Hitting minors on bounded treewidth graphs

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[arXiv 1704.07284]

Treewidth behaves very well algorithmically

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Monadic Second Order Logic (MSOL):

Graph logic that allows quantification over sets of vertices and edges.

Example: DomSet(S) : [$\forall v \in V(G) \setminus S, \exists u \in S : \{u, v\} \in E(G)$]

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Theorem (Courcelle, 1990)

Every problem expressible in MSOL can be solved in time $f(tw) \cdot n$ on graphs on n vertices and treewidth at most tw.

In parameterized complexity: FPT parameterized by treewidth.

Examples: VERTEX COVER, DOMINATING SET, HAMILTONIAN CYCLE, CLIQUE, INDEPENDENT SET, *k*-COLORING for fixed *k*, ...

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Major goal find the smallest possible function f(tw).

This is a very active area in parameterized complexity.

Remark: Algorithms parameterized by treewidth appear very often as a "black box" in all kinds of parameterized algorithms. Typically, FPT algorithms parameterized by treewidth are based on dynamic programming (DP) over a tree decomposition.

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But for the so-called connectivity problems, like LONGEST PATH or STEINER TREE, the "natural" DP algorithms provide only time

 $2^{\mathcal{O}(\mathsf{tw} \cdot \mathsf{log} \, \mathsf{tw})} \cdot n^{\mathcal{O}(1)}$.

(Single-exponential algorithms on sparse graphs)

On topologically structured graphs (planar, surfaces, minor-free), it is possible to solve connectivity problems in time $2^{\mathcal{O}(tw)} \cdot n^{\mathcal{O}(1)}$:

- Planar graphs:
- Graphs on surfaces:
- Minor-free graphs:

[Dorn, Penninkx, Bodlaender, Fomin. 2005]

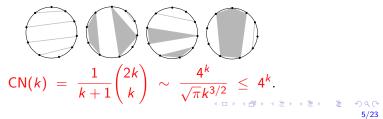
[Dorn, Fomin, Thilikos. 2006]

[Rué, S., Thilikos. 2010]

[Dorn, Fomin, Thilikos. 2008]

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Main idea special type of decomposition with nice topological properties: partial solutions ↔ non-crossing partitions



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This was false!!

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Deterministic algorithms with algebraic tricks: [Bodlaender, Cygan, Kratsch, Nederlof. 2013]

Representative sets in matroids:

[Fomin, Lokshtanov, Saurabh. 2014]

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No!

CYCLE PACKING: find the maximum number of vertex-disjoint cycles.

An algorithm in time $2^{\mathcal{O}(\text{tw} \cdot \log \text{tw})} \cdot n^{\mathcal{O}(1)}$ is optimal under the ETH.

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ETH: The 3-SAT problem on *n* variables cannot be solved in time $2^{o(n)}$ [Impagliazzo, Paturi. 1999] Do all connectivity problems admit single-exponential algorithms (on general graphs) parameterized by treewidth?

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There are other examples of such problems...

The $\mathcal{F}\text{-}\mathrm{M}\text{-}\mathrm{Deletion}$ problem

Let \mathcal{F} be a fixed finite collection of graphs.

$\mathcal{F} ext{-}\mathrm{M} ext{-}\mathrm{Deletion}$

Input:A graph G and an integer k.Parameter:The treewidth tw of G.Question:Does G contain a set $S \subseteq V(G)$ with $|S| \leq k$ such that
G - S does not contain any of the graphs in \mathcal{F} as a minor?

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• $\mathcal{F} = \{K_2\}$: Vertex Cover.

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• $\mathcal{F} = \{K_2\}$: VERTEX COVER. Easily solvable in time $2^{\Theta(tw)} \cdot n^{\mathcal{O}(1)}$.

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- $\mathcal{F} = \{K_2\}$: VERTEX COVER. Easily solvable in time $2^{\Theta(tw)} \cdot n^{\mathcal{O}(1)}$.
- $\mathcal{F} = \{C_3\}$: Feedback Vertex Set.

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[Cut&Count. 2011]

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[Cut&Count. 2011]

• $\mathcal{F} = \{K_5, K_{3,3}\}$: Vertex Planarization.

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- $\mathcal{F} = \{K_5, K_{3,3}\}$: VERTEX PLANARIZATION. Solvable in time $2^{\Theta(\text{tw} \cdot \log \text{tw})} \cdot n^{\mathcal{O}(1)}$. [Jansen, Lokshtanov, Saurabh. 2014 + Pilipczuk. 2017]

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[Lewis, Yannakakis. 1980]

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Both problems are NP-hard if \mathcal{F} contains some edge. [Lewis, Yannakakis. 1980] FPT by Courcelle, or by Graph Minors theory.

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Objective

Determine, for every fixed \mathcal{F} , the (asymptotically) smallest function $f_{\mathcal{F}}$ such that \mathcal{F} -M-DELETION/ \mathcal{F} -TM-DELETION can be solved in time

 $f_{\mathcal{F}}(\mathsf{tw}) \cdot n^{\mathcal{O}(1)}$

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on *n*-vertex graphs.

- We do not want to optimize the degree of the polynomial factor.
- We do not want to optimize the constants.
- Our hardness results hold under the ETH.

¹Connected collection \mathcal{F} : all the graphs are connected.

• For every \mathcal{F} : \mathcal{F} -M/TM-DELETION in time $2^{2^{\mathcal{O}(\mathsf{tw} \cdot \log \mathsf{tw})}} \cdot n^{\mathcal{O}(1)}$.

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Summary of our results

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• \mathcal{F} (connected): \mathcal{F} -M/TM-DELETION not in time $2^{o(tw)} \cdot n^{\mathcal{O}(1)}$ unless the ETH fails, even if G planar.

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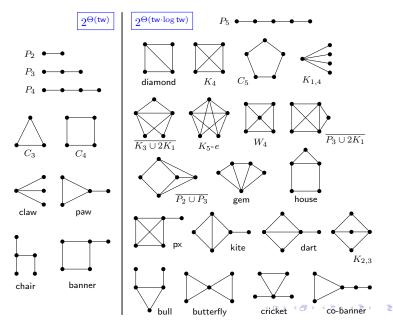
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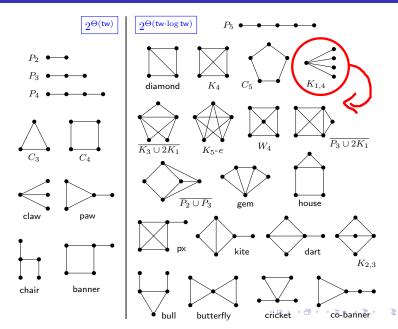
²Planar collection \mathcal{F} : contains at least one planar graph $\square \rightarrow A \square \rightarrow A$

Complexity of hitting small planar minors H

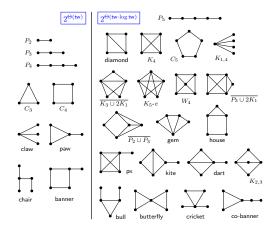


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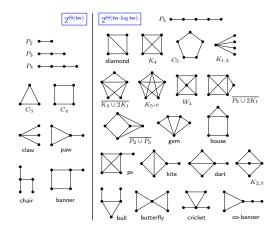
For topological minors, there (at least) one change



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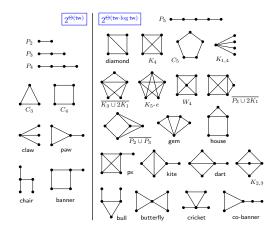


All these cases can be succinctly described as follows:



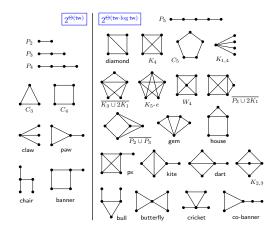
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- All the graphs on the right are not minors of



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- All the graphs on the left are minors of 4 (called the banner)
- All the graphs on the right are not minors of \downarrow except P_{5} .

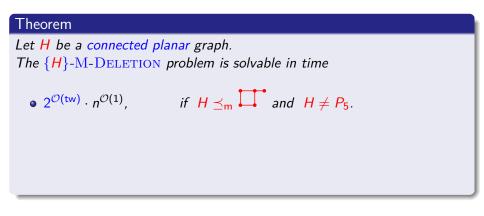
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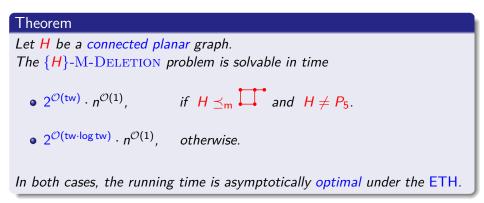
Theorem

Let H be a connected planar graph.

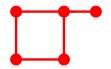
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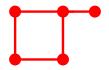
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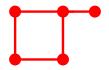


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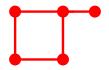


• Every connected component (with at least 5 vertices) of a graph that excludes the banner as a (topological) minor is either:

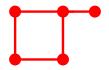
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- Both such types of components can be maintained by a dynamic programming algorithm in single-exponential time.
- If the characterization of the allowed connected components is enriched in some way, such as restricting the length of the allowed cycles or forbidding certain degrees, the problem becomes harder.

General algorithms

- For every \mathcal{F} : time $2^{2^{\mathcal{O}(\mathsf{tw} \cdot \log \mathsf{tw})}} \cdot n^{\mathcal{O}(1)}$.
- \mathcal{F} connected + planar: time $2^{\mathcal{O}(\mathsf{tw} \cdot \log \mathsf{tw})} \cdot n^{\mathcal{O}(1)}$.
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Lower bounds under the ETH

- 2^{o(tw)} is "easy".
- 2^{o(tw·log tw)} is much more involved and we get ideas from:

[Lokshtanov, Marx, Saurabh. 2011] [Marcin Pilipczuk. 2017] [Bonnet, Brettell, Kwon, Marx. 2017]

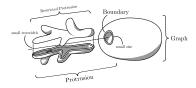
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We build on the machinery of boundaried graphs and representatives:



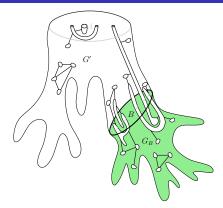
[Bodlaender, Fomin, Lokshtanov, Penninkx, Saurabh, Thilikos. 2009] [Fomin, Lokshtanov, Saurabh, Thilikos. 2010] [Kim, Langer, Paul, Reidl, Rossmanith, S., Sikdar. 2013] [Garnero, Paul, S., Thilikos. 2014] ▷ Skin

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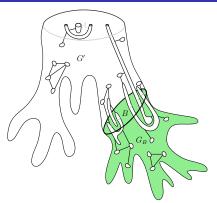
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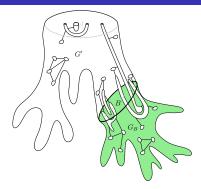
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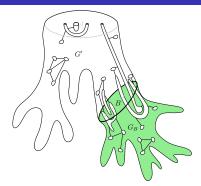
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For a fixed *F*, we define an equivalence relation ≡^(*F*,*t*) on *t*-boundaried graphs:

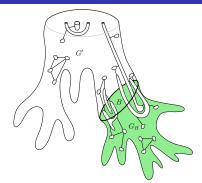
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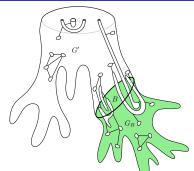
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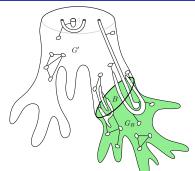
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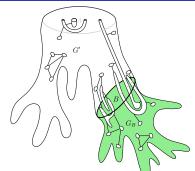
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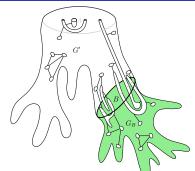
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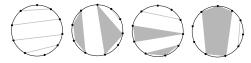
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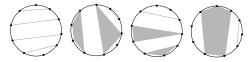


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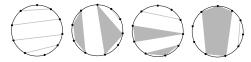
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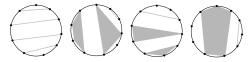
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- We can extend this algorithm to input graphs *G* embedded in arbitrary surfaces by using surface-cut decompositions.

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