

Graph modification of bounded size to minor-closed
classes as fast as vertex deletion

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ESA 2025, Warsaw, Poland

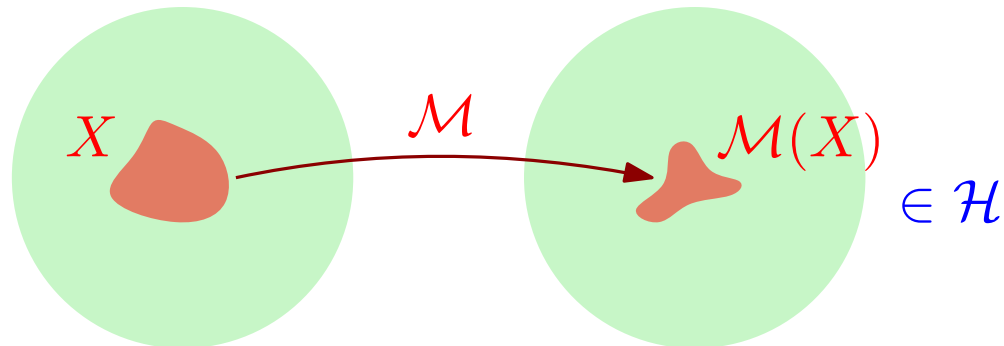


Modification \mathcal{M} , graph class \mathcal{H}

Graph modification problem:

Input: Graph G , integer k .

Question: Can we do $\leq k$ modifications to G s.t. the modified graph belongs to the target class \mathcal{H} ?



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Modification	+	Target class	=	Problem
vertex deletion		edgeless graphs		VERTEX COVER
		forests		FEEDBACK VERTEX SET
		bipartite graphs		ODD CYCLE TRANSVERSAL
edge addition + deletion		union of cliques		CLUSTER EDITING
edge contraction		planar graphs		CONTRACTION TO PLANAR

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Highly prolific field:

299 papers mentionned just for edge-modifications in

[A survey of parameterized algorithms and the complexity of edge-modification, Crespelle, Drange, Fomin, Golovach, 2023]

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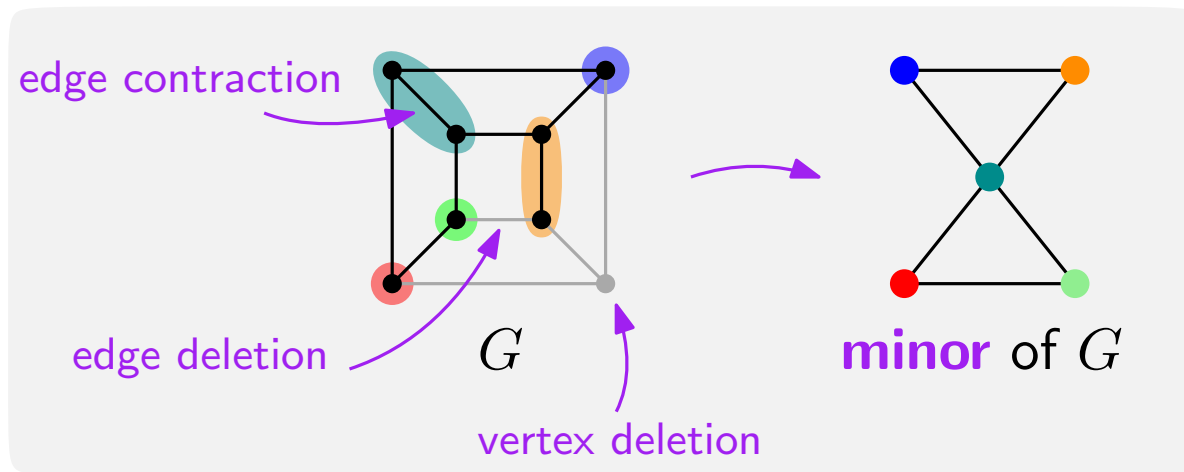
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Holy grail:

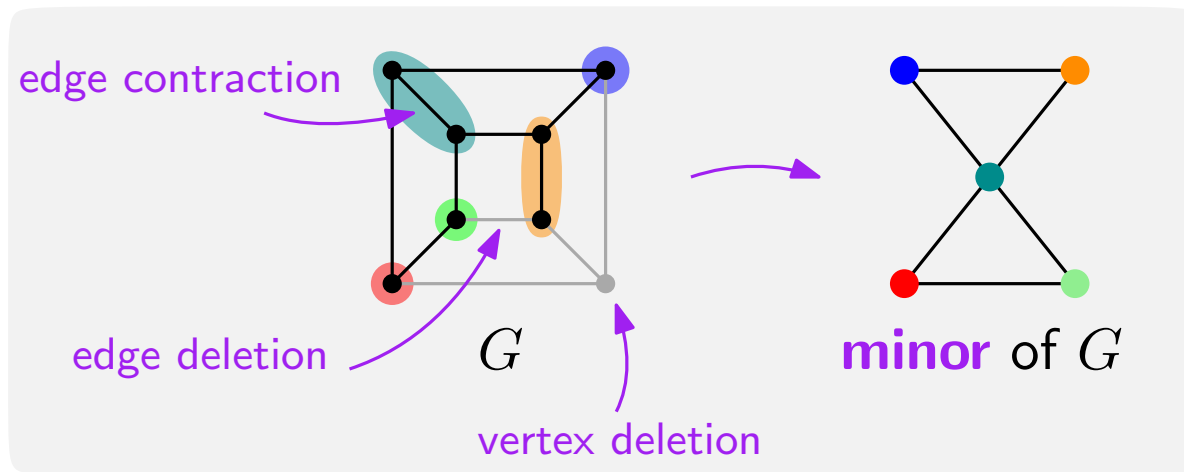
Instead of solving modification problems one by one, can we provide a meta-algorithm solving as many problems as possible at once?

Meta-algorithm **on** target classes

Meta-algorithm on target classes

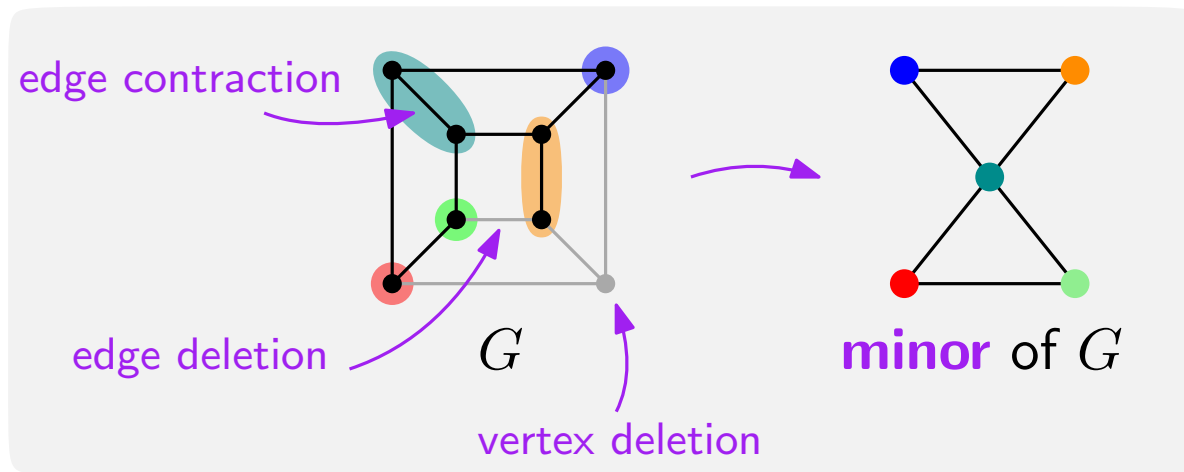


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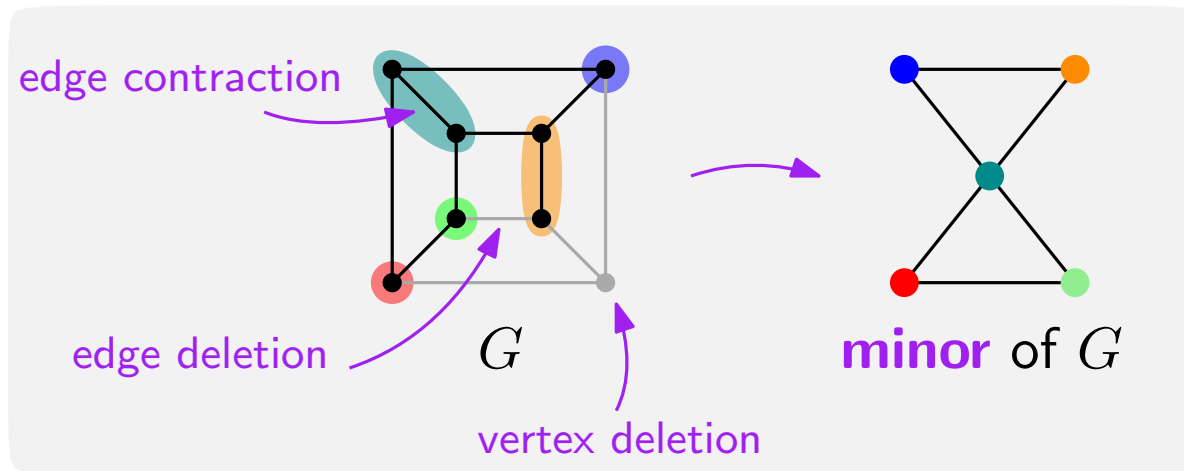
Minor-closed graph class \mathcal{H}

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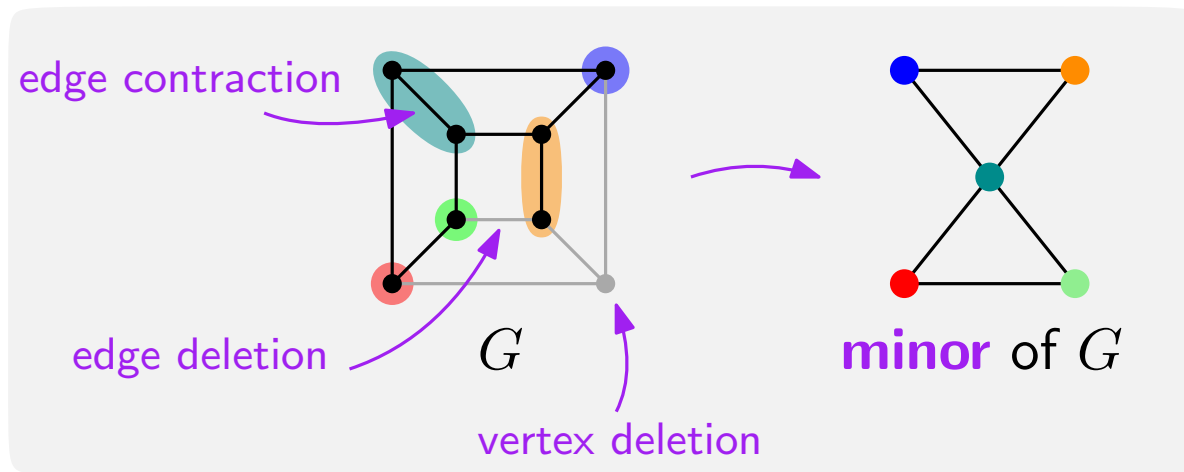
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Meta-algorithm on target classes



Minor-closed graph class \mathcal{H} ← If $G \in \mathcal{H}$, then minors of G in \mathcal{H} .
edgeless graphs, forests,
planar graphs, graphs
embeddable on a surface, ...

Meta-algorithm on target classes

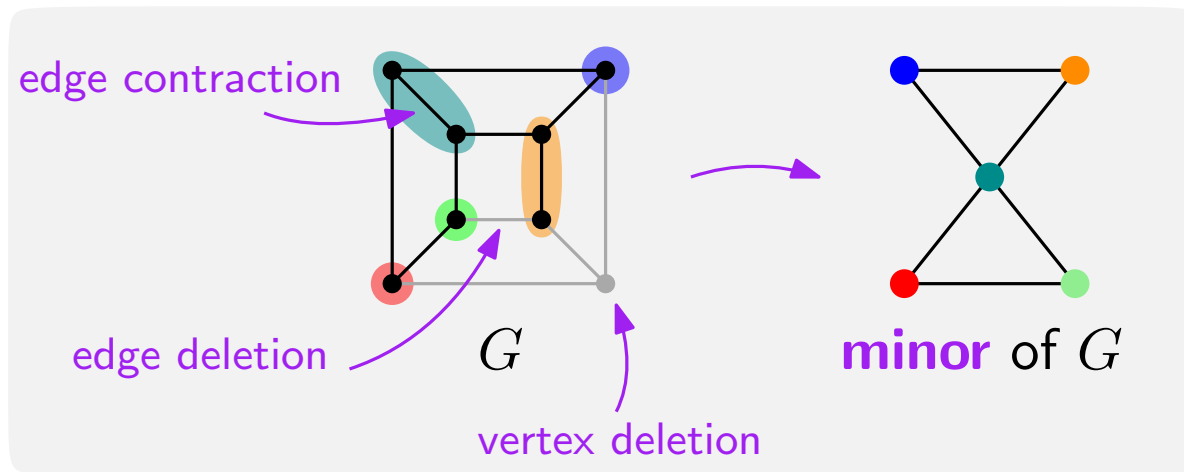


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[Robertson, Seymour, 2004]

\mathcal{H} has a finite number of minor-obstructions.

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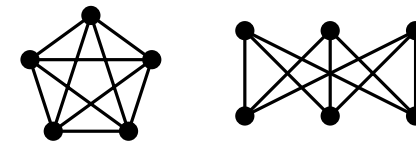


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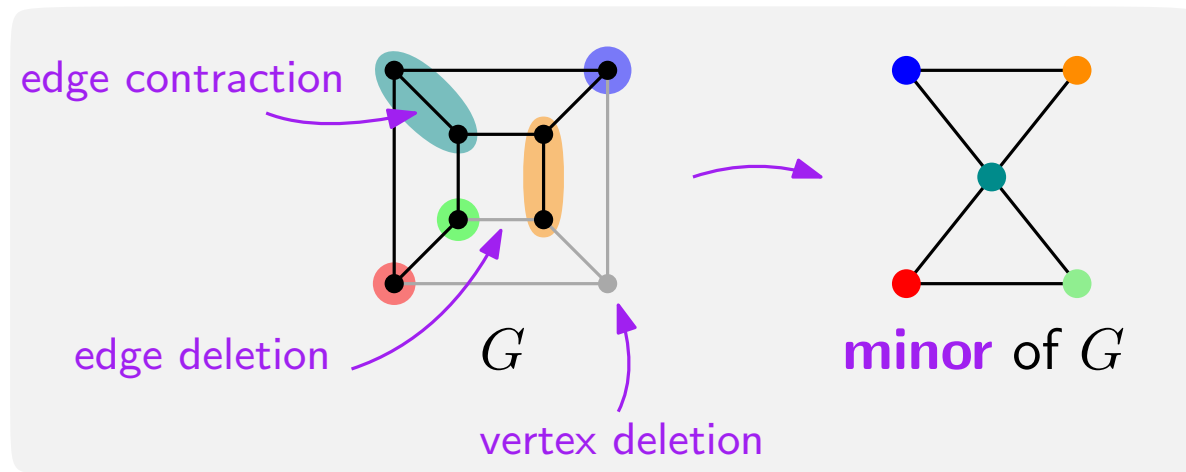
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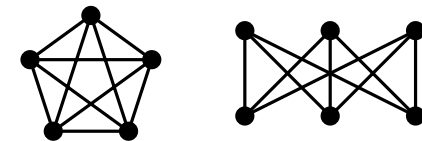


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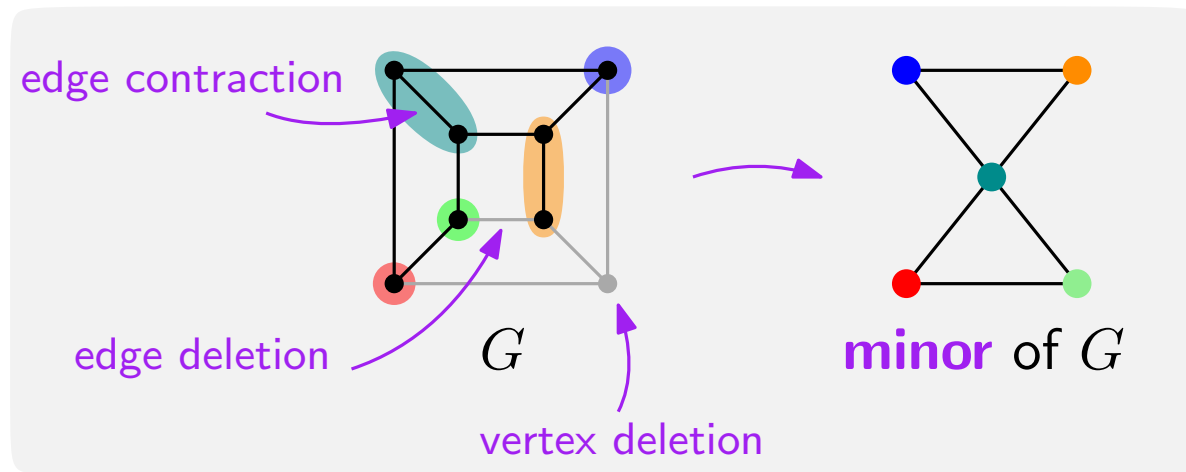
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[Korhonen, Pilipczuk, Stamoulis, 2024]

Checking whether H is a minor of G can be done in time $\mathcal{O}_H(n^{1+o(1)})$.

Meta-algorithm on target classes

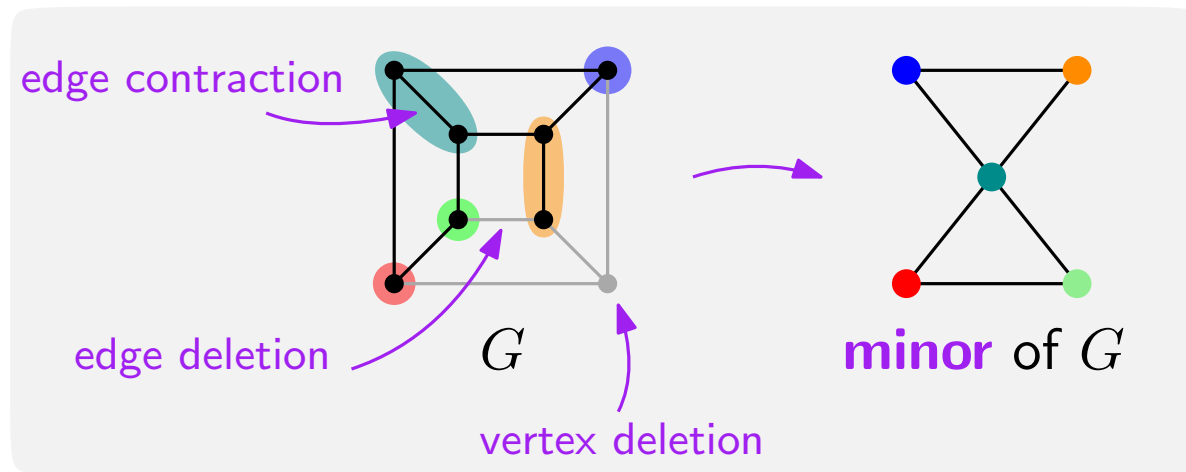


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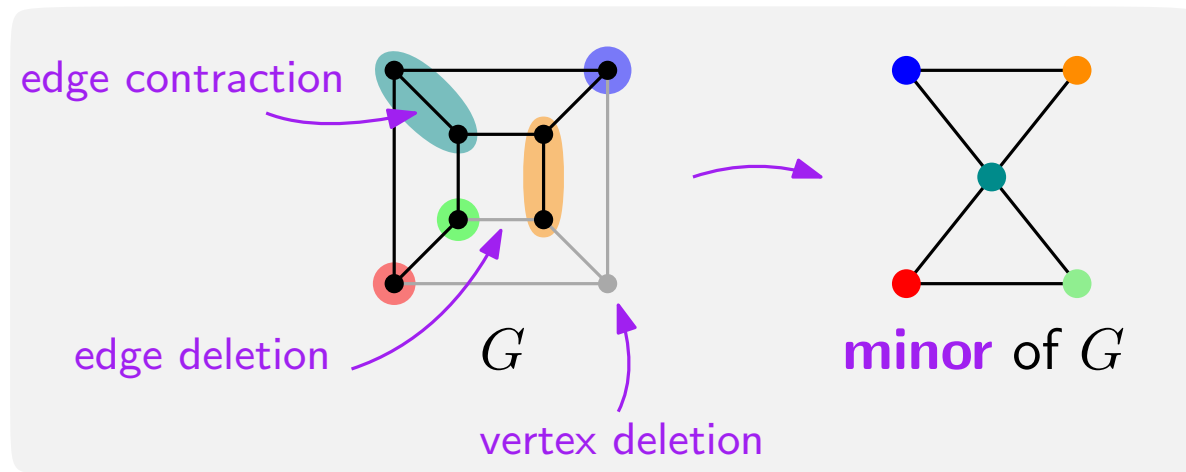
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→ VERTEX / EDGE DELETION TO \mathcal{H} in time $f_{\mathcal{H}}(k) \cdot n^{1+o(1)}$.

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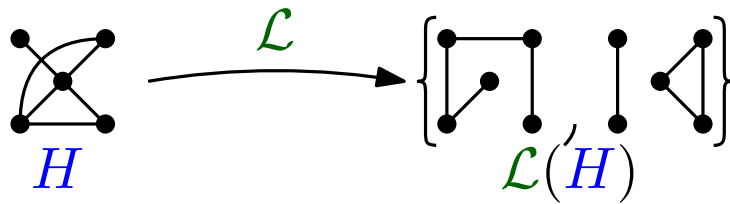
\rightarrow VERTEX / EDGE DELETION TO \mathcal{H} in time $f_{\mathcal{H}}(k) \cdot n^{1+o(1)}$.

because yes-instances of k -VERTEX / EDGE DELETION TO \mathcal{H} are minor-closed.

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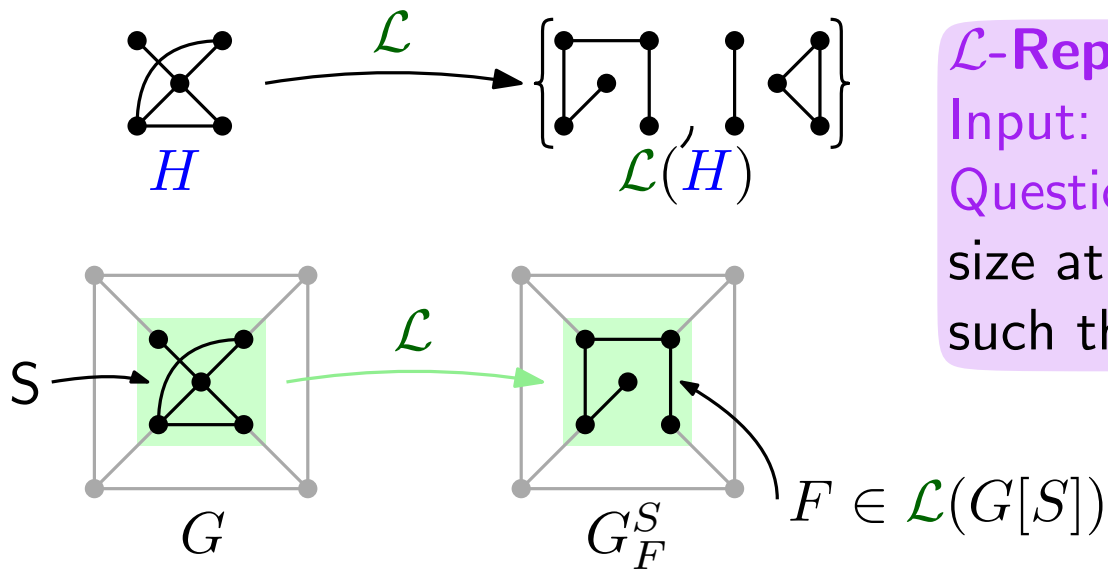
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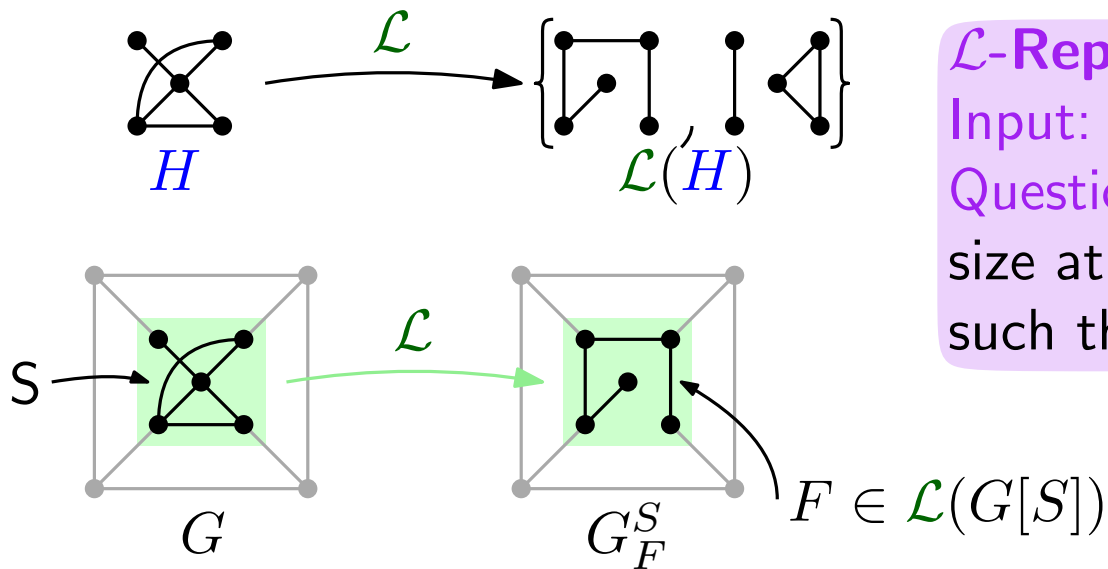
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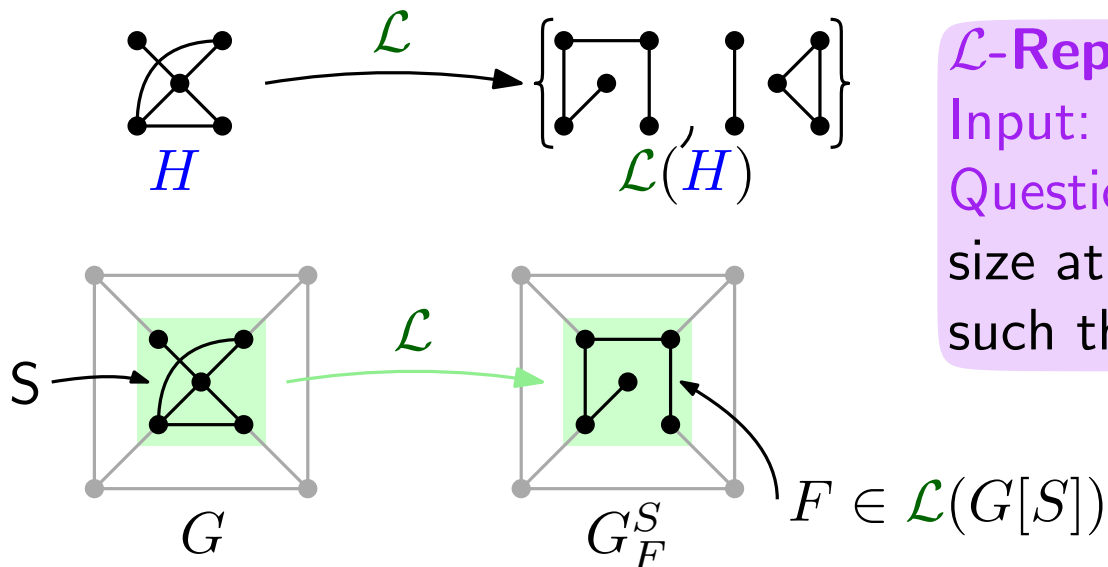
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EDGE DELETION TO PLANAR

PLANAR COMPLETION TO A SUBGRAPH

MATCHING DELETION TO PLANAR

PLANAR SUBGRAPH ISOMORPHISM

Meta-algorithm on modifications and target classes

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[S., Stamoulis, Thilikos, 2025]

Given a formula $\varphi \in \text{CMSO/tw} + \text{dp}$, and a graph G that is H -minor-free, one can check whether $G \models \varphi$ in time $f(|\varphi|, |H|) \cdot n^2$.

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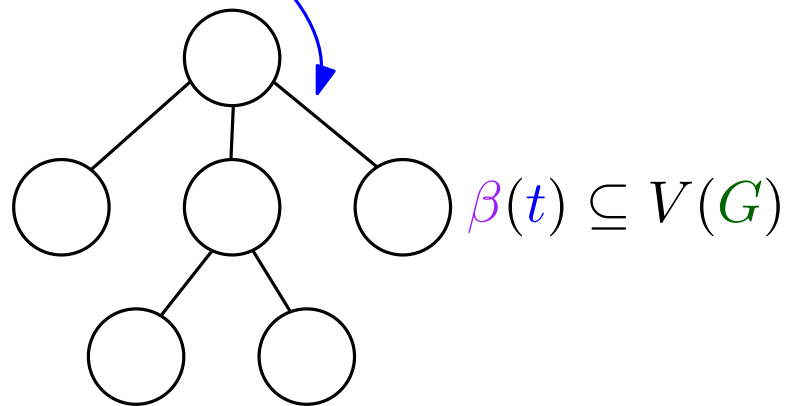
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Tree decomposition (T, β) of G



$$\bigcup_{t \in V(T)} \beta(t) = V(G)$$

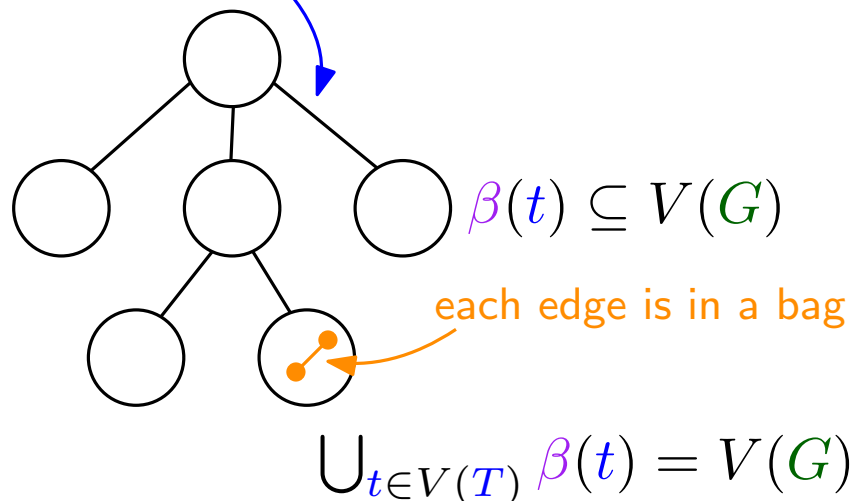
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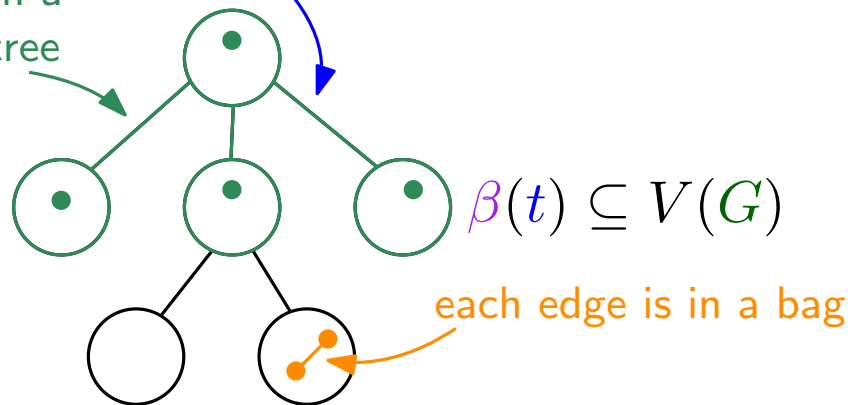
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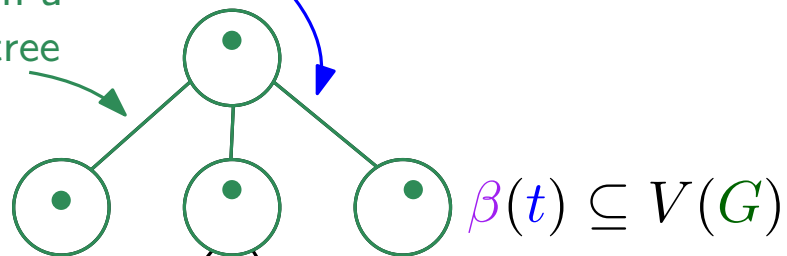
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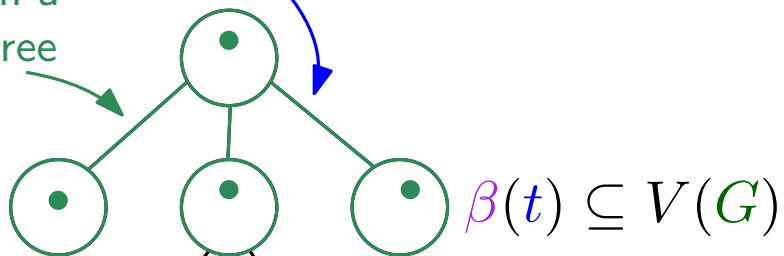
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$\text{tw} \leq k$:



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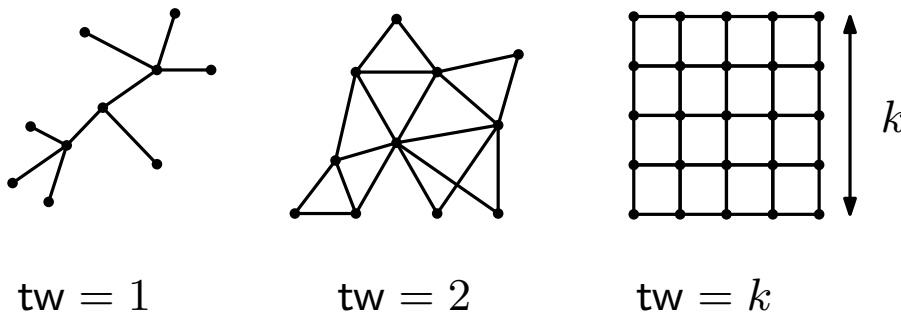
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$f(k)$ \rightarrow ?

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Natural goal: efficient parametric dependence on k , for particular (still relevant) cases of the modification operation.

\mathcal{H} minor-closed

[Baste, S., Thilikos, 2018-2020]

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VERTEX DELETION TO \mathcal{H} in time
 $2^{O_{\mathcal{H}}(\text{tw} \log \text{tw})} \cdot n$

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The result of this paper

"MODIFICATION OF BOUNDED SIZE TO \mathcal{H} " in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$

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\mathcal{L} -REPLACEMENT TO \mathcal{H} in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$

Our result can be seen as a **rare example** of an **efficient meta-algorithm** for graph modification problems to minor-closed graph classes.

Our result: if \mathcal{H} minor-closed

One can solve \mathcal{L} -REPLACEMENT TO \mathcal{H} in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$.

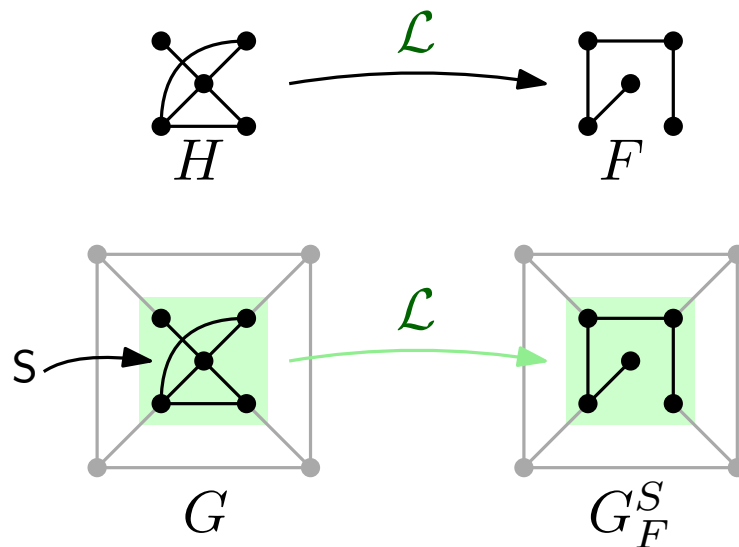
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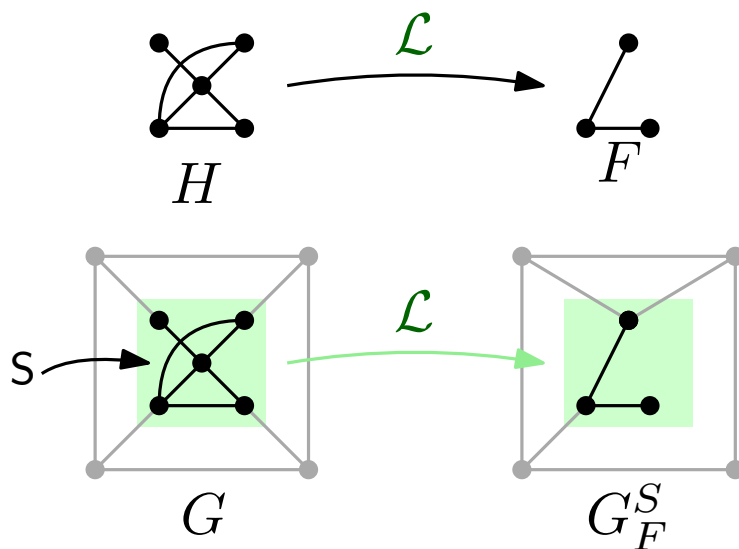
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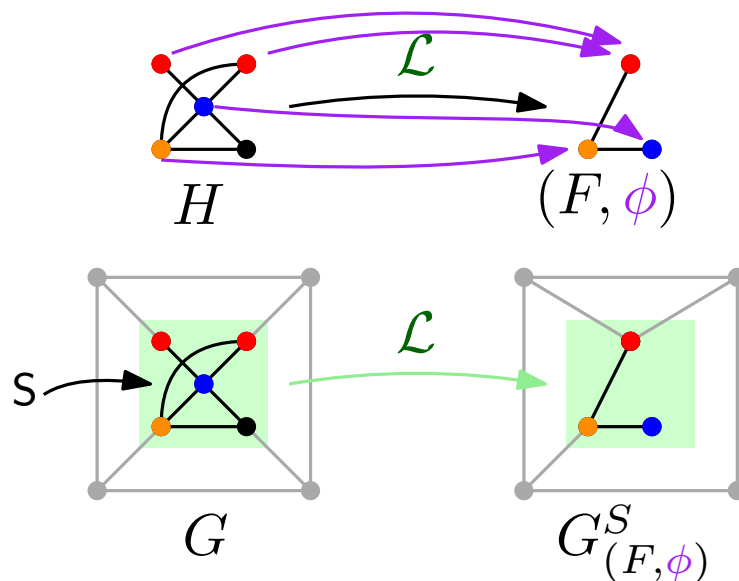
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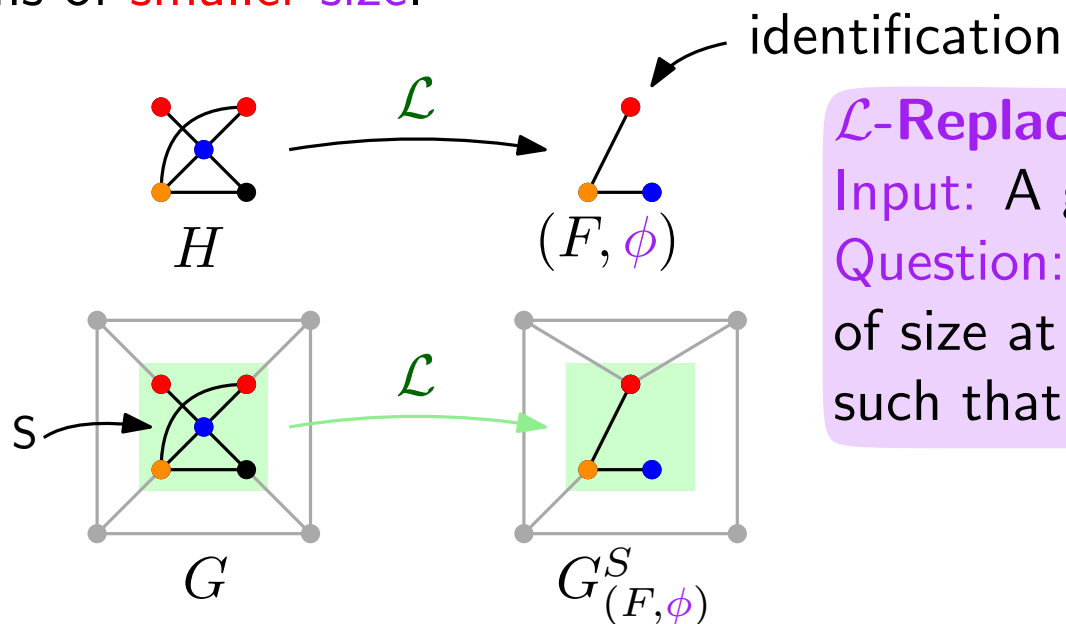
Our result: if \mathcal{H} minor-closed

One can solve \mathcal{L} -REPLACEMENT TO \mathcal{H} in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$.

[Fomin, Golovach, Thilikos, 2019]

\mathcal{L} -REPLACEMENT TO PLANAR in time $f(k) \cdot n^2$.

R-action: function \mathcal{L} mapping each graph H to a collection $\mathcal{L}(H)$ of graphs of smaller size.



\mathcal{L} -Replacement to \mathcal{H}

Input: A graph G , $k \in \mathbb{N}$.

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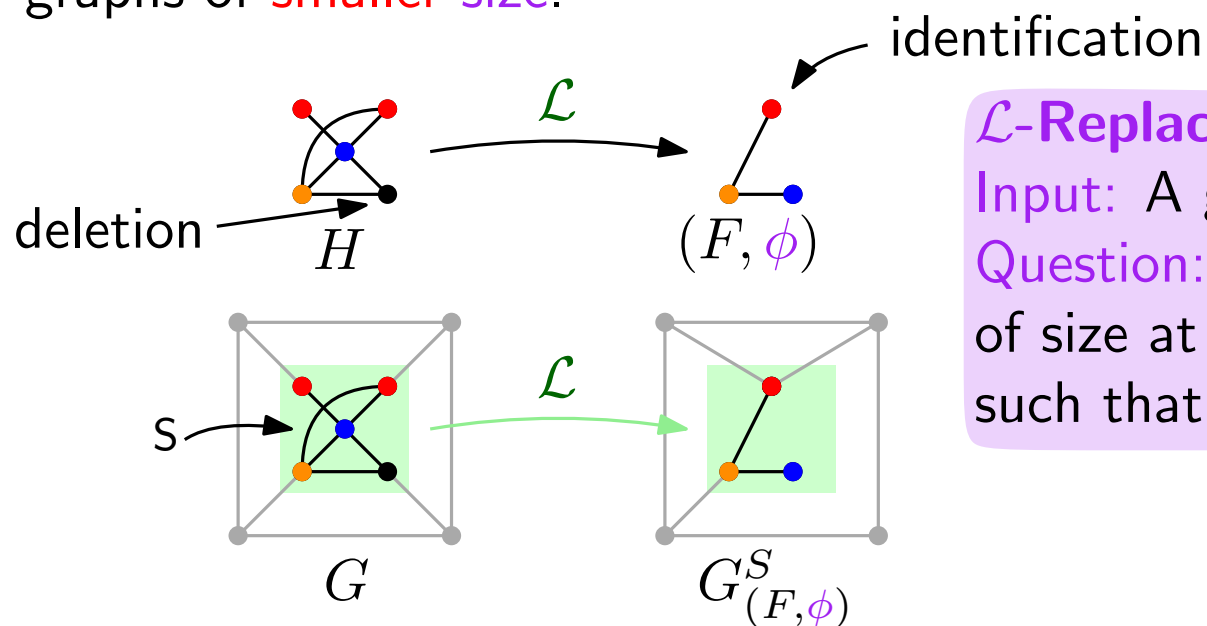
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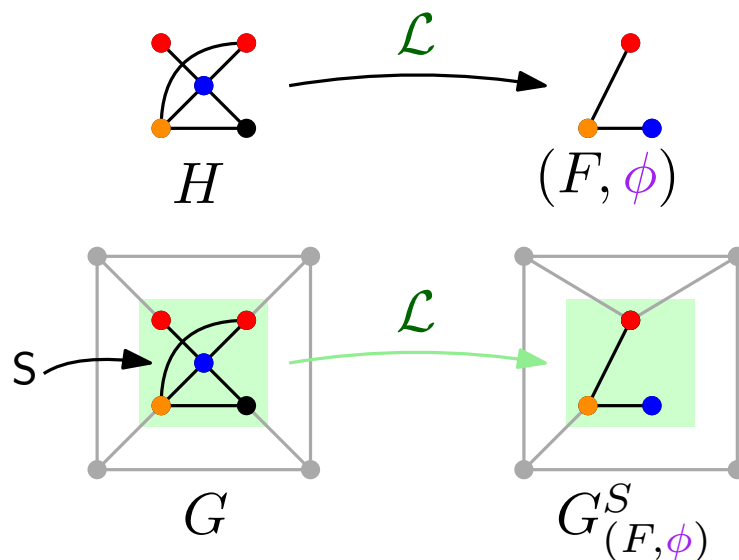
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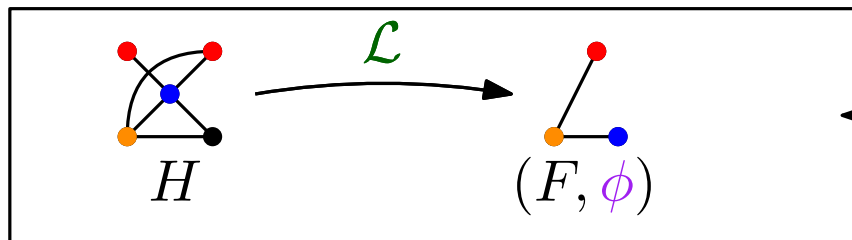
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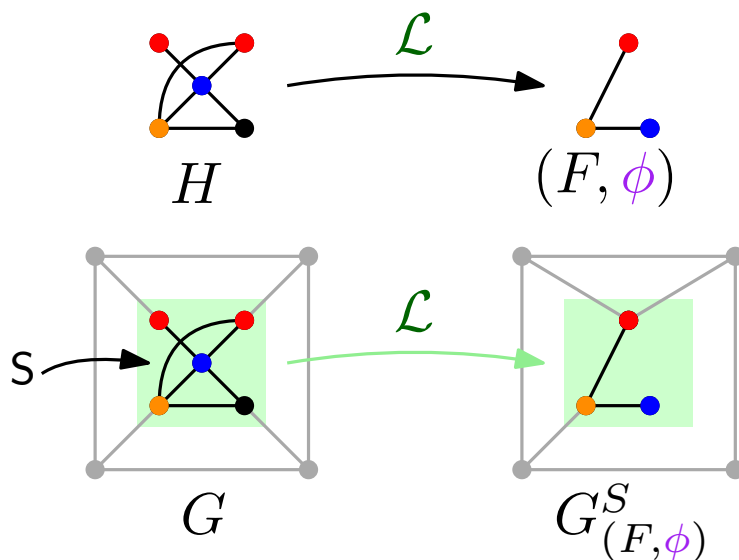
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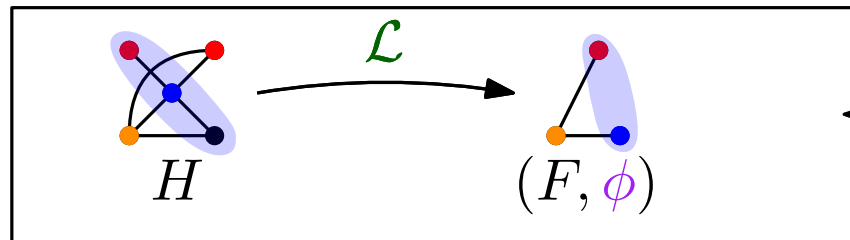
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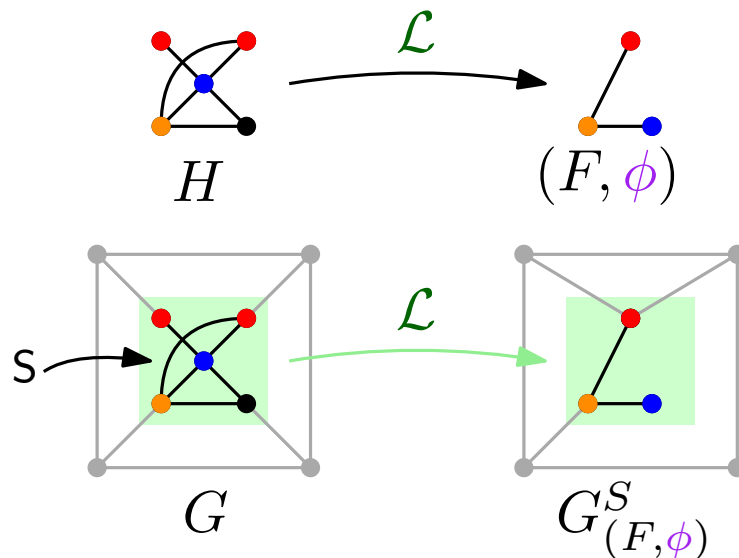
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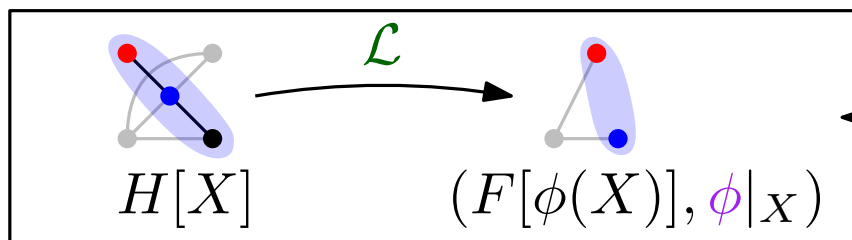
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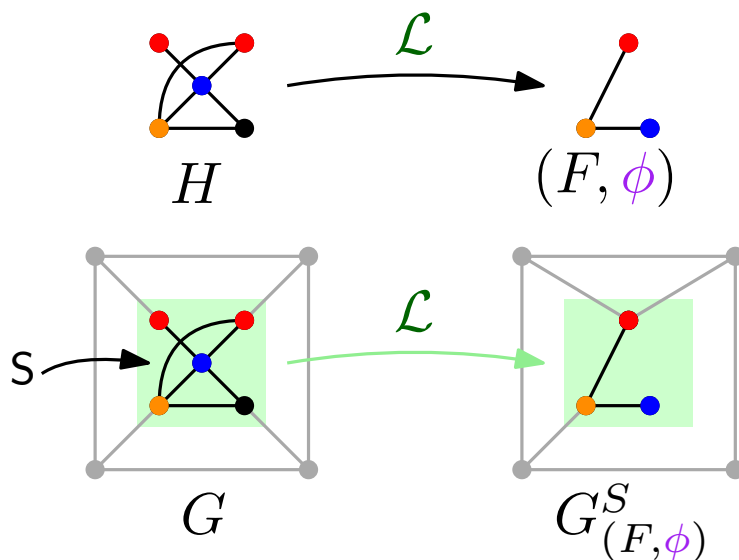
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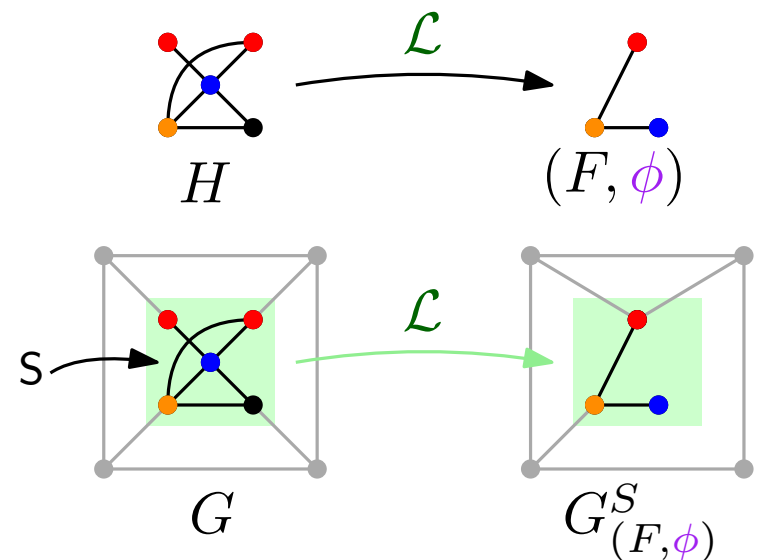
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\mathcal{L} hereditary:

- VERTEX DELETION TO \mathcal{H}
- EDGE DELETION TO \mathcal{H}
- EDGE CONTRACTION TO \mathcal{H}
- SUBGRAPH COMPLEMENTATION TO \mathcal{H}
- VERTEX IDENTIFICATION TO \mathcal{H}
- MATCHING CONTRACTION TO \mathcal{H}
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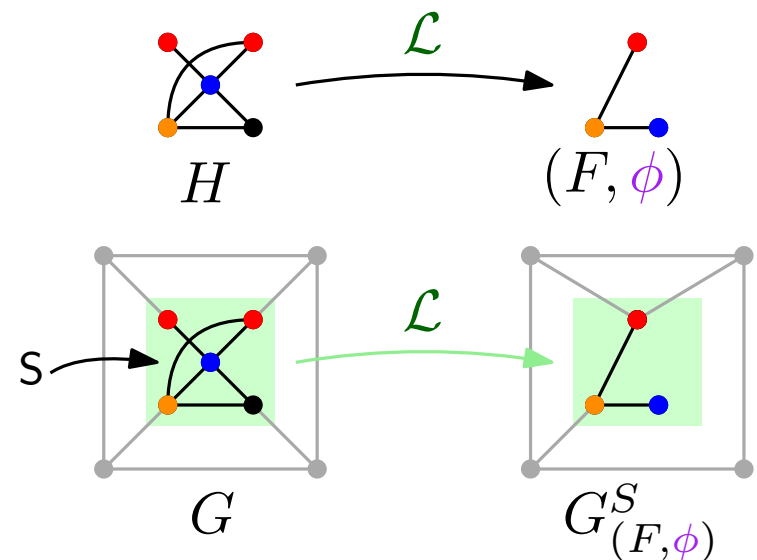
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\mathcal{L} non-hereditary:

- deleting exactly k vertices/edges
- PLANAR SUBGRAPH ISOMORPHISM



The Irrelevant Vertex technique

The Irrelevant Vertex technique ← originates from [Robertson, Seymour, 1995]

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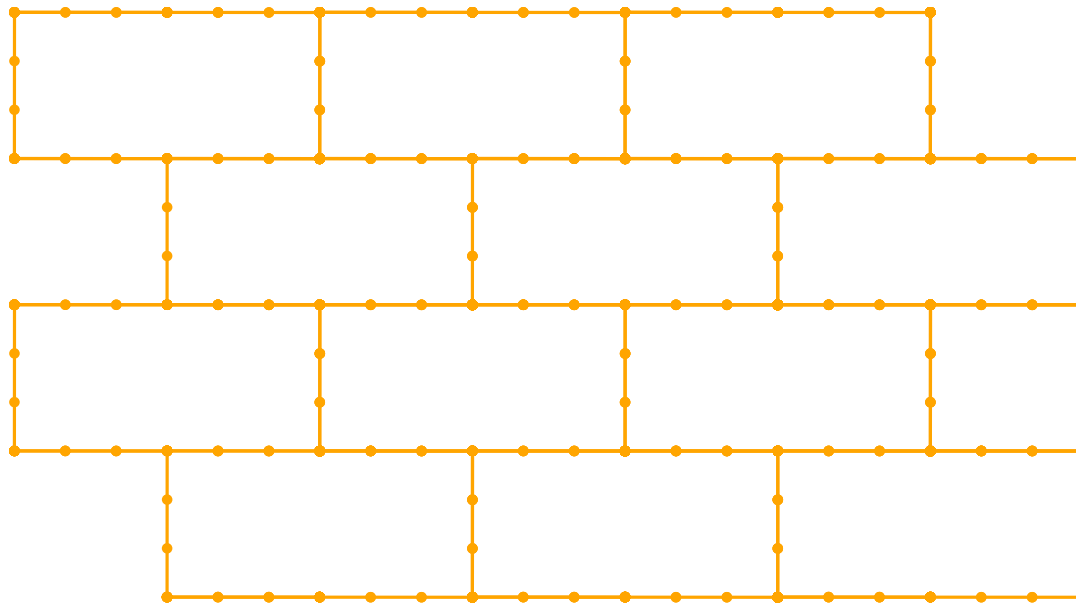
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A wall:



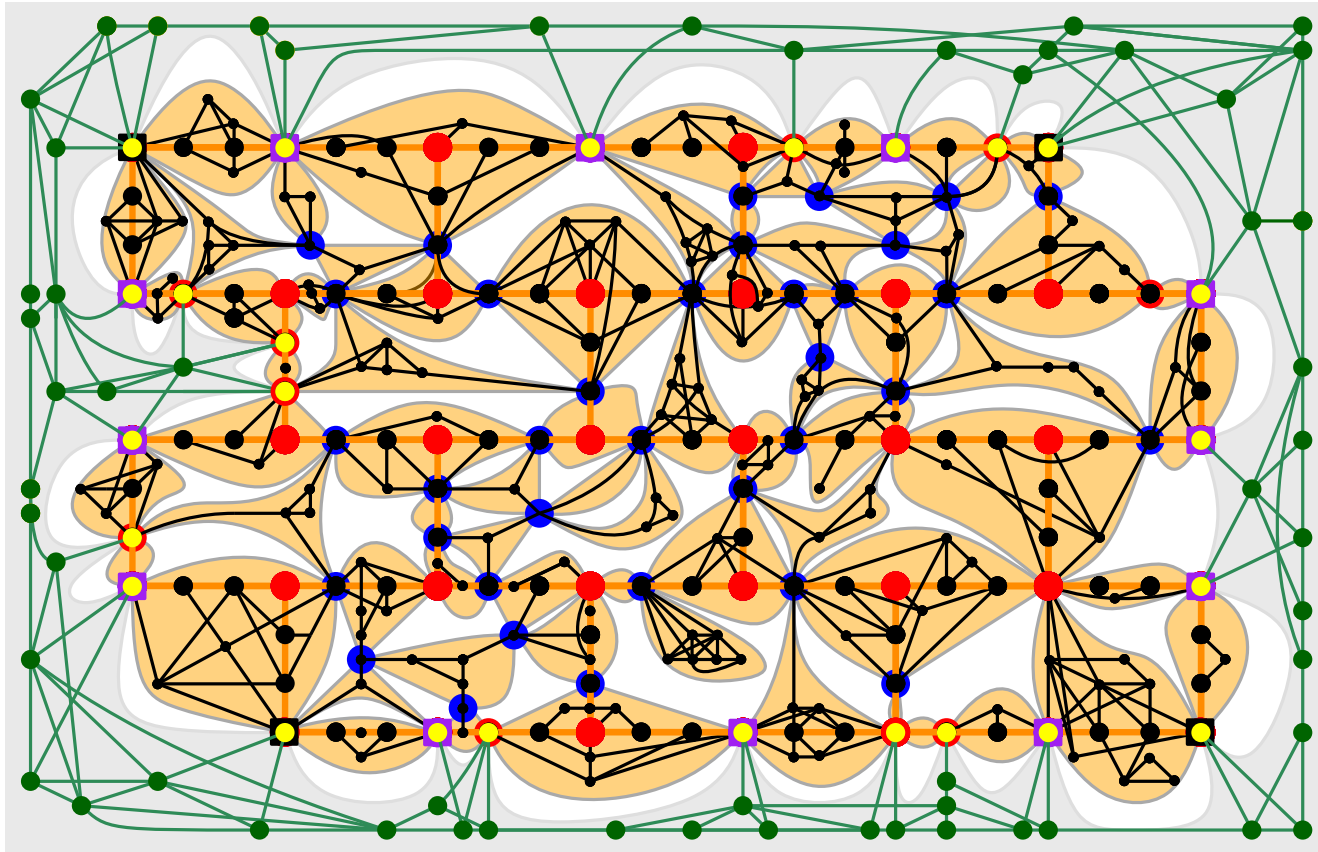
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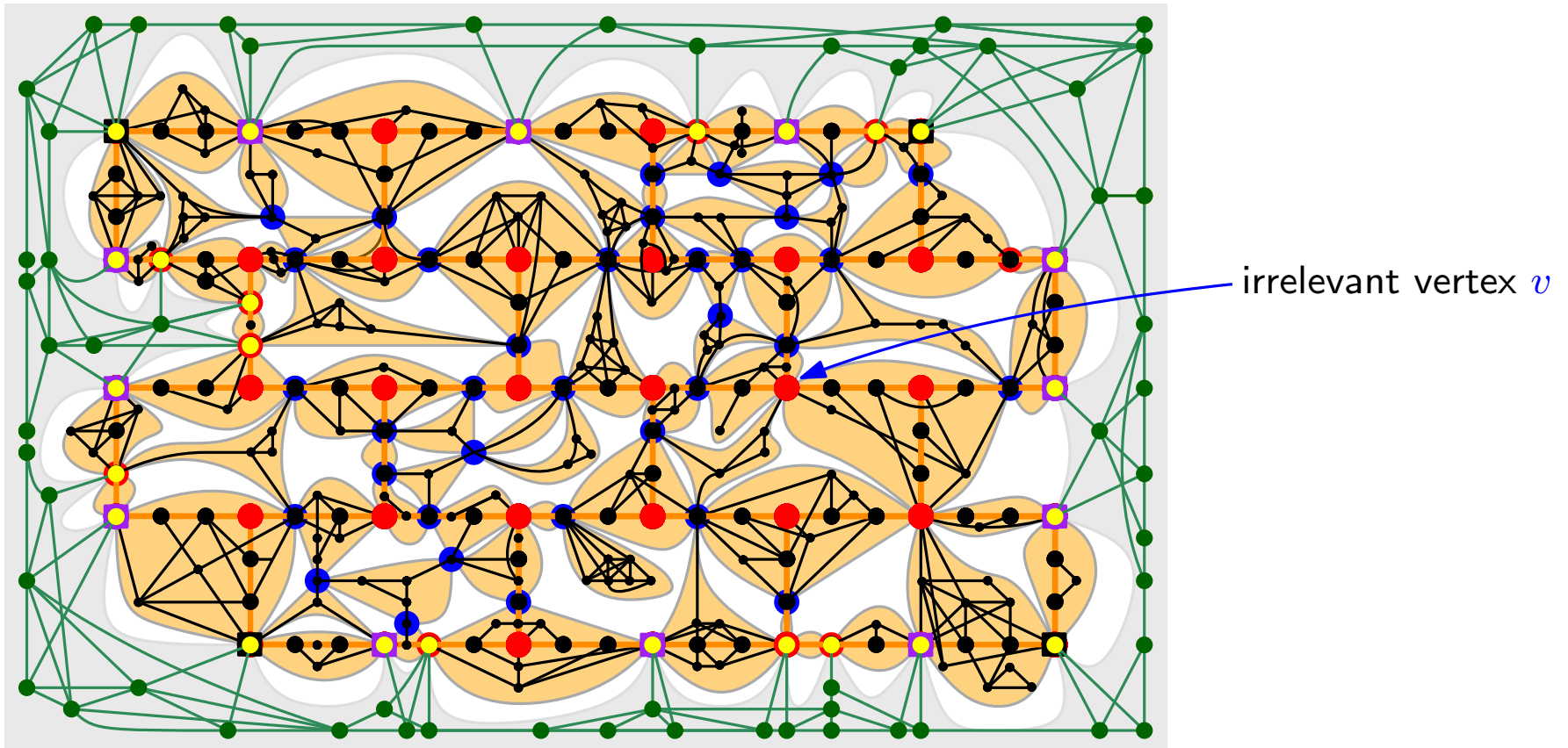
A **flat** wall:



The Irrelevant Vertex technique

Given a graph G and a big enough flat wall W in G , one can find a vertex v such that (G, k) and $(G - v, k)$ are equivalent instances of the problem.

A flat wall:

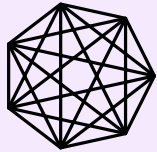


The Flat Wall theorem

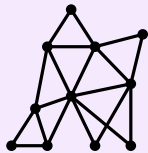
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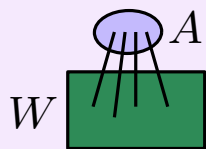
- a K_t -minor in G ,



- a tree decomposition of G of width $f(t) \cdot r$, or



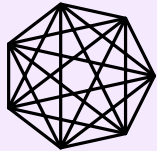
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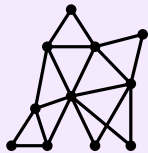
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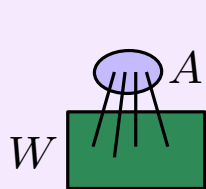
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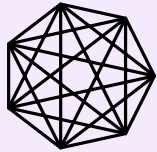


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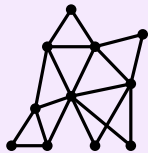
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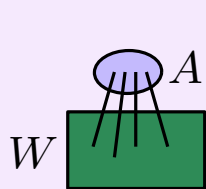
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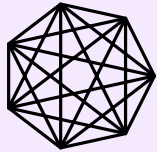
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Recurse on $(G - v, k)$

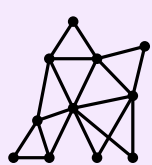
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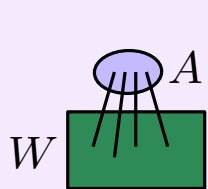


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Courcelle's theorem: Every problem expressible in CMSO logic is solvable in time $f(\text{tw}) \cdot n$.

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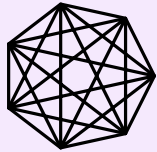
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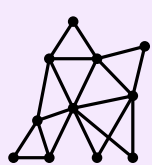
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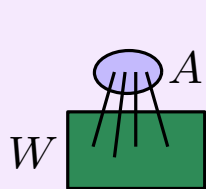


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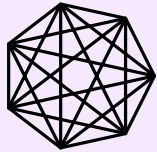
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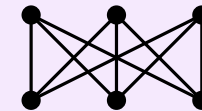
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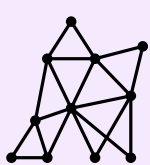
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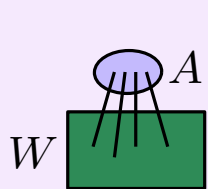
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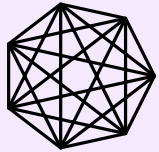
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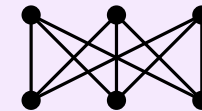
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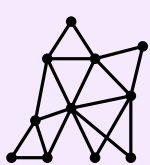


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$$t = s_{\mathcal{H}} + k$$



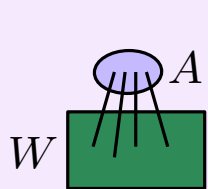
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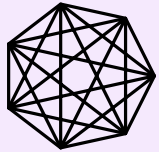
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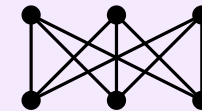
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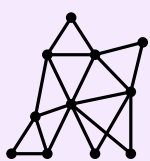


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$t = s_{\mathcal{H}} + k \longrightarrow \text{no-instance}$

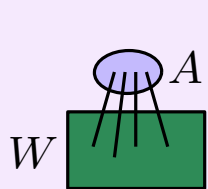
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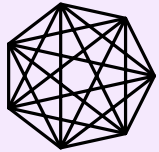
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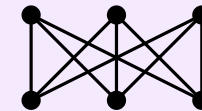
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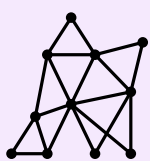
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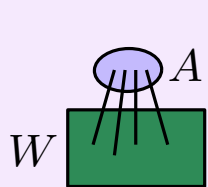
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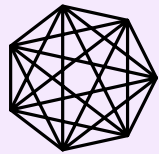
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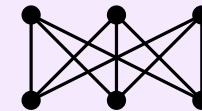
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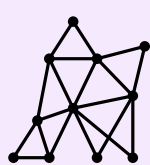
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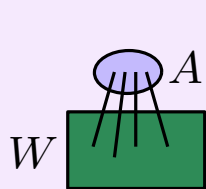
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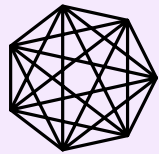
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bad!

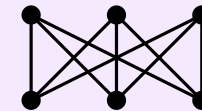
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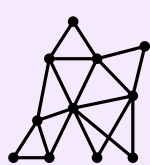
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$t = s_{\mathcal{H}} + k \longrightarrow \text{no-instance}$

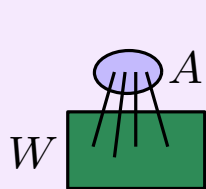
in time $f_{\mathcal{H}}(k) \cdot n$

- a tree decomposition of G of width $f(t) \cdot r$, or



Courcelle's theorem: Every problem expressible in CMSO logic is solvable in time $f(\text{tw}) \cdot n$.

- a set $A \subseteq V(G)$ of size at most $f(t)$ and a flat wall W of $G - A$ of height r .



Irrelevant Vertex technique: find an irrelevant vertex v , or branch to identify some vertex v that is in the solution.

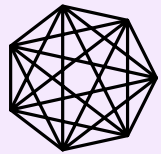
Recurse on $(G - v, k) \longrightarrow$ in time $2^{f_{\mathcal{H}}(k)} \cdot n$

bad!

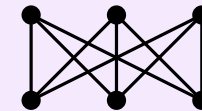
The Flat Wall theorem

Given a graph G and integers t and r , one can find either:

- a K_t -minor in G ,



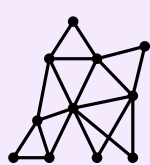
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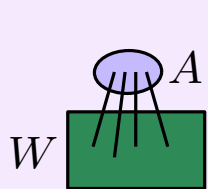
- a tree decomposition of G of width $f(t) \cdot r$, or

Conclude



\mathcal{L} -REPLACEMENT TO \mathcal{H} in time $2^{O_{\mathcal{H}}(k^2 + (k+tw) \log(k+tw))} \cdot n$

- a set $A \subseteq V(G)$ of size at most $f(t)$ and a flat wall W of $G - A$ of height r .



Irrelevant Vertex technique: find an irrelevant vertex v , or branch to identify some vertex v that is in the solution.

Recurse on $(G - v, k) \longrightarrow$ in time $2^{f_{\mathcal{H}}(k)} \cdot n$

bad!

\mathcal{H} minor-closed

One can solve \mathcal{L} -REPLACEMENT TO \mathcal{H} in time $2^{\text{poly}_{\mathcal{H}}(k)} \cdot n^2$ for \mathcal{L} hereditary.

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?



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$$k^{2^{2^{s_{\mathcal{H}}}} 24} <$$


\mathcal{H} minor-closed

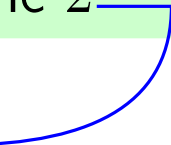
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$\mathcal{H} = \mathcal{P}$ planar: $s_{\mathcal{H}} = 6 \rightarrow$ already very big!

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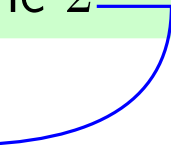
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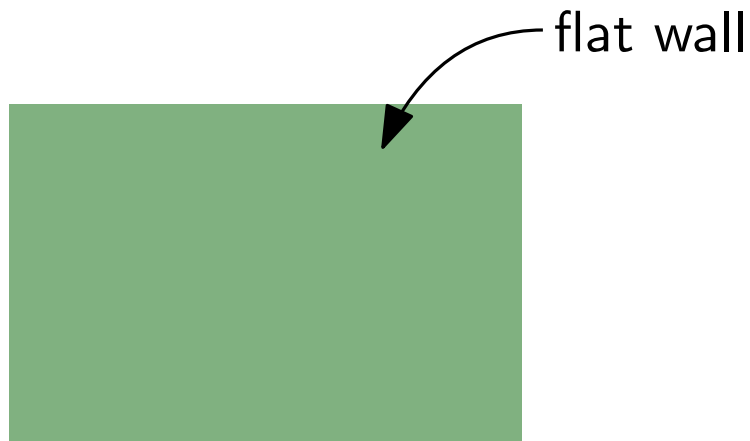
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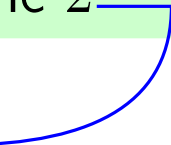
Irrelevant vertex technique

General case:



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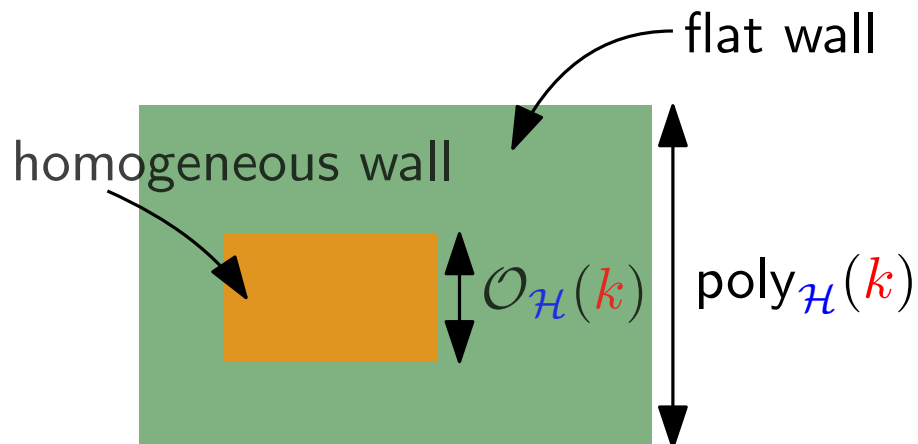
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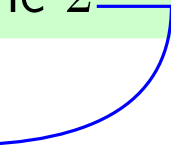
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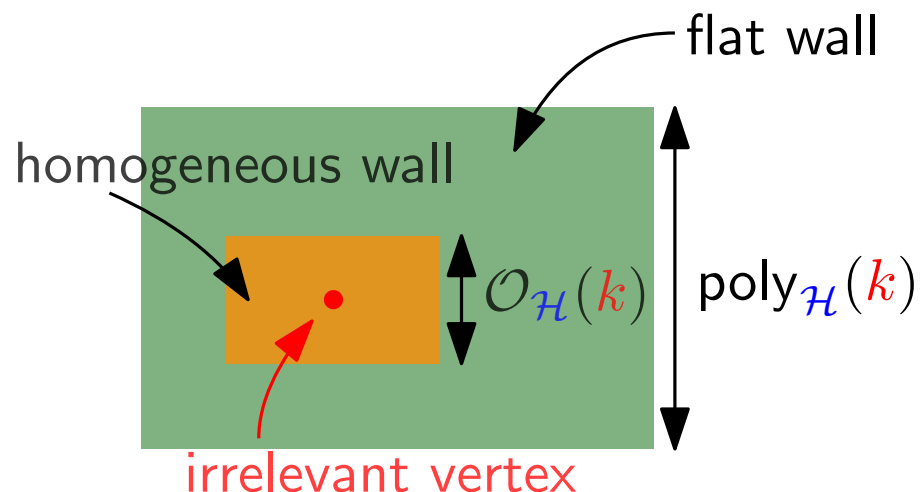
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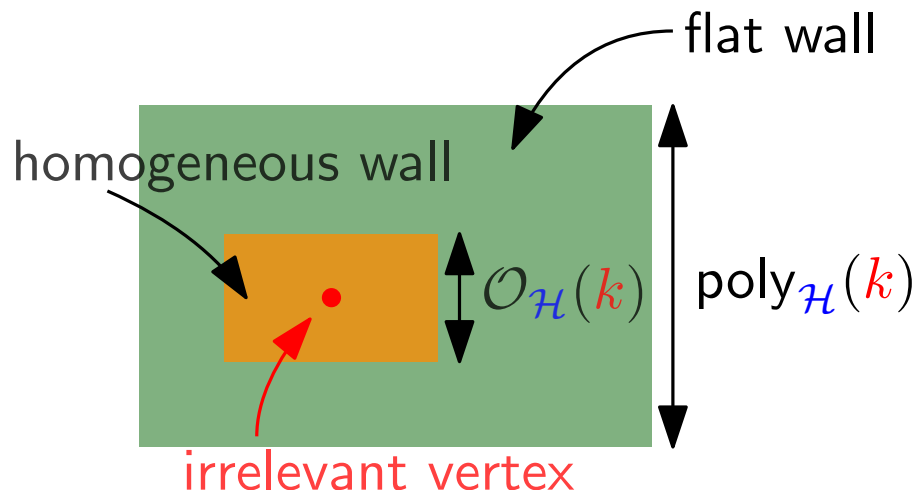
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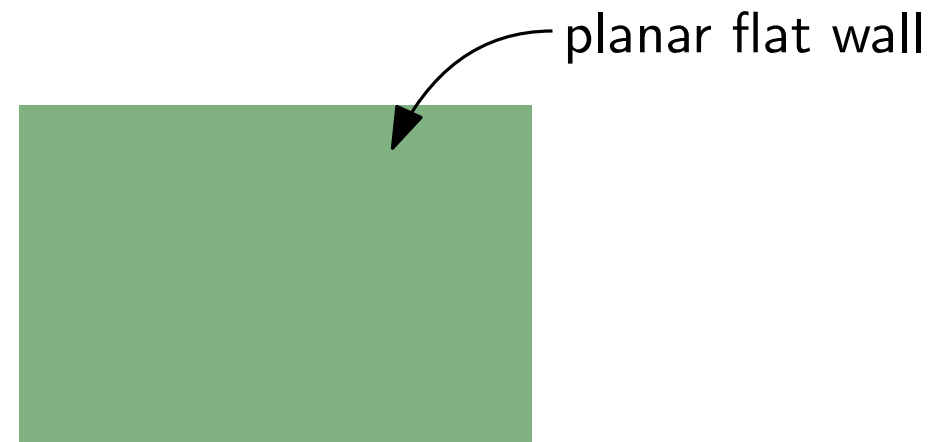
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Irrelevant vertex technique

General case:



Planar case:



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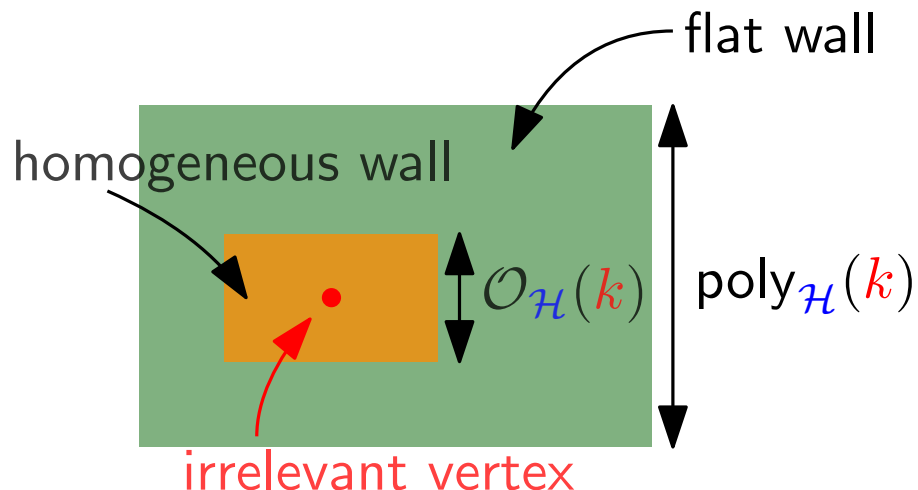
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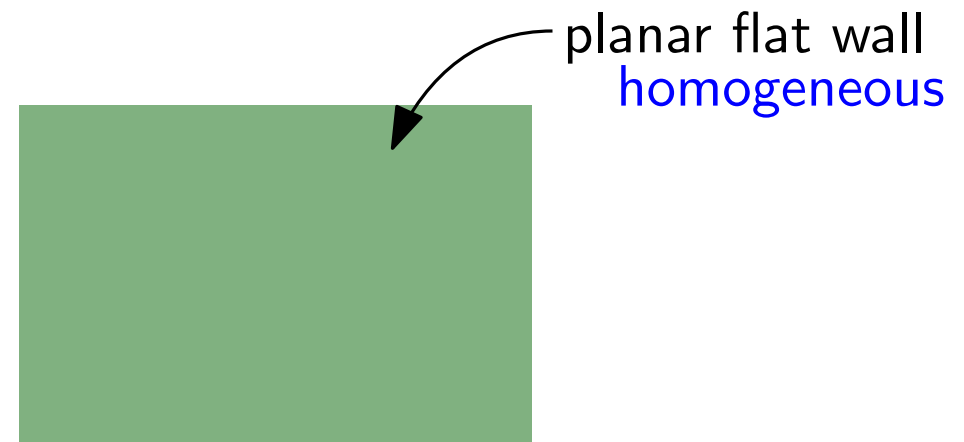
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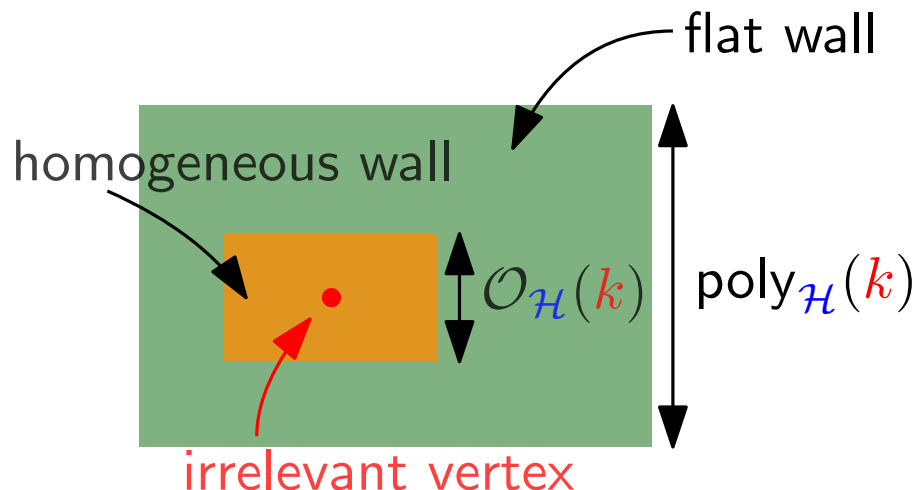
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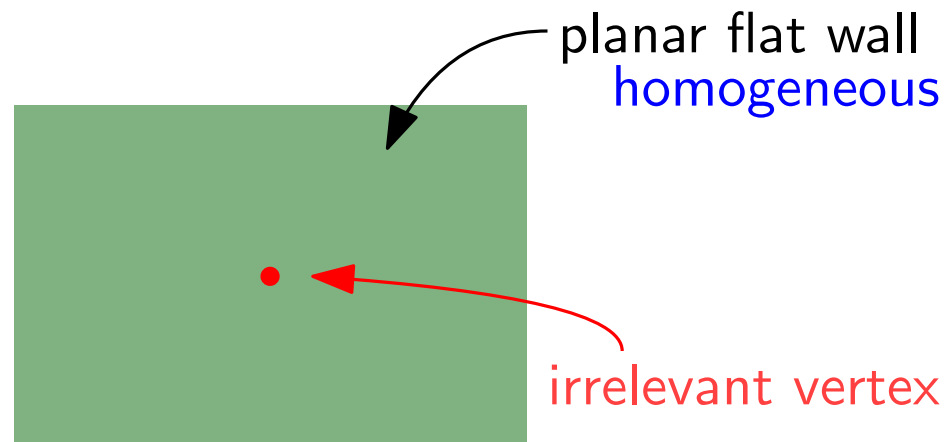
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General case:

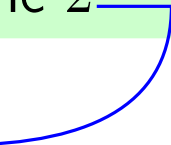


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works also for the class of graphs embeddable on a surface Σ

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Can we improve?


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k : bound on the size of the vertex set involved in the modification

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treewidth instead?

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ELIMINATION DISTANCE TO \mathcal{H}
 \mathcal{H} -TREEWIDTH

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ELIMINATION DISTANCE TO \mathcal{H}
 \mathcal{H} -TREEWIDTH

Thanks!