

# Computing Distances on Graph Associahedra is Fixed-parameter Tractable

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**Seminaire AIGCo, LIRMM, Montpellier**

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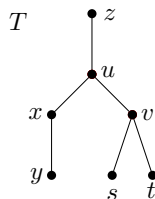
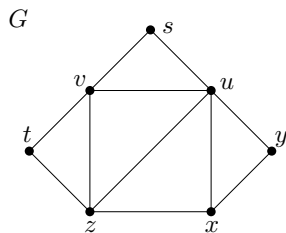
Originated in II Fortaleza Workshop em Combinatória (ForWorC 2023)

Available at [arXiv:2504.18338](#) (ICALP 2025)



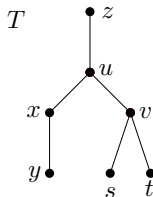
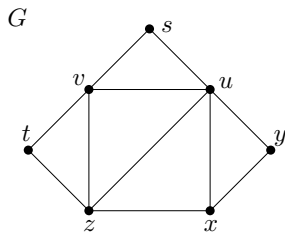
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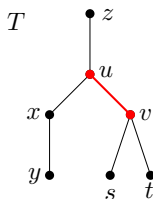
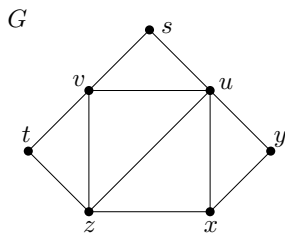


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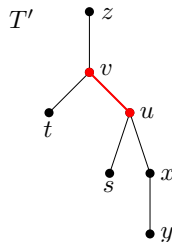
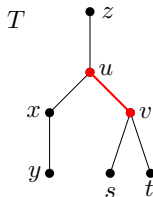
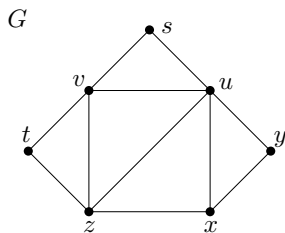


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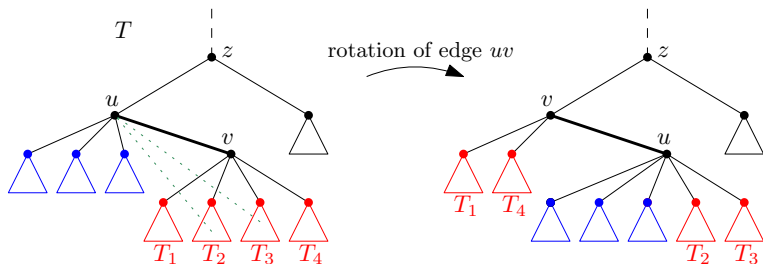
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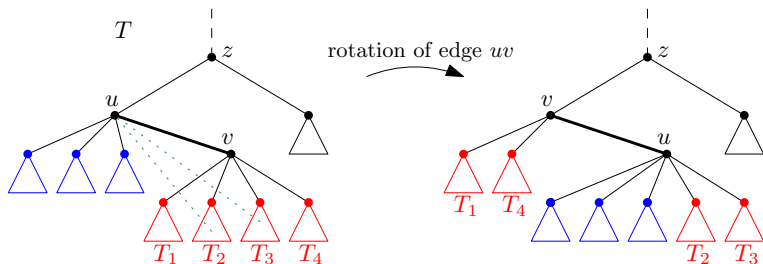
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# Rotation distance between elimination trees



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The **rotation distance** between two elimination trees (forests)  $T, T'$  of a graph  $G$ , denoted by  $\text{dist}(T, T')$ , is the **minimum number of rotations** it takes to transform  $T$  into  $T'$ .

# Graph associahedra

For any graph  $G$ , the flip graph of elimination forests of  $G$  under edge rotations is the skeleton of a polytope: graph associahedron  $\mathcal{A}(G)$ .

Object introduced by

[Carr, Devadoss, Postnikov. 2006-2009]

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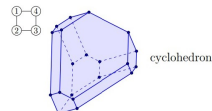
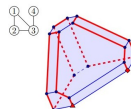
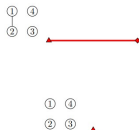
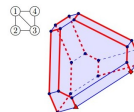
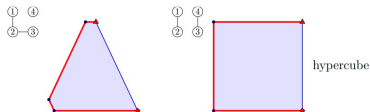
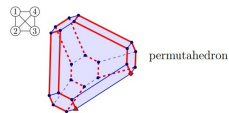
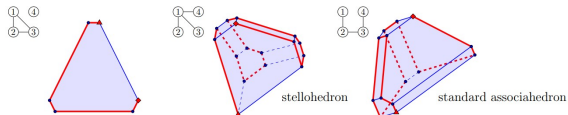
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Famous particular cases of  $\mathcal{A}(G)$  depending on the underlying graph  $G$ :

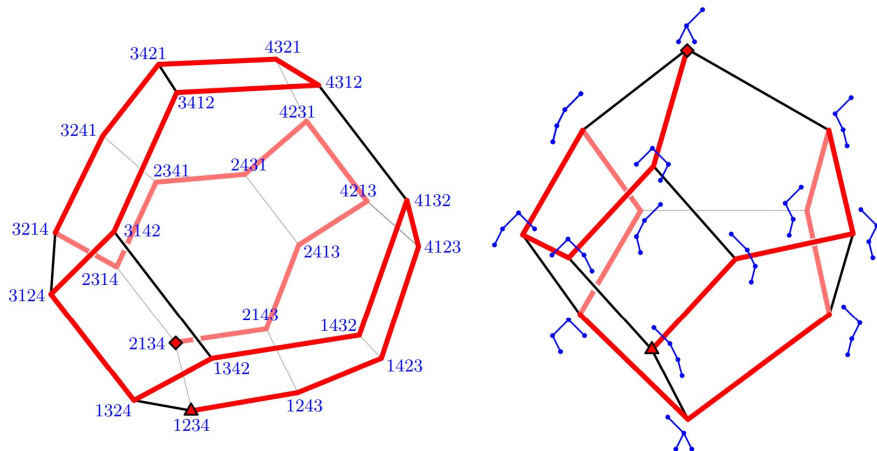
$G$	$\mathcal{A}(G)$
path	(standard) associahedron
complete graph	permutahedron
cycle	cyclohedron
star	stellohedron
matching	hypercube

# Illustration of some famous examples



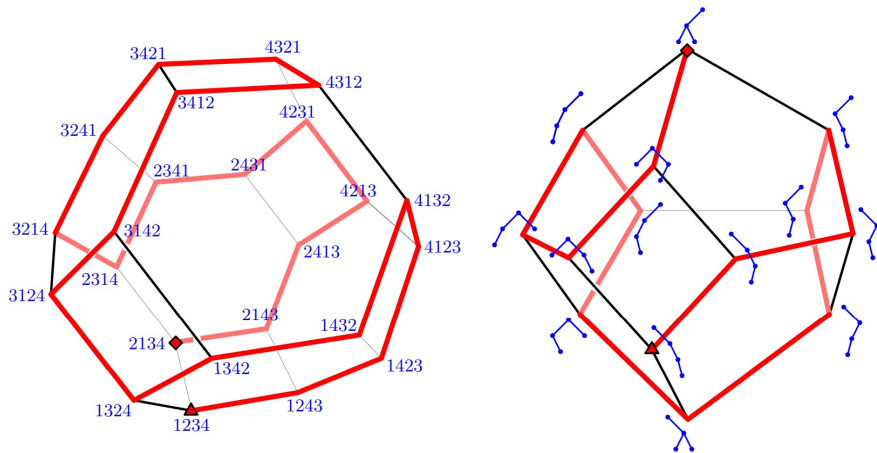
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# Zooming in: permutahedron and (standard) associahedron



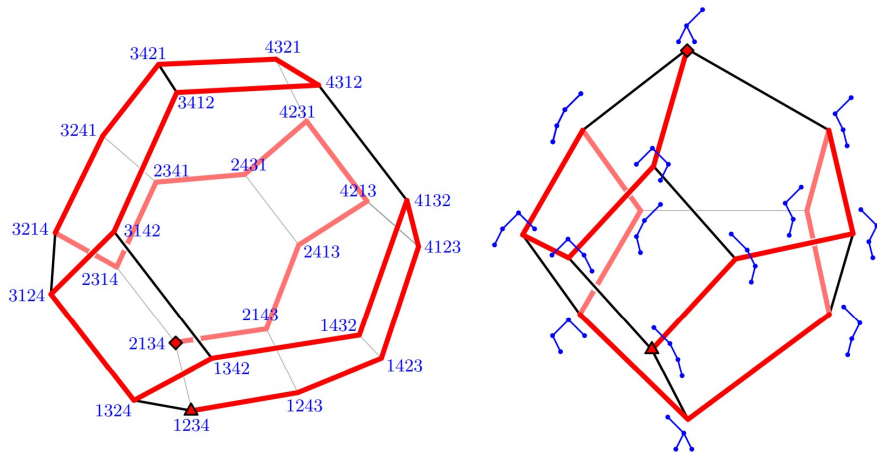
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The (standard) associahedron has a rich history and literature, connecting computer science, combinatorics, algebra, and topology.

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Binary trees are in **bijection** with many other **Catalan objects**:  
triangulations of a convex polygon, well-formed parenthesis, Dyck paths, ...

# Intensively studied: diameter of graph associahedra

Determining the **diameter** exactly, or upper/lower bounds, or estimates:

- If  $G$  is a **path**: [Sleator, Tarjan, Thurston. 1998]  
[Pournin. 2014]
- If  $G$  is a **star**: [Manneville, Pilaud. 2010]
- If  $G$  is a **cycle**: [Pournin. 2017]
- If  $G$  is a **tree**: [Manneville, Pilaud. 2010]  
[Cardinal, Langerman, Pérez-Lantero. 2018]
- If  $G$  is a **complete bipartite** or **trivially perfect** graph:  
[Cardinal, Pournin, Valencia-Pabon. 2022]
- If  $G$  is a **caterpillar**: [Berendsohn. 2022]
- If  $G$  has bounded **treedepth** or **treewidth**:  
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# Our focus: computing distances on graph associahedra

Suppose for simplicity that the considered graph  $G$  is connected.

## ROTATION DISTANCE

**Instance:** A graph  $G$ , two elimination trees  $T$  and  $T'$  of  $G$ , and a positive integer  $k$ .

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Only few cases known to be solvable in **polynomial time**:

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This is **not** the problem we solve!

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This motivates the study of the **parameterized complexity** of the problem.

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- **W[i]-hard** problem, for  $i \geq 1$ : strong evidence that it is *not* FPT.
- **para-NP-hard** problem: NP-hard for a fixed value of the parameter.

# Statement of the parameterized problem

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Prior to our work, only the case where  $G$  is a path was known to be FPT.

[Cleary, St. John. 2009] [Lucas. 2010] [Kanj, Sedgwick, Xia. 2017] [Li, Xia. 2023]

# Main ideas of the FPT algorithm

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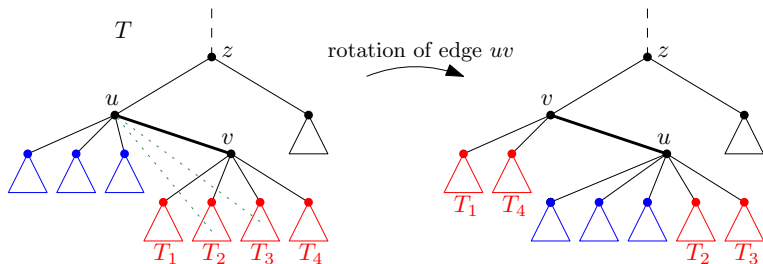
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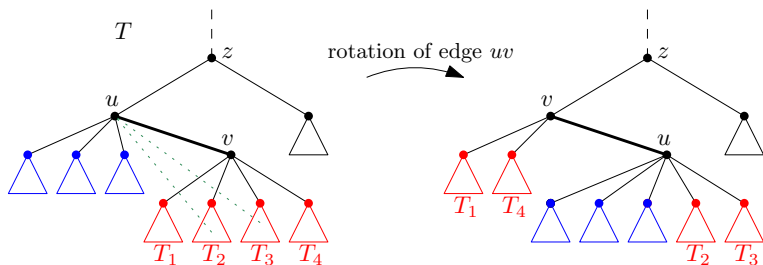
Let us see how we find such a “small” set  $M \subseteq V(T)$  of marked vertices...

# There are few children-bad vertices



**Observation:** a rotation may change the set of **children** of at most **three** vertices (but the parent of arbitrarily many vertices).

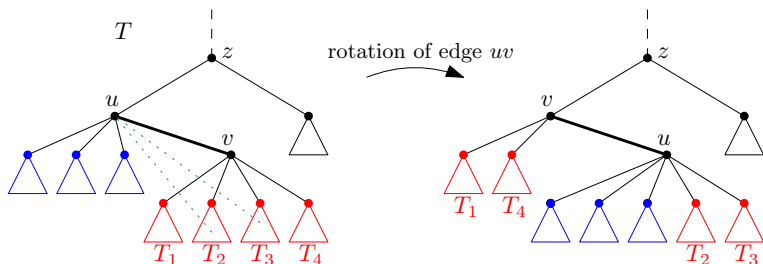
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We may assume that there are **at most  $3k$   $(T, T')$ -children-bad vertices**.

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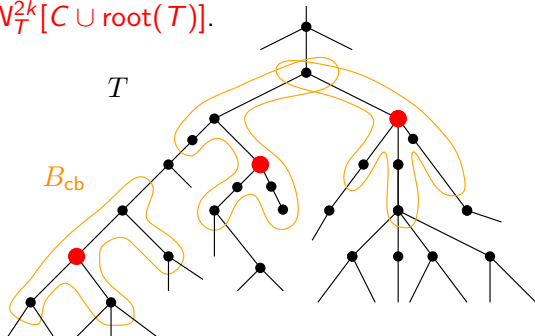
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We define  $B_{cb} = N_T^{2k}[C \cup \text{root}(T)]$ .

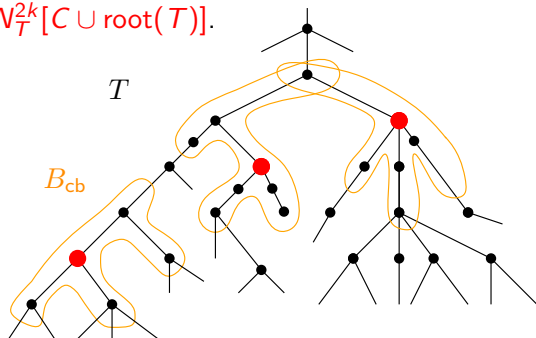


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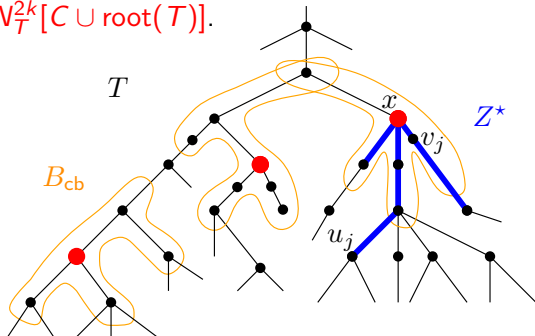
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If  $\Delta(T)$  is bounded (in particular, if  $\Delta(G)$  is bounded), we are done!

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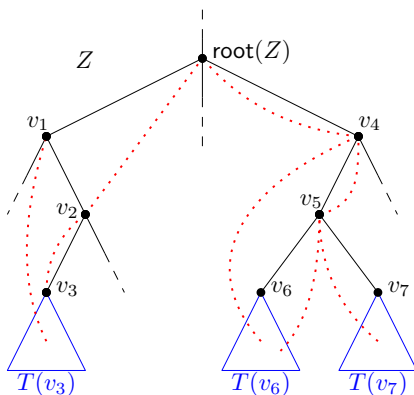
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# Towards the marking algorithm: trace of a vertex

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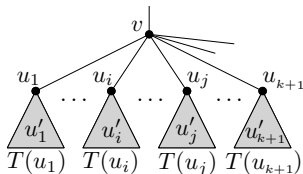
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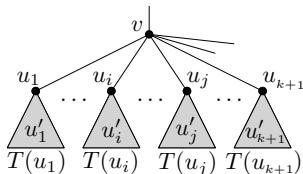
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Crucial: enough to keep track of “**at least  $k + 1$** ”, **not the actual number**.

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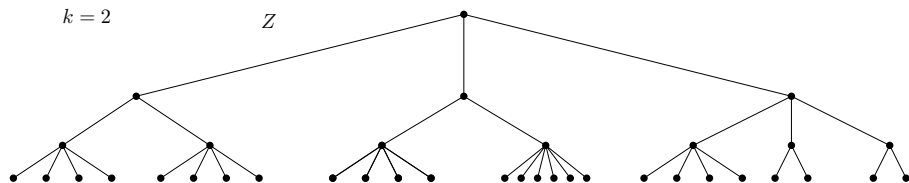
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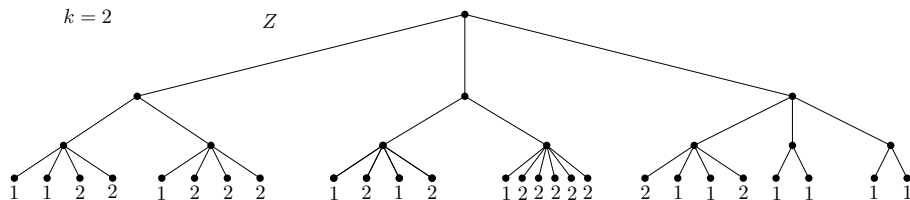
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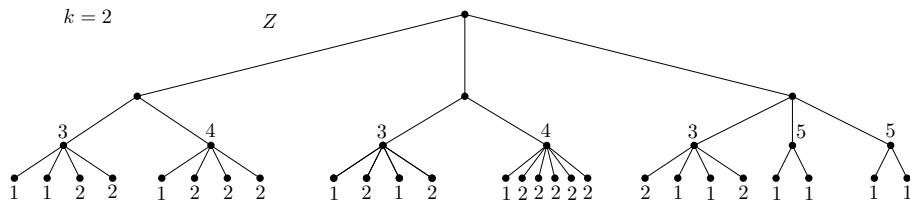
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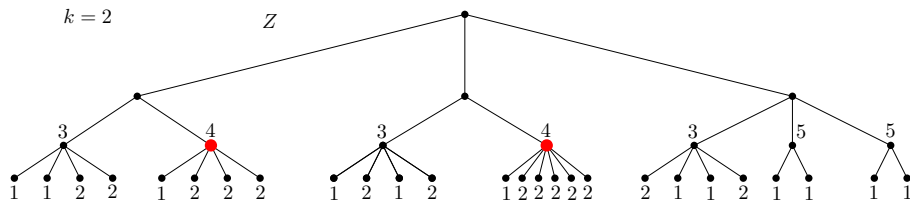
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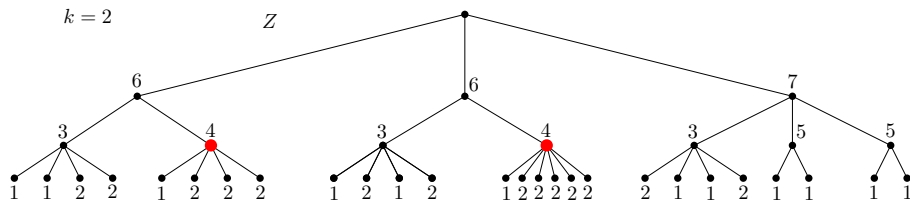
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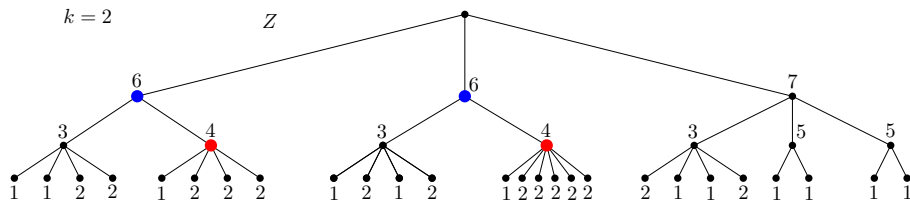
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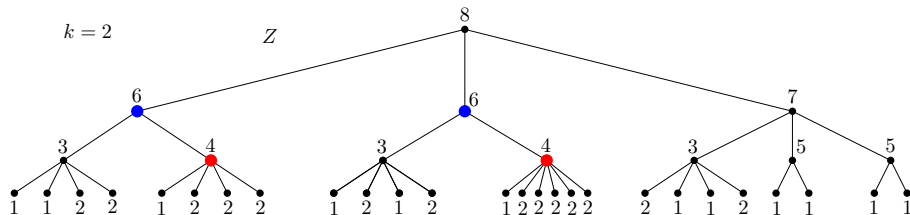
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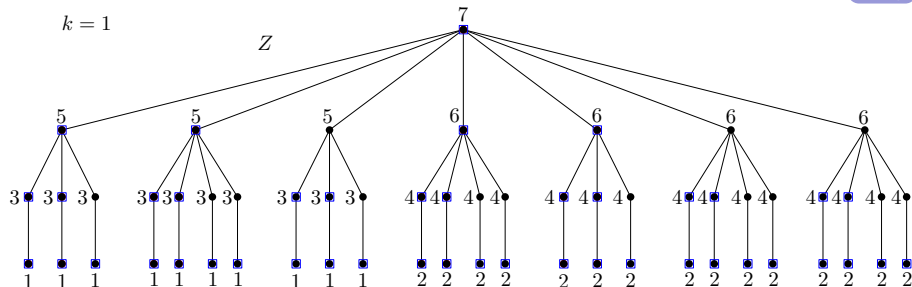
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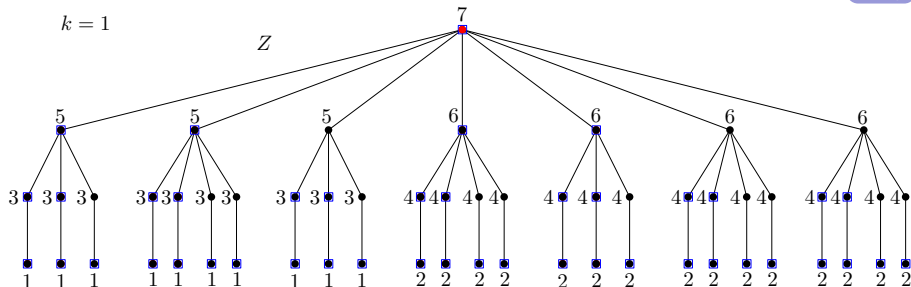
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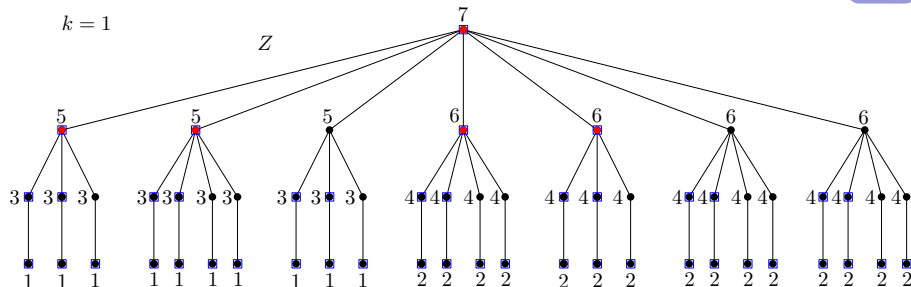
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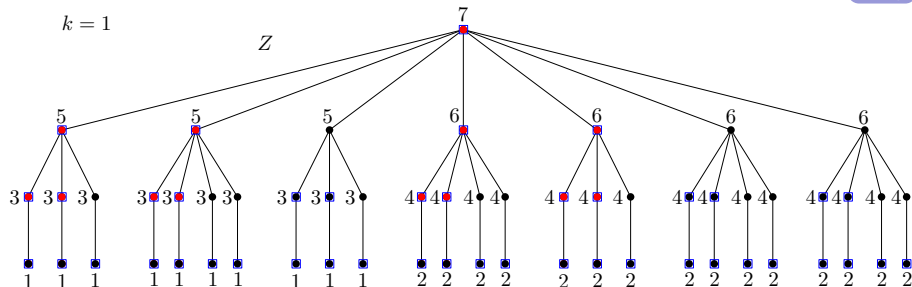
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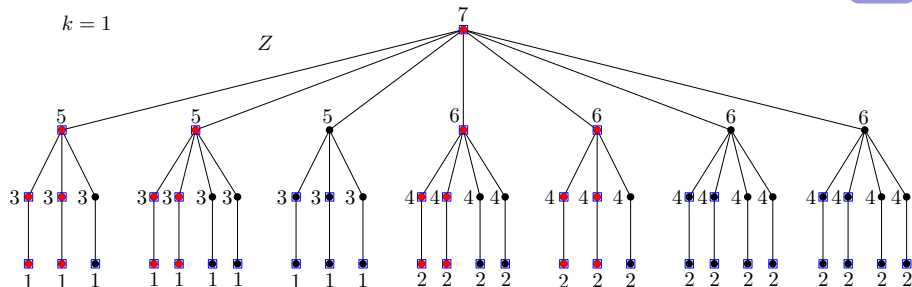
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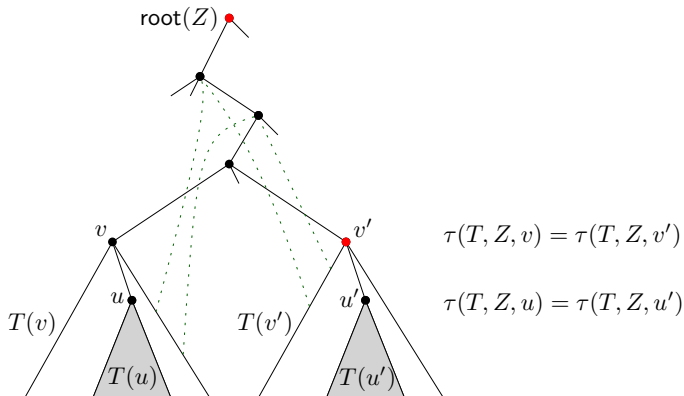
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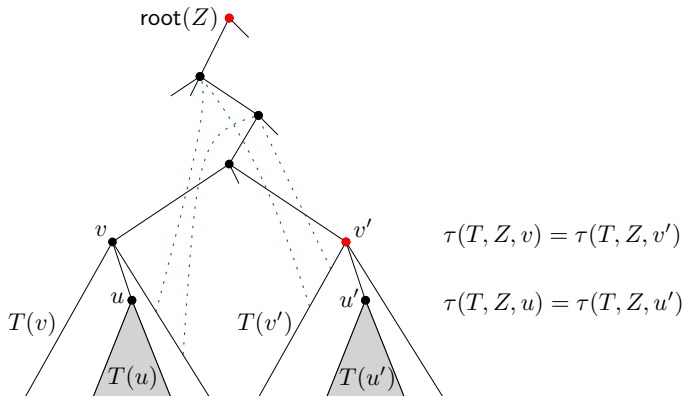
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We define  $\sigma'$  from  $\sigma$  by just replacing  $v$  with  $v'$  in all the rotations of  $\sigma$  involving  $v$ .

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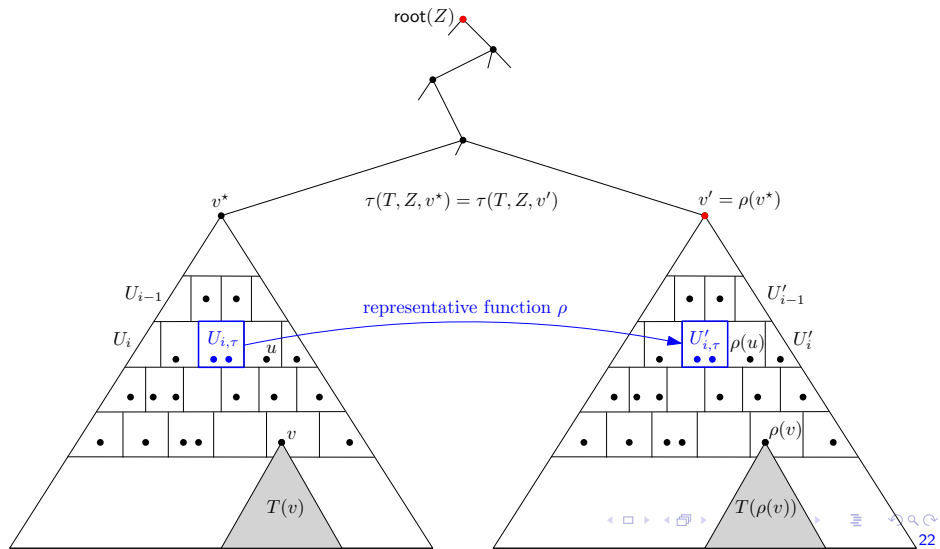
There exists a unique vertex  $v^* \in \text{ancestors}(Z, v)$  such that

- all vertices in  $T(v^*)$  are non-marked,
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- $v^*$  is the vertex closest to  $v$  satisfying the above properties.

# Proof of the main technical lemma: Case 2

All  $T$ -siblings  $v'$  of  $v$  with  $\tau(T, Z, v) = \tau(T, Z, v')$  are non-marked.

In this case, to define  $\sigma'$ , we need to modify  $\sigma$  in a more global way:



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ROTATION DISTANCE problem: distances on graph associahedra.

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Natural generalization: distances on hypergraphic polytopes.

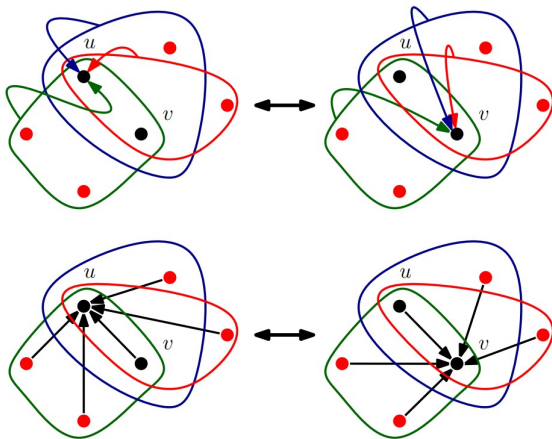
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Fix a **hypergraph**  $H$ . We define the **hypergraphic polytope** of  $H$  as:

- **Vertices:** all **acyclic orientations** of  $H$ .
- **Edges:** if the two corresponding rotations are related by a **flip**.



# New results: can we go beyond graph associahedra?

Computing distances on **hypergraphic polytopes** is **NP-hard**.

[Cardinal, Steiner. 2023]

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We present a parameterized reduction from  *$k$ -DOMINATING SET*.

# Conclusions and further research

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## Theorem

The **ROTATION DISTANCE** problem can be solved in time  $f(k) \cdot |V(G)|$ ,

$$\text{with } f(k) = k^{k \cdot 2^{2^{\cdot^{2^{\mathcal{O}(k^2)}}}}},$$

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ROTATION DISTANCE	paths	general graphs
NP-hard	open	✓
FPT	✓	✓ [this talk]
Polynomial kernel	✓	open

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## COMBINATORIAL SHORTEST PATH ON POLYMATROIDS:

- **NP-hard**. [Ito, Kakimura, Kamiyama, Kobayashi, Maezawa, Nozaki, Okamoto. 2023]
- Is it also **FPT**?

Gràcies!