## Hitting minors on bounded treewidth graphs

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Dagstuhl 19041 January 2019

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[arXiv 1704.07284]

## Treewidth behaves very well algorithmically

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Monadic Second Order Logic (MSOL):

Graph logic that allows quantification over sets of vertices and edges.

**Example**: DomSet(S) : [ $\forall v \in V(G) \setminus S, \exists u \in S : \{u, v\} \in E(G)$ ]

### Monadic Second Order Logic (MSOL):

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## Theorem (Courcelle, 1990)

Every problem expressible in MSOL can be solved in time  $f(tw) \cdot n$  on graphs on n vertices and treewidth at most tw.

In parameterized complexity: FPT parameterized by treewidth.

**Examples**: VERTEX COVER, DOMINATING SET, HAMILTONIAN CYCLE, CLIQUE, INDEPENDENT SET, *k*-COLORING for fixed *k*, ...

## Is it enough to prove that a problem is FPT?

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$$f(\mathsf{tw}) \cdot n^{\mathcal{O}(1)} = 2^{3^{4^{5^{6^{7^{8^{tw}}}}}}} \cdot n^{\mathcal{O}(1)}$$

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Major goal find the smallest possible function f(tw).

This is a very active area in parameterized complexity.

Remark: Algorithms parameterized by treewidth appear very often as a "black box" in all kinds of parameterized algorithms. Typically, FPT algorithms parameterized by treewidth are based on dynamic programming (DP) over a tree decomposition.

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But for the so-called connectivity problems, like LONGEST PATH or STEINER TREE, the "natural" DP algorithms provide only time

 $2^{\mathcal{O}(\mathsf{tw} \cdot \mathsf{log} \, \mathsf{tw})} \cdot n^{\mathcal{O}(1)}$ .

# (Single-exponential algorithms on sparse graphs)

On topologically structured graphs (planar, surfaces, minor-free), it is possible to solve connectivity problems in time  $2^{\mathcal{O}(tw)} \cdot n^{\mathcal{O}(1)}$ :

- Planar graphs:
- Graphs on surfaces:
- Minor-free graphs:

[Dorn, Penninkx, Bodlaender, Fomin. 2005]

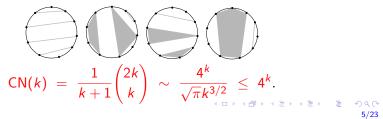
[Dorn, Fomin, Thilikos. 2006]

[Rué, S., Thilikos. 2010]

[Dorn, Fomin, Thilikos. 2008]

[Rué, S., Thilikos. 2012]

Main idea special type of decomposition with nice topological properties: partial solutions ↔ non-crossing partitions



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This was false!!

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Deterministic algorithms with algebraic tricks: [Bodlaender, Cygan, Kratsch, Nederlof. 2013]

Representative sets in matroids:

[Fomin, Lokshtanov, Saurabh. 2014]

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## No!

CYCLE PACKING: find the maximum number of vertex-disjoint cycles.

An algorithm in time  $2^{\mathcal{O}(\text{tw} \cdot \log \text{tw})} \cdot n^{\mathcal{O}(1)}$  is optimal under the ETH.

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ETH: The 3-SAT problem on *n* variables cannot be solved in time  $2^{o(n)}$ [Impagliazzo, Paturi. 1999] Do all connectivity problems admit single-exponential algorithms (on general graphs) parameterized by treewidth?

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There are other examples of such problems...

# The $\mathcal{F}\text{-}\mathrm{M}\text{-}\mathrm{Deletion}$ problem

Let  $\mathcal{F}$  be a fixed finite collection of graphs.

## $\mathcal{F} ext{-}\mathrm{M} ext{-}\mathrm{Deletion}$

Input:A graph G and an integer k.Parameter:The treewidth tw of G.Question:Does G contain a set  $S \subseteq V(G)$  with  $|S| \leq k$  such that<br/>G - S does not contain any of the graphs in  $\mathcal{F}$  as a minor?

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•  $\mathcal{F} = \{K_2\}$ : Vertex Cover.

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•  $\mathcal{F} = \{K_2\}$ : VERTEX COVER. Easily solvable in time  $2^{\Theta(tw)} \cdot n^{\mathcal{O}(1)}$ .

#### $\mathcal{F}$ -M-Deletion

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- $\mathcal{F} = \{K_2\}$ : VERTEX COVER. Easily solvable in time  $2^{\Theta(tw)} \cdot n^{\mathcal{O}(1)}$ .
- $\mathcal{F} = \{C_3\}$ : Feedback Vertex Set.

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[Cut&Count. 2011]

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[Cut&Count. 2011]

•  $\mathcal{F} = \{K_5, K_{3,3}\}$ : Vertex Planarization.

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- $\mathcal{F} = \{K_5, K_{3,3}\}$ : VERTEX PLANARIZATION. Solvable in time  $2^{\Theta(\text{tw} \cdot \log \text{tw})} \cdot n^{\mathcal{O}(1)}$ . [Jansen, Lokshtanov, Saurabh. 2014 + Pilipczuk. 2017]

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[Lewis, Yannakakis. 1980]

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Both problems are NP-hard if  $\mathcal{F}$  contains some edge. [Lewis, Yannakakis. 1980] FPT by Courcelle, or by Graph Minors theory.

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## Objective

Determine, for every fixed  $\mathcal{F}$ , the (asymptotically) smallest function  $f_{\mathcal{F}}$  such that  $\mathcal{F}$ -M-DELETION/ $\mathcal{F}$ -TM-DELETION can be solved in time

 $f_{\mathcal{F}}(\mathsf{tw}) \cdot n^{\mathcal{O}(1)}$ 

on *n*-vertex graphs.

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on *n*-vertex graphs.

- We do not want to optimize the degree of the polynomial factor.
- We do not want to optimize the constants.
- Our hardness results hold under the ETH.

<sup>&</sup>lt;sup>1</sup>Connected collection  $\mathcal{F}$ : all the graphs are connected.

• For every  $\mathcal{F}$ :  $\mathcal{F}$ -M/TM-DELETION in time  $2^{2^{\mathcal{O}(\mathsf{tw} \cdot \log \mathsf{tw})}} \cdot n^{\mathcal{O}(1)}$ .

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- $\mathcal{F}$  connected<sup>1</sup> + planar<sup>2</sup>:  $\mathcal{F}$ -M-DELETION in time  $2^{\mathcal{O}(\mathsf{tw} \cdot \mathsf{log} \, \mathsf{tw})} \cdot n^{\mathcal{O}(1)}$ .

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(For  $\mathcal{F}$ -TM-DELETION we need:  $\mathcal{F}$  contains a subcubic planar graph.)

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- $\mathcal{F} = \{H\}$ , H planar + connected:

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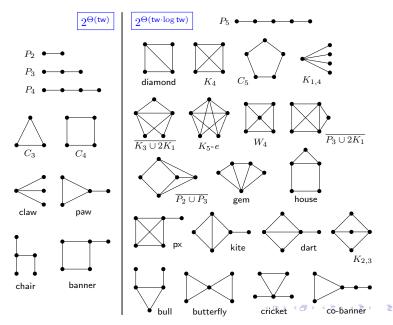
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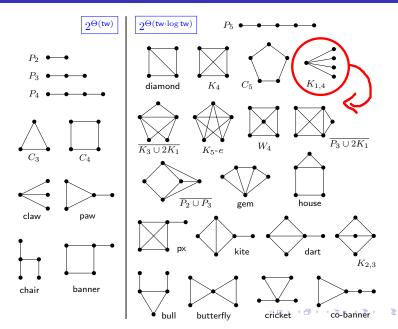
<sup>&</sup>lt;sup>2</sup>Planar collection  $\mathcal{F}$ : contains at least one planar graph  $\square \rightarrow A \square \rightarrow A$ 

### Complexity of hitting small planar minors H

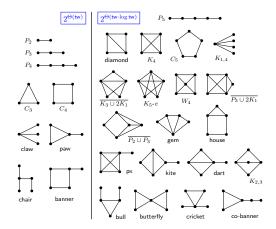


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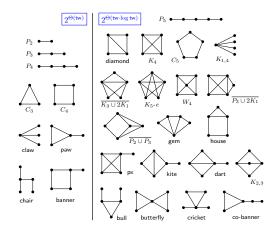
### For topological minors, there (at least) one change



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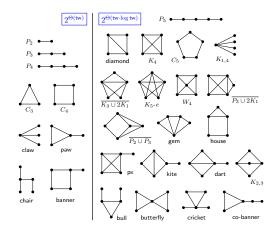


All these cases can be succinctly described as follows:



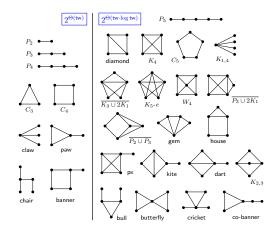
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- All the graphs on the right are not minors of



All these cases can be succinctly described as follows:

- All the graphs on the left are minors of 4 (called the banner)
- All the graphs on the right are not minors of  $\downarrow$  except  $P_{5}$ .

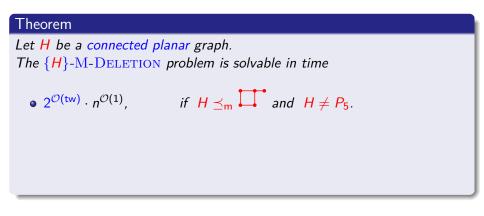
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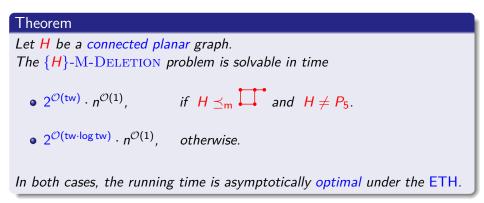
#### Theorem

Let H be a connected planar graph.

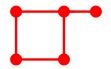
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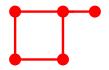
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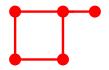


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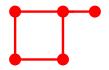


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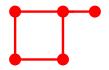
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- Both such types of components can be maintained by a dynamic programming algorithm in single-exponential time.
- If the characterization of the allowed connected components is enriched in some way, such as restricting the length of the allowed cycles or forbidding certain degrees, the problem becomes harder.

#### General algorithms

- For every  $\mathcal{F}$ : time  $2^{2^{\mathcal{O}(\mathsf{tw} \cdot \log \mathsf{tw})}} \cdot n^{\mathcal{O}(1)}$ .
- $\mathcal{F}$  connected + planar: time  $2^{\mathcal{O}(\mathsf{tw} \cdot \log \mathsf{tw})} \cdot n^{\mathcal{O}(1)}$ .
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### Lower bounds under the ETH

- 2<sup>o(tw)</sup> is "easy".
- 2<sup>o(tw·log tw)</sup> is much more involved and we get ideas from:

[Lokshtanov, Marx, Saurabh. 2011] [Marcin Pilipczuk. 2017] [Bonnet, Brettell, Kwon, Marx. 2017]

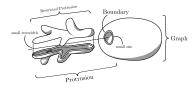
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#### We build on the machinery of boundaried graphs and representatives:



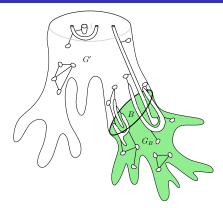
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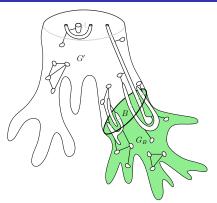
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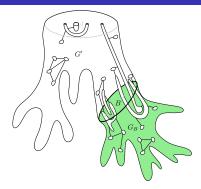
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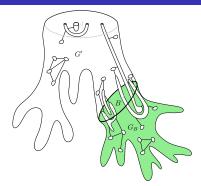
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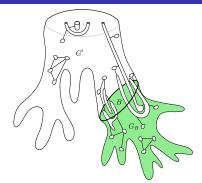
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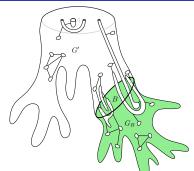
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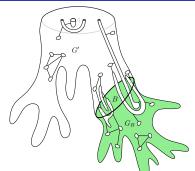
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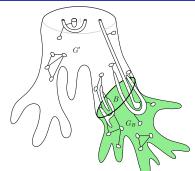
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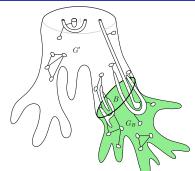
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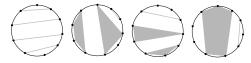
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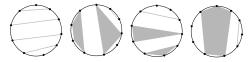


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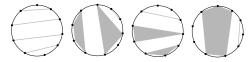
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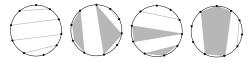
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Deletion to genus at most  $g: 2^{\mathcal{O}_g(\text{tw} \cdot \log \text{tw})} \cdot n^{\mathcal{O}(1)}$ . [Kociumaka, Pilipczuk. 2017]

- Ultimate goal: classify the (asymptotically) tight complexity of  $\mathcal{F}$ -DELETION for every family  $\mathcal{F}$ .
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