

Hardness and Approximation of Traffic Grooming

Omid Amini *Stéphane Pérennes* **Ignasi Sau**

Projet MASCOTTE, CNRS/I3S-INRIA-UNSA, France

COST 293 - Rome

Outline of the talk

- Introduction
- Traffic Grooming
 - ▶ Definition of the problem
 - ▶ Example
 - ▶ State of the art
 - ▶ Evolution in COST 293
- Problem of MECT-B
- Hardness results
- Approximation algorithm
- Conclusions

How to prove hardness results

- **Class APX (Approximable):**

an optimization problem is in APX if it admits to be approximated within a constant factor.

Example: VERTEX COVER

- **Class PTAS (Polynomial-Time Approximation Scheme):**

an optimization problem is in PTAS if it admits to be approximated within a factor $1 + \epsilon$, for all $\epsilon > 0$.

(the best one can hope for an NP-hard optimization problem).

Ex.: TRAVELING SALESMAN PROBLEM *in the Euclidean plane*

- We know that

$$\text{PTAS} \subsetneq \text{APX}$$

- So, if Π is an optimization problem:

$$\Pi \text{ is APX-hard} \Rightarrow \Pi \notin \text{PTAS}$$

How to prove hardness results

- **Class APX (Approximable):**

an optimization problem is in APX if it admits to be approximated within a constant factor.

Example: VERTEX COVER

- **Class PTAS (Polynomial-Time Approximation Scheme):**

an optimization problem is in PTAS if it admits to be approximated within a factor $1 + \varepsilon$, for all $\varepsilon > 0$.

(the best one can hope for an NP-hard optimization problem).

Ex.: TRAVELING SALESMAN PROBLEM *in the Euclidean plane*

- We know that

$$\text{PTAS} \subsetneq \text{APX}$$

- So, if Π is an optimization problem:

$$\Pi \text{ is APX-hard} \Rightarrow \Pi \notin \text{PTAS}$$

How to prove hardness results

- **Class APX (Approximable):**

an optimization problem is in APX if it admits to be approximated within a constant factor.

Example: VERTEX COVER

- **Class PTAS (Polynomial-Time Approximation Scheme):**

an optimization problem is in PTAS if it admits to be approximated within a factor $1 + \varepsilon$, for all $\varepsilon > 0$.

(the best one can hope for an NP-hard optimization problem).

Ex.: TRAVELING SALESMAN PROBLEM *in the Euclidean plane*

- We know that

$$\text{PTAS} \subsetneq \text{APX}$$

- So, if Π is an optimization problem:

$$\Pi \text{ is APX-hard} \Rightarrow \Pi \notin \text{PTAS}$$

Traffic Grooming

Introduction

- WDM (Wavelength Division Multiplexing) networks

- ▶ 1 wavelength (or frequency) = up to 40 Gb/s
- ▶ 1 fiber = hundreds of wavelengths = Tb/s

- Idea

Traffic grooming consists in packing low-speed traffic flows into higher speed streams

→ we allocate the same wavelength to several low-speed requests (TDM, Time Division Multiplexing)

- Objectives

- ▶ Better use of bandwidth
- ▶ Reduce the equipment cost (mostly given by electronics)

Introduction

- WDM (Wavelength Division Multiplexing) networks

- ▶ 1 wavelength (or frequency) = up to 40 Gb/s
- ▶ 1 fiber = hundreds of wavelengths = Tb/s

- Idea

Traffic grooming consists in packing low-speed traffic flows into higher speed streams

→ we allocate the same wavelength to several low-speed requests (TDM, Time Division Multiplexing)

- Objectives

- ▶ Better use of bandwidth
- ▶ Reduce the equipment cost (mostly given by electronics)

Introduction

- WDM (Wavelength Division Multiplexing) networks

- ▶ 1 wavelength (or frequency) = up to 40 Gb/s
- ▶ 1 fiber = hundreds of wavelengths = Tb/s

- Idea

Traffic grooming consists in packing low-speed traffic flows into higher speed streams

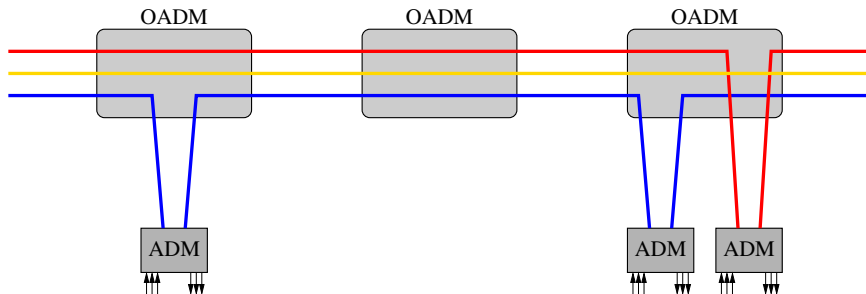
→ we allocate the same wavelength to several low-speed requests (TDM, Time Division Multiplexing)

- Objectives

- ▶ Better use of bandwidth
- ▶ Reduce the equipment cost (mostly given by electronics)

ADM and OADM

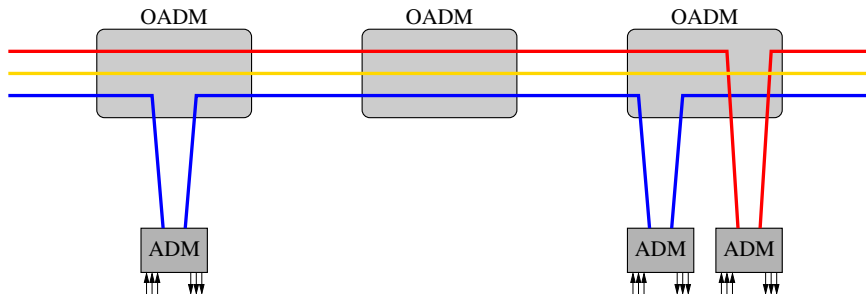
- **OADM** (Optical Add/Drop Multiplexer)= insert/extract a wavelength to/from an optical fiber
- **ADM** (Add/Drop Multiplexer)= insert/extract an OC/STM (electric low-speed signal) to/from a wavelength



→ we want to minimize the number of ADMs

ADM and OADM

- **OADM** (Optical Add/Drop Multiplexer)= insert/extract a wavelength to/from an optical fiber
- **ADM** (Add/Drop Multiplexer)= insert/extract an OC/STM (electric low-speed signal) to/from a wavelength



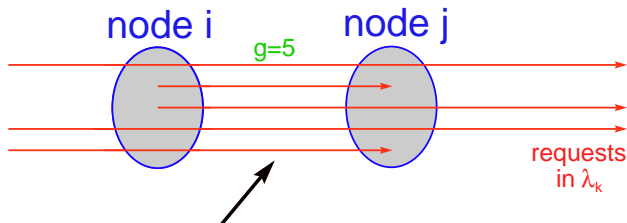
→ we want to minimize the number of ADMs

Definitions

- **Request** (i, j) : a pair of vertices i, j that want to exchange (low-speed) traffic

Definitions

- **Request** (i, j) : a pair of vertices (i, j) that want to exchange (low-speed) traffic
- **Grooming factor** g :



For each wavelength and each arc between two nodes, there can be only g requests routed through this arc

Example:

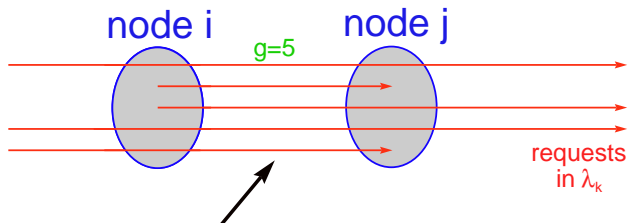
Capacity of one wavelength = 2400 Mb/s

Capacity used by a request = 600 Mb/s

$\Rightarrow g = 4$

Definitions

- **Request** (i, j) : a pair of vertices (i, j) that want to exchange (low-speed) traffic
- **Grooming factor** g :



For each wavelength and each arc between two nodes, there can be only g requests routed through this arc

Example:

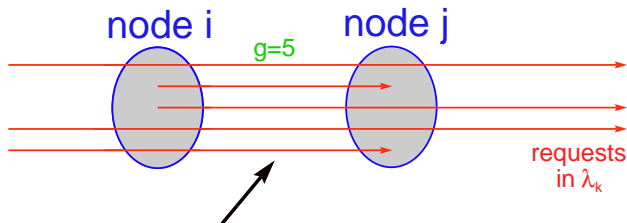
Capacity of one wavelength = 2400 Mb/s

Capacity used by a request = 600 Mb/s

$$\Rightarrow g = 4$$

Definitions

- **Request** (i, j) : a pair of vertices (i, j) that want to exchange (low-speed) traffic
- **Grooming factor** g :

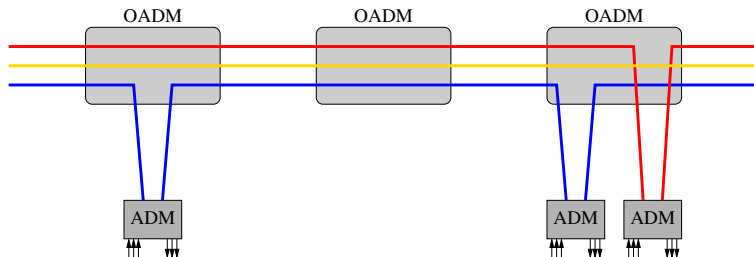


For each wavelength and each arc between two nodes, there can be only g requests routed through this arc

- **load** of an arc in a wavelength: number of requests using this arc in this wavelength ($\leq g$)

ADM and OADM

- **OADM** (Optical Add/Drop Multiplexer)= insert/extract a wavelength to/from an optical fiber
- **ADM** (Add/Drop Multiplexer)= insert/extract an OC/STM (electric low-speed signal) to/from a wavelength



- **Idea:** Use an **ADM only at the endpoints of a request** (lightpaths) in order to save as many ADMs as possible

To fix ideas...

- Model:

Topology	→	oriented graph G
Request set	→	oriented graph R
Grooming factor	→	integer g
Request in a wavelength	→	arcs in a subgraph of R
ADM in a wavelength	→	node in a subgraph of R

- We study the cases when $G = C_n$ (ring) or $G = P_n$ (path)

To fix ideas...

- Model:

Topology	→	oriented graph G
Request set	→	oriented graph R
Grooming factor	→	integer g
Request in a wavelength	→	arcs in a subgraph of R
ADM in a wavelength	→	node in a subgraph of R

- We study the cases when $G = C_n$ (ring) or $G = P_n$ (path)

Statement of the problem

Ring traffic grooming

Input

A cycle C_n on n nodes (network)
An oriented graph R (request set)
A grooming factor g

Output

Find for each arc $r \in R$ a path $P(r)$ in C_n , and a partition of the arcs of R into subgraphs R_ω , $1 \leq \omega \leq W$, in such a way that

$$\forall e \in E(C_n), \quad \text{load}(R_\omega, e) \leq g$$

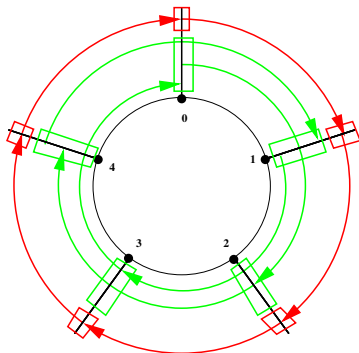
Objective

Minimize $\sum_{\omega=1}^W |V(R_\omega)|$

Example: $n = 5$, $R = K_5$, and $g = 2$

Example: $n = 5$, $R = K_5$, and $g = 2$

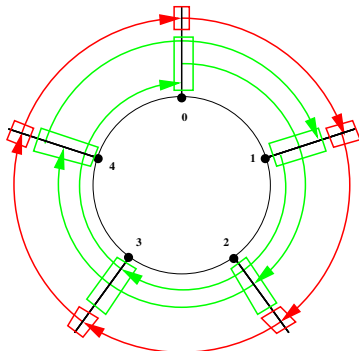
We partition the edges of R in two ways, both using two wavelengths:



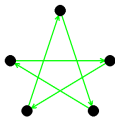
10 ADMS

Example: $n = 5$, $R = K_5$, and $g = 2$

We partition the edges of R in two ways, both using two wavelengths:

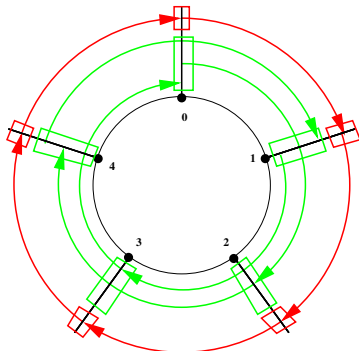


10 ADMS

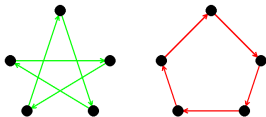


Example: $n = 5$, $R = K_5$, and $g = 2$

We partition the edges of R in two ways, both using two wavelengths:

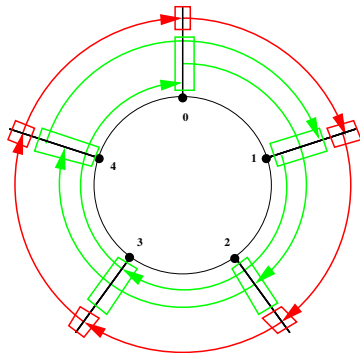


10 ADMS

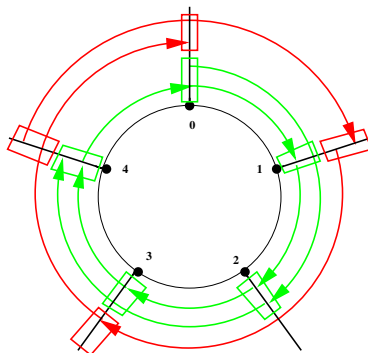


Example: $n = 5$, $R = K_5$, and $g = 2$

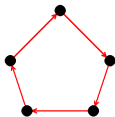
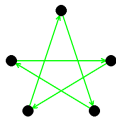
We partition the edges of R in two ways, both using two wavelengths:



10 ADMS

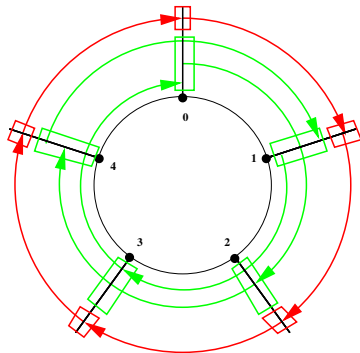


9 ADMS

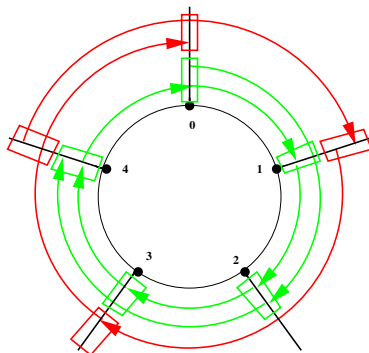
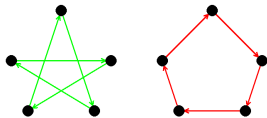


Example: $n = 5$, $R = K_5$, and $g = 2$

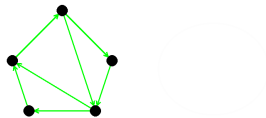
We partition the edges of R in two ways, both using two wavelengths:



10 ADMS

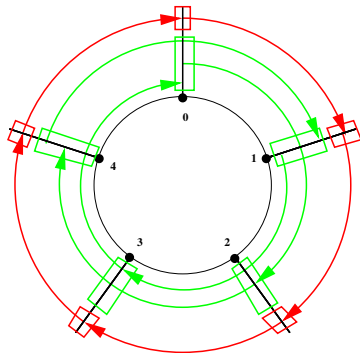


9 ADMS

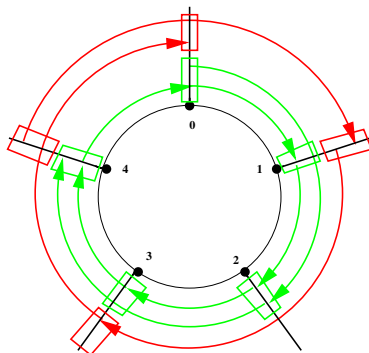
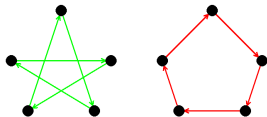


Example: $n = 5$, $R = K_5$, and $g = 2$

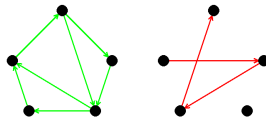
We partition the edges of R in two ways, both using two wavelengths:



10 ADMS



9 ADMS



State of the art (in the ring)

● Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG is **not in APX**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

● Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** good algorithm in polynomial time in g and n (i.e. when g is also part of the input)

State of the art (in the ring)

- Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG is **not in APX**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

- Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** good algorithm in polynomial time in g and n (i.e. when g is also part of the input)

State of the art (in the ring)

- Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG is **not in APX**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

- Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** good algorithm in polynomial time in g and n (i.e. when g is also part of the input)

State of the art (in the ring)

- Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG **is not in APX**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

- Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** good algorithm in polynomial time in g and n (i.e. when g is also part of the input)

State of the art (in the ring)

- Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG is **not in APX**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

- Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** good algorithm in polynomial time in g and n (i.e. when g is also part of the input)

State of the art (in the ring)

- Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG **is not in APX**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

- Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** *good* algorithm in polynomial time in g and n (i.e. when g is also part of the input)

State of the art (in the ring)

- Complexity:

- ▶ TRAFFIC GROOMING (TG) is **NP-complete** considering g as part of the input
(*T.Chow et P.Lin, Networks'04*)
- ▶ TG remains also NP-complete for fixed $g \geq 1$
(*M.Shalom, W.Unger et S.Zaks, FUN'07*)
- ▶ If g is part of the input, TG **is not in APx**
(*S.Huang, R.Dutta et G.N.Rouskas, IEEE JSAC'06*)
- ▶ **Open problem:** inapproximability for fixed g

- Approximability:

- ▶ Finding a \sqrt{g} -approximation is trivial (in polynomial time in n and g)
- ▶ The best approximation algorithm has ratio $\mathcal{O}(\log g)$, but the running time is exponential in g (more precisely, n^g)
(*M.Flammini et al., ISAAC'05*)
- ▶ **Open problem:** good algorithm in polynomial time in g and n (i.e. when g is also part of the input)

Different models of TRAFFIC GROOMING (in COST 293):

- There are many different models of TRAFFIC GROOMING in the literature.
- We focus on a **particular model** (minimizing the number of ADMs)
- Other models: G/MPLS, light-trails, light-tours, multi-cast aggregation, ...
- Some of the people who is working in other models:
T.Ginkler, M.Marciniak, J.-L.Marzo, F.Solano, J.Moulierac, A.Somani, ...

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (*ONDM'03*):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (*BROADNETS'04*):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (*SIAM JDM'05*):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (*SIROCCO'05*):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (*ISAAC'05*):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (*WG'06*):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (*ICTON'06*):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (*FUN'07*):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (*ISAAC'07*):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (*ONDM'03*):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (*BROADNETS'04*):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (*SIAM JDM'05*):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (*SIROCCO'05*):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (*ISAAC'05*):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (*WG'06*):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (*ICTON'06*):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (*FUN'07*):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (*ISAAC'07*):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (*ONDM'03*):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (*BROADNETS'04*):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (*SIAM JDM'05*):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (*SIROCCO'05*):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (*ISAAC'05*):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (*WG'06*):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (*ICTON'06*):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (*FUN'07*):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (*ISAAC'07*):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (*ONDM'03*):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (*BROADNETS'04*):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (*SIAM JDM'05*):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (*SIROCCO'05*):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (*ISAAC'05*):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (*WG'06*):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (*ICTON'06*):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (*FUN'07*):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (*ISAAC'07*):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (ONDM'03):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (BROADNETS'04):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (SIAM JDM'05):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (SIROCCO'05):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (ISAAC'05):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (WG'06):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (ICTON'06):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (FUN'07):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (ISAAC'07):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (ONDM'03):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (BROADNETS'04):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (SIAM JDM'05):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (SIROCCO'05):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (ISAAC'05):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (WG'06):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (ICTON'06):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (FUN'07):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (ISAAC'07):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (ONDM'03):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (BROADNETS'04):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (SIAM JDM'05):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (SIROCCO'05):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (ISAAC'05):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (WG'06):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (ICTON'06):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (FUN'07):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (ISAAC'07):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- 2003 Coudert, Muñoz et al. (ONDM'03):
Statement of the problem in unidirectional rings (all-to-all case).
- 2004 Shalom and Zaks (BROADNETS'04):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- 2005 Coudert, Muñoz et al. (SIAM JDM'05):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- 2005 Coudert et al. (SIROCCO'05):
Grooming in unidirectional paths for $g = 1, 2$.
- 2005 Flammini, Moscadelli, Shalom and Zaks (ISAAC'05):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- 2006 Flammini, Moscadelli, Shalom, Zaks et al. (WG'06):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- 2006 Coudert, Muñoz, Sau et al. (ICTON'06):
Grooming in bidirectional rings (all-to-all case).
- 2007 Shalom, Unger and Zaks (FUN'07):
Grooming in rings is NP-complete for fixed g .
- 2007 Amini, Pérennes and Sau (ISAAC'07):
Hardness and approximation of traffic grooming in rings and paths.

Evolution of Traffic Grooming in COST 293:

- **2003** Coudert, Muñoz et al. (*ONDM'03*):
Statement of the problem in unidirectional rings (all-to-all case).
- **2004** Shalom and Zaks (*BROADNETS'04*):
 $(\frac{10}{7} + \epsilon)$ -approximation of grooming in rings for $g = 1$.
- **2005** Coudert, Muñoz et al. (*SIAM JDM'05*):
Grooming in unidirectional rings for $g = 6$ (all-to-all case).
- **2005** Coudert et al. (*SIROCCO'05*):
Grooming in unidirectional paths for $g = 1, 2$.
- **2005** Flammini, Moscadelli, Shalom and Zaks (*ISAAC'05*):
 $\mathcal{O}(\log g)$ -approximation of grooming in rings.
- **2006** Flammini, Moscadelli, Shalom, Zaks et al. (*WG'06*):
 $\mathcal{O}(\log g)$ -approximation of grooming in paths and stars.
- **2006** Coudert, Muñoz, Sau et al. (*ICTON'06*):
Grooming in bidirectional rings (all-to-all case).
- **2007** Shalom, Unger and Zaks (*FUN'07*):
Grooming in rings is NP-complete for fixed g .
- **2007** Amini, Pérennes and Sau (*ISAAC'07*):
Hardness and approximation of traffic grooming in rings and paths.

Summing up: open questions

- (1) Inapproximability (hardness) of TRAFFIC GROOMING for fixed g .
- (2) *Good* algorithm for approximating TRAFFIC GROOMING, running in polynomial time in both g and n , and with an approximation ratio not depending on g .

Hardness of grooming for fixed g

- Now we are going to answer to the first open question:

Theorem

Traffic grooming in the ring is APX-complete for fixed $g \geq 1$.

Theorem

Traffic grooming in the path is APX-complete for fixed $g \geq 2$.

- To prove these results, we reduce traffic grooming to the following problem:

Finding the maximum number of edge-disjoint triangles in a graph.

Hardness of grooming for fixed g

- Now we are going to answer to the first open question:

Theorem

Traffic grooming in the ring is APX-complete for fixed $g \geq 1$.

Theorem

Traffic grooming in the path is APX-complete for fixed $g \geq 2$.

- To prove these results, we reduce traffic grooming to the following problem:

Finding the maximum number of edge-disjoint triangles in a graph.

Hardness of grooming for fixed g

- Now we are going to answer to the first open question:

Theorem

Traffic grooming in the ring is APX-complete for fixed $g \geq 1$.

Theorem

Traffic grooming in the path is APX-complete for fixed $g \geq 2$.

- To prove these results, we reduce traffic grooming to the following problem:

Finding the maximum number of edge-disjoint triangles in a graph.

MECT-B

- MAXIMUM BOUNDED EDGE COVERING BY TRIANGLES (MECT-B):
Find the maximum number of edge-disjoint triangles in a graph of bounded degree B .
- The problem is NP-complete
(*I.Holyer, SIAM J.Comput'81*)
- Finding **node-disjoint** triangles is APX-complete
(*V.Kann, Inf. Proces. Let'91*)
- We have proved that MECT-B is also APX-complete

MECT-B

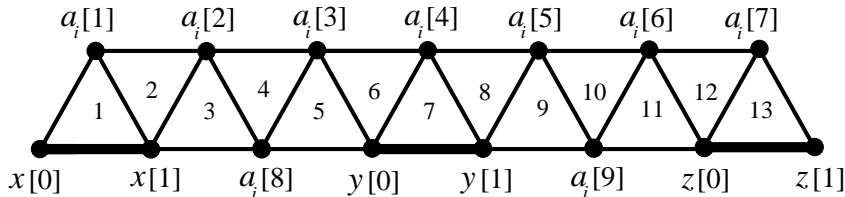
- MAXIMUM BOUNDED EDGE COVERING BY TRIANGLES (MECT-B):
Find the maximum number of edge-disjoint triangles in a graph of bounded degree B .
- The problem is NP-complete
(*I.Holyer, SIAM J.Comput'81*)
- Finding **node-disjoint** triangles is APX-complete
(*V.Kann, Inf. Proces. Let'91*)
- We have proved that MECT-B is also APX-complete

MECT-B

- MAXIMUM BOUNDED EDGE COVERING BY TRIANGLES (MECT-B):
Find the maximum number of edge-disjoint triangles in a graph of bounded degree B .
- The problem is NP-complete
(*I.Holyer, SIAM J.Comput'81*)
- Finding **node-disjoint** triangles is APX-complete
(*V.Kann, Inf. Proces. Let'91*)
- We have proved that MECT-B is also APX-complete

Idea of the proof

- Reduction from MAXIMUM BOUNDED COVERING BY 3-SETS (MAX 3SC-B).
- For each subset $c_i = \{x_i, y_i, z_i\}$ we build the following graph:

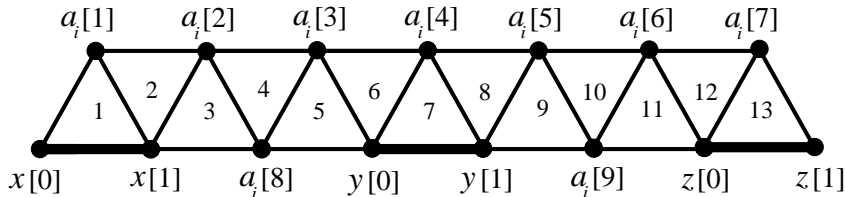


- We deduce that

$$OPT(MECT-B) \leq (18B + 1)OPT(\text{MAX 3SC-B})$$

Idea of the proof

- Reduction from MAXIMUM BOUNDED COVERING BY 3-SETS (MAX 3SC-B).
- For each subset $c_i = \{x_i, y_i, z_i\}$ we build the following graph:

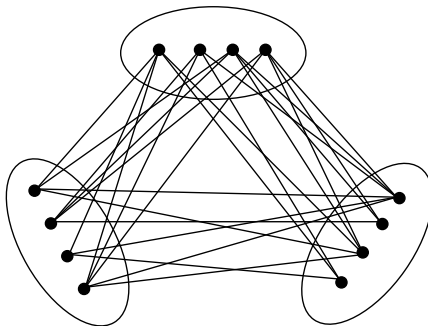


- We deduce that

$$OPT(MECT-B) \leq (18B + 1)OPT(\text{MAX 3SC-B})$$

APX-completeness of RING TRAFFIC GROOMING

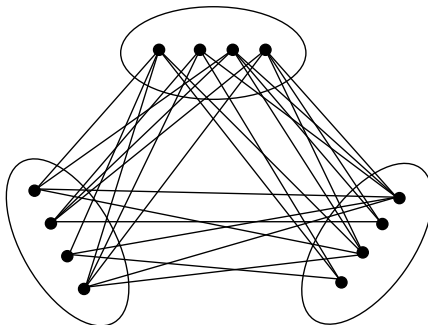
- Idea of the proof for $g = 1$: we take a tripartite request graph:



- The problem of traffic grooming is equivalent to finding the maximum number of edge-disjoint triangles
- Thus, traffic grooming is APX-complete

APX-completeness of RING TRAFFIC GROOMING

- Idea of the proof for $g = 1$: we take a tripartite request graph:



- The problem of traffic grooming is equivalent to finding the maximum number of edge-disjoint triangles
- Thus, traffic grooming is APX-complete

APX-completeness of PATH TRAFFIC GROOMING

- The problem is in P for $g = 1$
(*J.-C.Bermond, L.Braud and D.Coudert, SIROCCO'05*)
- The complexity for fixed $g \geq 2$ (even if $P/NP?$) has been an open problem for a while
- We have proved that the problem is APX-complete for fixed $g \geq 2$

APX-completeness of PATH TRAFFIC GROOMING

- The problem is in P for $g = 1$
(*J.-C.Bermond, L.Braud and D.Coudert, SIROCCO'05*)
- The complexity for fixed $g \geq 2$ (even if $P/NP?$) has been an open problem for a while
- We have proved that the problem is APX-complete for fixed $g \geq 2$

Approximation algorithm for TRAFFIC GROOMING

- Now we are going to answer to the second open question:

approximation algorithm (for rings and paths) with running time polynomial in both n and g , with an approximation ratio depending only on n :

Theorem

There exists a polynomial-time approximation algorithm that approximates RING TRAFFIC GROOMING within a factor $\mathcal{O}(n^{1/3} \log^2 n)$ for any $g \geq 1$.

Approximation algorithm for TRAFFIC GROOMING

- Now we are going to answer to the second open question:

approximation algorithm (for rings and paths) with running time polynomial in both n and g , with an approximation ratio depending only on n :

Theorem

There exists a polynomial-time approximation algorithm that approximates RING TRAFFIC GROOMING within a factor $\mathcal{O}(n^{1/3} \log^2 n)$ for any $g \geq 1$.

Idea of the algorithm: first step

- Divide the request set into $\log n$ classes C_i , $i = 0, \dots, \log n - 1$ s.t. in each class C_i the length of the requests is in $[2^i, 2^{i+1})$:

$C_0 \rightarrow$ length in the interval $[1, 2)$

$C_1 \rightarrow$ length in the interval $[2, 4)$

$C_2 \rightarrow$ length in the interval $[4, 8)$

...

$C_{\log n - 1} \rightarrow$ length in the interval $[\frac{n}{2}, n)$

First step of the algorithm (II)

- For each class $C_i \rightarrow$ the ring can be divided into intervals of length 2^i s.t. the **only requests are between consecutive intervals**.
- we obtain $\frac{n}{2^i}$ subproblems for each class:
each one consists in finding an optimal solution in a bipartite graph of size $2 \cdot 2^i$.

BIPARTITE TRAFFIC GROOMING

Input: A bipartite graph R , and a grooming factor g .

Output: Partition of the edges of R into subgraphs R_ω with at most g edges, $1 \leq \omega \leq W$.

Objective: Minimize $\sum_{\omega=1}^W |V(R_\omega)|$.

- Solve all these BIPARTITE TRAFFIC GROOMING subproblems independently, and output the union of all solutions.

First step of the algorithm (II)

- For each class $C_i \rightarrow$ the ring can be divided into intervals of length 2^i s.t. the **only requests are between consecutive intervals**.
- we obtain $\frac{n}{2^i}$ subproblems for each class:
each one consists in finding an optimal solution in a bipartite graph of size $2 \cdot 2^i$.

BIPARTITE TRAFFIC GROOMING

Input: A bipartite graph R , and a grooming factor g .

Output: Partition of the edges of R into subgraphs R_ω with at most g edges, $1 \leq \omega \leq W$.

Objective: Minimize $\sum_{\omega=1}^W |V(R_\omega)|$.

- Solve all these BIPARTITE TRAFFIC GROOMING subproblems independently, and output the union of all solutions.

First step of the algorithm (II)

- For each class $C_i \rightarrow$ the ring can be divided into intervals of length 2^i s.t. the **only requests are between consecutive intervals**.
- we obtain $\frac{n}{2^i}$ subproblems for each class:
each one consists in finding an optimal solution in a bipartite graph of size $2 \cdot 2^i$.

BIPARTITE TRAFFIC GROOMING

Input: A bipartite graph R , and a grooming factor g .

Output: Partition of the edges of R into subgraphs R_ω with at most g edges, $1 \leq \omega \leq W$.

Objective: Minimize $\sum_{\omega=1}^W |V(R_\omega)|$.

- Solve all these BIPARTITE TRAFFIC GROOMING subproblems independently, and output the union of all solutions.

First step of the algorithm (II)

- For each class $C_i \rightarrow$ the ring can be divided into intervals of length 2^i s.t. the **only requests are between consecutive intervals**.
- we obtain $\frac{n}{2^i}$ subproblems for each class:
each one consists in finding an optimal solution in a bipartite graph of size $2 \cdot 2^i$.

BIPARTITE TRAFFIC GROOMING

Input: A bipartite graph R , and a grooming factor g .

Output: Partition of the edges of R into subgraphs R_ω with at most g edges, $1 \leq \omega \leq W$.

Objective: Minimize $\sum_{\omega=1}^W |V(R_\omega)|$.

- Solve all these BIPARTITE TRAFFIC GROOMING subproblems independently, and output the union of all solutions.

Second step of the algorithm

- The **density** $\rho(G)$ of a graph $G = (V, E)$: is its edges-to-vertices ratio, that is:

$$\rho(G) := \frac{|E(G)|}{|V(G)|}$$

- More generally, for any subset $S \subset V$, we call *density* of S , $\rho_G(S)$ or simply $\rho(S)$, to the density of the induced graph on S , i.e. $\rho(S) := \rho(G[S])$.
- We use the DENSE k -SUBGRAPH optimization problem:

DENSE k -SUBGRAPH (DkS):

Input: a graph $G = (V, E)$.

Output: a subset $S \subseteq V$, with $|S| = k$, such that $\rho(S)$ is maximized.

(U.Feige, D.Peleg and G.Kortsarz, Algorithmica'01)

Second step of the algorithm

- The **density** $\rho(G)$ of a graph $G = (V, E)$: is its edges-to-vertices ratio, that is:

$$\rho(G) := \frac{|E(G)|}{|V(G)|}$$

- More generally, for any subset $S \subset V$, we call *density* of S , $\rho_G(S)$ or simply $\rho(S)$, to the density of the induced graph on S , i.e. $\rho(S) := \rho(G[S])$.
- We use the DENSE k -SUBGRAPH optimization problem:

DENSE k -SUBGRAPH (DkS):

Input: a graph $G = (V, E)$.

Output: a subset $S \subseteq V$, with $|S| = k$, such that $\rho(S)$ is maximized.

(U.Feige, D.Peleg and G.Kortsarz, Algorithmica'01)

Second step of the algorithm (II)

- To solve each BIPARTITE TRAFFIC GROOMING subproblem in a bipartite graph R :

proceed **greedily** (until all edges are covered),
by finding at step i a **subgraph**

$$R_i \subseteq G \setminus (R_1 \cup \dots \cup R_{i-1})$$

with at most g edges in the following way:

For each $k = 2, \dots, 2g$ find a subgraph

$$B_k \subseteq R \setminus (R_1 \cup \dots \cup R_{i-1})$$

using the best algorithm for the **DENSE k -SUBGRAPH** problem.
(*U.Feige, D.Peleg and G.Kortsarz, Algorithmica'01*)

- Now we have to choose one of these B_k .

Second step of the algorithm (II)

- To solve each BIPARTITE TRAFFIC GROOMING subproblem in a bipartite graph R :

proceed **greedily** (until all edges are covered),
by finding at step i a **subgraph**

$$R_i \subseteq G \setminus (R_1 \cup \dots \cup R_{i-1})$$

with at most g edges in the following way:

For each $k = 2, \dots, 2g$ find a subgraph

$$B_k \subseteq R \setminus (R_1 \cup \dots \cup R_{i-1})$$

using the best algorithm for the **DENSE k -SUBGRAPH** problem.
(*U.Feige, D.Peleg and G.Kortsarz, Algorithmica'01*)

- Now we have to choose one of these B_k .

Second step of the algorithm (II)

- To solve each BIPARTITE TRAFFIC GROOMING subproblem in a bipartite graph R :

proceed **greedily** (until all edges are covered),
by finding at step i a **subgraph**

$$R_i \subseteq G \setminus (R_1 \cup \dots \cup R_{i-1})$$

with at most g edges in the following way:

For each $k = 2, \dots, 2g$ find a subgraph

$$B_k \subseteq R \setminus (R_1 \cup \dots \cup R_{i-1})$$

using the best algorithm for the **DENSE k -SUBGRAPH** problem.
(*U.Feige, D.Peleg and G.Kortsarz, Algorithmica'01*)

- Now we have to choose one of these B_k .

Second step of the algorithm (III)

- If for some k^* ,

$$|E(B_{k^*})| > g, \text{ and } |E(B_i)| \leq g \text{ for all } i < k^*,$$

remove $|E(B_{k^*})| - g$ **arbitrary edges** of B_{k^*} , and replace B_{k^*} with this new graph.

Stop the search at k^* , and **output the densest graph** among $B_2, \dots, B_{k^*-1}, B_{k^*}$.

- If not, output the densest subgraph among B_2, \dots, B_{2g} .

Second step of the algorithm (III)

- If for some k^* ,

$$|E(B_{k^*})| > g, \text{ and } |E(B_i)| \leq g \text{ for all } i < k^*,$$

remove $|E(B_{k^*})| - g$ **arbitrary edges** of B_{k^*} , and replace B_{k^*} with this new graph.

Stop the search at k^* , and **output the densest graph** among $B_2, \dots, B_{k^*-1}, B_{k^*}$.

- If not, output the densest subgraph among B_2, \dots, B_{2g} .

Second step of the algorithm (III)

- If for some k^* ,

$$|E(B_{k^*})| > g, \text{ and } |E(B_i)| \leq g \text{ for all } i < k^*,$$

remove $|E(B_{k^*})| - g$ **arbitrary edges** of B_{k^*} , and replace B_{k^*} with this new graph.

Stop the search at k^* , and **output the densest graph** among $B_2, \dots, B_{k^*-1}, B_{k^*}$.

- If not, output the densest subgraph among B_2, \dots, B_{2g} .

Approximation ratio?

- *Recall:* n is the number of nodes, and g is the grooming factor.
- **Step 1:** divide the request set into subsets (according to the length), and solve each problem independently.

We loose a factor $2 \log n$

- **Step 2:** proceed greedily by removing a subgraph found using the algorithm for DENSE k -SUBGRAPH (removing edges if necessary).

We loose a factor $2 \log n$ due to the *greedy* approach,
and a factor $2n^{1/3}$ due to DENSE k -SUBGRAPH

- So, the approximation ratio of the algorithm is at most:

$$2 \log n \cdot 2 \log n \cdot 2n^{1/3} = 8n^{1/3} \log^2 n$$

- **Remark:** if the request graph is H -minor free, then the approximation ratio becomes $\mathcal{O}(\log^2 n)$.

Approximation ratio?

- *Recall*: n is the number of nodes, and g is the grooming factor.
- **Step 1**: divide the request set into subsets (according to the length), and solve each problem independently.

We loose a factor $2 \log n$

- **Step 2**: proceed greedily by removing a subgraph found using the algorithm for DENSE k -SUBGRAPH (removing edges if necessary).

We loose a factor $2 \log n$ due to the *greedy* approach,
and a factor $2n^{1/3}$ due to DENSE k -SUBGRAPH

- So, the approximation ratio of the algorithm is at most:

$$2 \log n \cdot 2 \log n \cdot 2n^{1/3} = 8n^{1/3} \log^2 n$$

- **Remark**: if the request graph is H -minor free, then the approximation ratio becomes $\mathcal{O}(\log^2 n)$.

Approximation ratio?

- *Recall:* n is the number of nodes, and g is the grooming factor.
- **Step 1:** divide the request set into subsets (according to the length), and solve each problem independently.

We loose a factor $2 \log n$

- **Step 2:** proceed greedily by removing a subgraph found using the algorithm for DENSE k -SUBGRAPH (removing edges if necessary).

We loose a factor $2 \log n$ due to the *greedy* approach,
and a factor $2n^{1/3}$ due to DENSE k -SUBGRAPH

- So, the approximation ratio of the algorithm is at most:

$$2 \log n \cdot 2 \log n \cdot 2n^{1/3} = 8n^{1/3} \log^2 n$$

- **Remark:** if the request graph is H -minor free, then the approximation ratio becomes $\mathcal{O}(\log^2 n)$.

Approximation ratio?

- *Recall:* n is the number of nodes, and g is the grooming factor.
- **Step 1:** divide the request set into subsets (according to the length), and solve each problem independently.

We loose a factor $2 \log n$

- **Step 2:** proceed greedily by removing a subgraph found using the algorithm for DENSE k -SUBGRAPH (removing edges if necessary).

We loose a factor $2 \log n$ due to the *greedy* approach,
and a factor $2n^{1/3}$ due to DENSE k -SUBGRAPH

- So, the approximation ratio of the algorithm is at most:

$$2 \log n \cdot 2 \log n \cdot 2n^{1/3} = 8n^{1/3} \log^2 n$$

- **Remark:** if the request graph is H -minor free, then the approximation ratio becomes $\mathcal{O}(\log^2 n)$.

Approximation ratio?

- *Recall:* n is the number of nodes, and g is the grooming factor.
- **Step 1:** divide the request set into subsets (according to the length), and solve each problem independently.

We loose a factor $2 \log n$

- **Step 2:** proceed greedily by removing a subgraph found using the algorithm for DENSE k -SUBGRAPH (removing edges if necessary).

We loose a factor $2 \log n$ due to the *greedy* approach,
and a factor $2n^{1/3}$ due to DENSE k -SUBGRAPH

- So, the approximation ratio of the algorithm is at most:

$$2 \log n \cdot 2 \log n \cdot 2n^{1/3} = 8n^{1/3} \log^2 n$$

- **Remark:** if the request graph is H -minor free, then the approximation ratio becomes $\mathcal{O}(\log^2 n)$.

Conclusions and further research

- We have proved that TRAFFIC GROOMING for a fixed grooming factor g does not accept to be approximated within any constant factor.
- We have exhibited a polynomial-time approximation algorithm for TRAFFIC GROOMING when both the number of nodes and the grooming factor belong to the input.
- Further research (for both PATH and RING):
 - ▶ **For fixed g :** improve the best constant-factor approximation algorithm.
So far is $\mathcal{O}(\log g)$
 - ▶ **For g belonging to the input:** improve the algorithm and/or the best existing hardness result.
So far is not APX, we conjecture that it is n^ε for some constant $\varepsilon > 0$

Conclusions and further research

- We have proved that TRAFFIC GROOMING for a fixed grooming factor g does not accept to be approximated within any constant factor.
- We have exhibited a polynomial-time approximation algorithm for TRAFFIC GROOMING when both the number of nodes and the grooming factor belong to the input.
- Further research (for both PATH and RING):
 - ▶ **For fixed g :** improve the best constant-factor approximation algorithm.
So far is $\mathcal{O}(\log g)$
 - ▶ **For g belonging to the input:** improve the algorithm and/or the best existing hardness result.
So far is not APX, we conjecture that it is n^ε for some constant $\varepsilon > 0$

Conclusions and further research

- We have proved that TRAFFIC GROOMING for a fixed grooming factor g does not accept to be approximated within any constant factor.
- We have exhibited a polynomial-time approximation algorithm for TRAFFIC GROOMING when both the number of nodes and the grooming factor belong to the input.
- Further research (for both PATH and RING):
 - ▶ **For fixed g :** improve the best constant-factor approximation algorithm.
So far is $\mathcal{O}(\log g)$
 - ▶ **For g belonging to the input:** improve the algorithm and/or the best existing hardness result.
So far is not APX, we conjecture that it is n^ε for some constant $\varepsilon > 0$

Conclusions and further research

- We have proved that TRAFFIC GROOMING for a fixed grooming factor g does not accept to be approximated within any constant factor.
- We have exhibited a polynomial-time approximation algorithm for TRAFFIC GROOMING when both the number of nodes and the grooming factor belong to the input.
- Further research (for both PATH and RING):
 - ▶ **For fixed g :** improve the best constant-factor approximation algorithm.
So far is $\mathcal{O}(\log g)$
 - ▶ **For g belonging to the input:** improve the algorithm and/or the best existing hardness result.
So far is not APX, we conjecture that it is n^ϵ for some constant $\epsilon > 0$

Conclusions and further research

- We have proved that TRAFFIC GROOMING for a fixed grooming factor g does not accept to be approximated within any constant factor.
- We have exhibited a polynomial-time approximation algorithm for TRAFFIC GROOMING when both the number of nodes and the grooming factor belong to the input.
- Further research (for both PATH and RING):
 - ▶ **For fixed g :** improve the best constant-factor approximation algorithm.
So far is $\mathcal{O}(\log g)$
 - ▶ **For g belonging to the input:** improve the algorithm and/or the best existing hardness result.
So far is not APX, we conjecture that it is n^ϵ for some constant $\epsilon > 0$

Thanks!