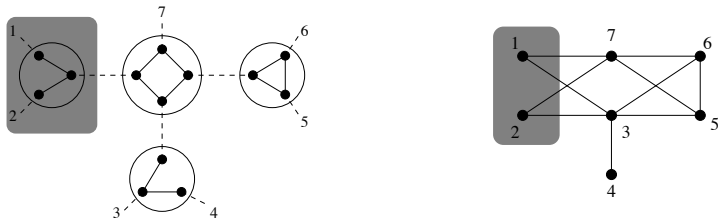
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A bipartition (A, B) of the vertices of a graph is a **split** iff

- ▶ $|A| \geq 2$, $|B| \geq 2$;
- ▶ for $x \in A$ and $y \in B$, $xy \in E$ iff $x \in N(B)$ and $y \in N(A)$.

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Observation: every tree edge of a GLT defines a split of its accessibility graph

Split decomposition (4)

Examples of splits

- ▶ any non-trivial bipartition of the clique
- ▶ any non-trivial bipartition of the $K_{1,n}$

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Theorem [Cunnigham'82 reformulated]

For any connected graph G , there exists a unique graph-labelled tree (T, \mathcal{F}) with a minimum number of nodes such that

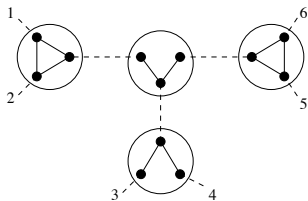
1. $G = G_S(T, \mathcal{F})$,
2. any graph of \mathcal{F} is prime or degenerate (clique or star) for the split decomposition.

→ We note $(T, \mathcal{F}) = ST(G)$

Split decomposition (5)

Definition A graph is **totally decomposable** (by the split decomposition) if every induced subgraph of size at least 4 has a split.

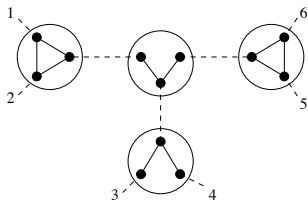
Theorem A graph is totally decomposable iff it is a DH graph.



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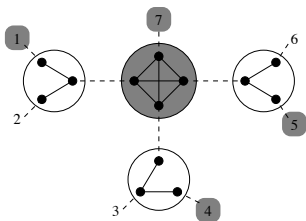


Theorem A graph is a DH graph iff its split tree only contains star and clique nodes.

Incremental recognition (1)

Let (T, \mathcal{F}) be a graph-labelled tree, and S be a subset of leaves of T . A node u of $T(S)$ is:

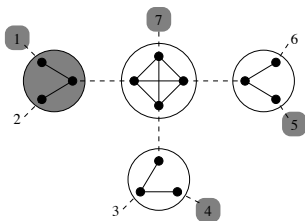
- ▶ **fully-marked** by S if any subtree of $T - u$ contains a leaf of S ;



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- ▶ **fully-marked** by S if any subtree of $T - u$ contains a leaf of S ;
- ▶ **singly-marked** by S if it is a star-node and exactly two subtrees of $T - u$ contain a leaf $l \in S$ among which the subtree containing the neighbor v of u such that $\rho_u(uv)$ is the centre of G_u ;



Incremental recognition (2)

Theorem (DH incremental characterization [Gioan, P.'07])

Let G be a connected DH graph and $ST(G) = (T, \mathcal{F})$ be its split tree. Then $G + (x, S)$ is a DH graph iff:

1. At most one node of $T(S)$ is partially-marked.

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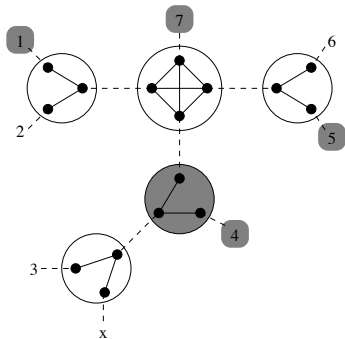
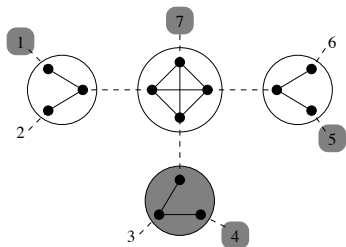
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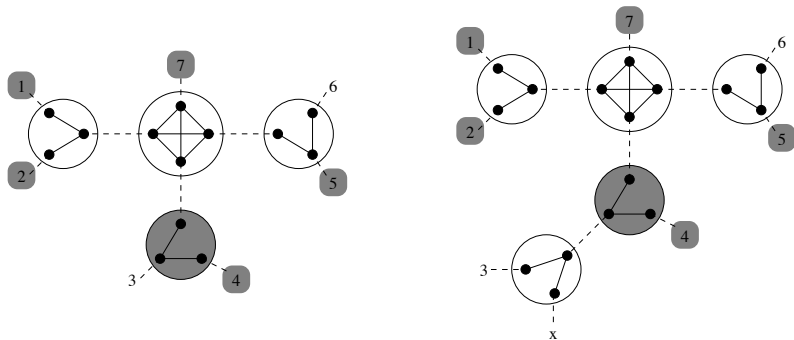
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3. If there exists a partially-marked node u , then any star node $v \neq u$ of $T(S)$ is oriented towards u if and only if it is fully-marked.
4. Otherwise, there exists a tree-edge e of $T(S)$ towards which any star node of $T(S)$ is oriented if and only if it is fully-marked.

Incremental recognition (3)



The insertion fails: the two singly-marked nodes are oriented towards the partially-marked node !

Incremental recognition (4)



The insertion succeeds: in $G_S(T, \mathcal{F})$, we have $N(x) = S$

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Given G and its split tree, the algorithm can be implemented in $O(|S|)$ time.

Intersection model (1)

Definition Let $\Sigma = \{S_1, \dots, S_n\}$ be a set family. The **intersection graph** of Σ is the graph the vertices of which are in one-to-one correspondence with \mathcal{F} and two vertices x_i, x_j are adjacent if $S_i \cap S_j \neq \emptyset$.

Observation 1 [Marczewski] Every graph is an intersection graph.

Definition Let Σ be a set family, then $\mathcal{I}(\Sigma)$ is the family of graphs containing the intersection graphs of subfamilies of Σ .

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Observation 2 Every intersection graph family is hereditary

Observation 3 Every intersection graph family is closed under true twin addition

Observation 4 If \mathcal{F} is an intersection graph family, then there exists an enumerable family Σ such that $\mathcal{F} = \mathcal{I}(\Sigma)$.

Intersection model (2)

Theorem [Scheinermann'86]

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1. \mathcal{F} is hereditary
2. \mathcal{F} is closed under true twin addition
3. \mathcal{F} has a **series ordering**

$\exists G_1 \dots G_i, G_{i+1} \dots G_k$ such that

- ▶ $\forall i, G_i \in \mathcal{F}$
- ▶ $\forall i, G_i$ is an induced subgraph of G_{i+1}
- ▶ $\forall H \in \mathcal{F}, \exists i$ H is a subgraph of G_i

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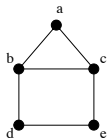
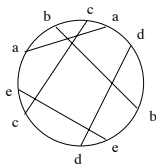
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Lemma: the family of DH graphs has an intersection model

BUT find the model ...

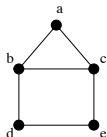
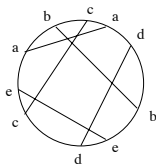
Intersection model (3)



Observation Every DH graphs is the intersection graph of a set of chord in a circle

(that is DH graphs form a subfamily of the circle graphs)

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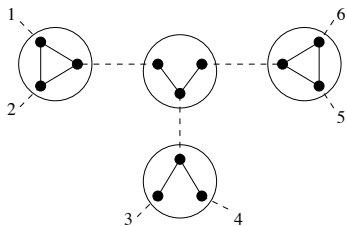
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BUT ... this is not a characterization

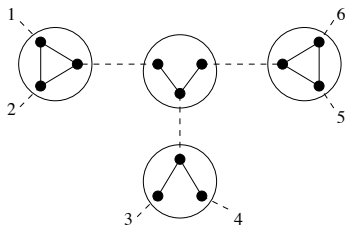
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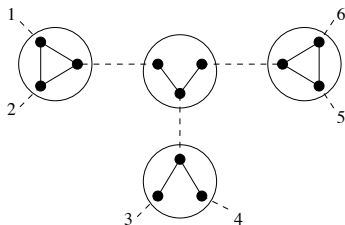
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- ▶ each vertex x receives a set $S(x)$ of path of T :
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- ▶ vertices x and y are adjacent iff $S(x) \cap S(y) \neq \emptyset$

Intersection model (5)

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e.g. compare with the intersection model of chordal graphs

Theorem

Let G be a graph. The following conditions are equivalent:

1. G has no chordless cycle of length at least four (G is chordal)
2. G has a tree-decomposition, the bags of which are cliques
3. G is the intersection graph of subtrees of a tree