

Introduction + Bidimensionality Theory

Ignasi Sau

CNRS, LIRMM, Montpellier (France)

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Outline of the talk

1 Introduction, part II

- Treewidth
- Dynamic programming on tree decompositions
- Structure of H -minor-free graphs
- Some algorithmic issues
- A few words on other containment relations

2 Bidimensionality

- Some ingredients
- An illustrative example
- Meta-algorithms
- Further extensions

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Parameterized complexity in one slide

- **Idea** given an NP-hard problem, fix one parameter of the input to see if the problem gets more “tractable”.

Example: the size of a VERTEX COVER.

- Given a (NP-hard) problem with input of size n and a parameter k , a **fixed-parameter tractable (FPT)** algorithm runs in

$$f(k) \cdot n^{\mathcal{O}(1)}, \text{ for some function } f.$$

Examples: k -VERTEX COVER, k -LONGEST PATH.

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- **Single-exponential** FPT algorithm:

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- **Subexponential** FPT algorithm:

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Tree decompositions and treewidth

A *tree decomposition* of a graph G is a pair $D = (T, \mathcal{X})$ such that T is a tree and $\mathcal{X} = \{X_t \mid t \in V(T)\}$ is a collection of subsets of $V(G)$ such that:

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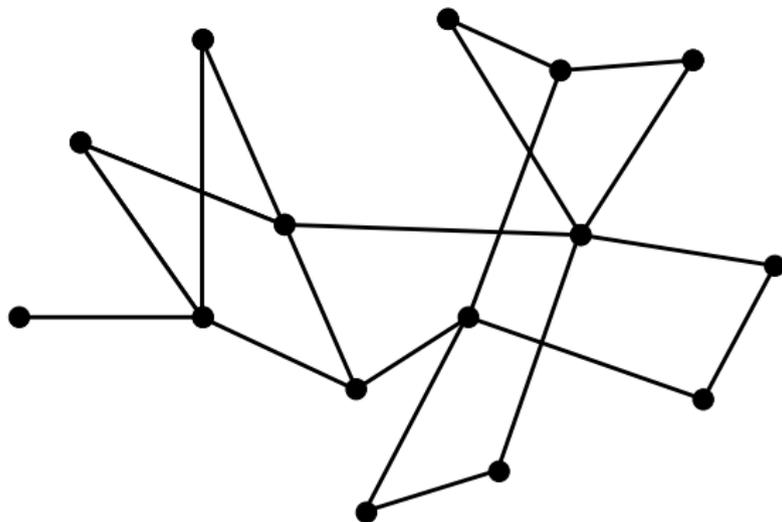
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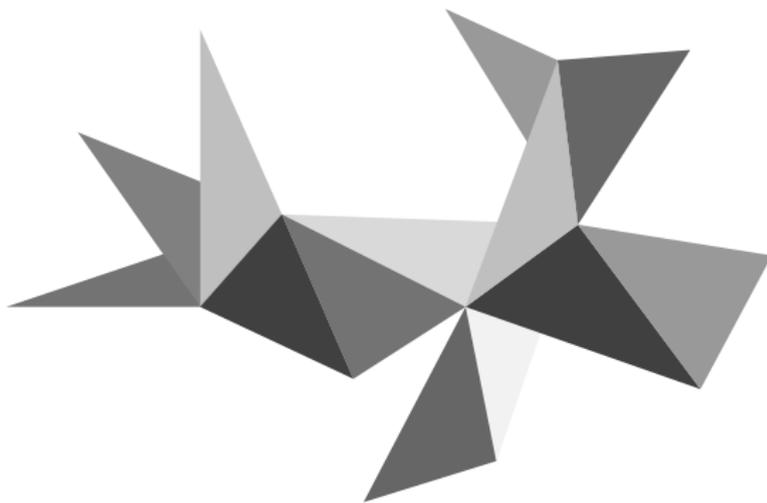
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Invariant that measures the *topological complexity* of a graph.

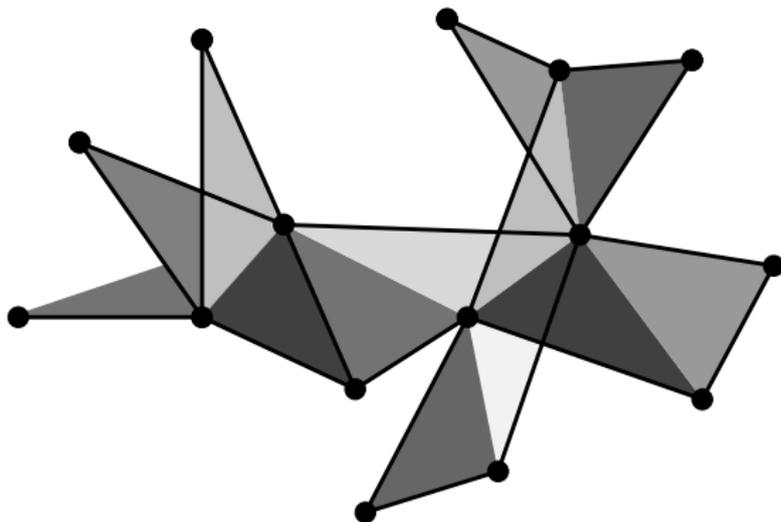
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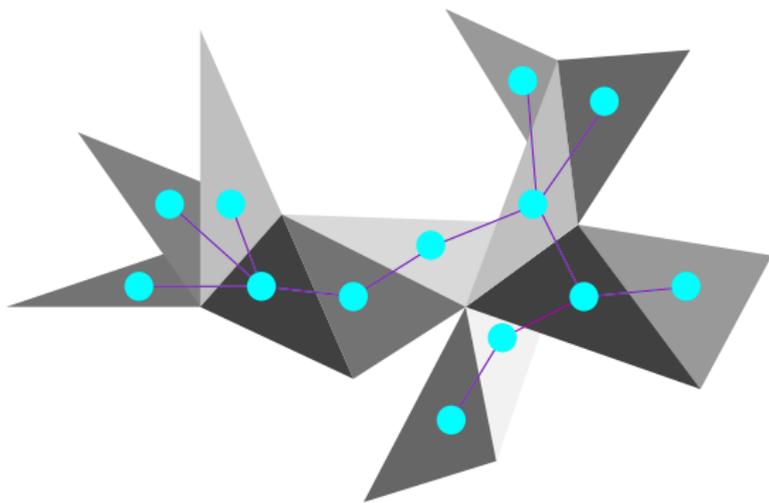
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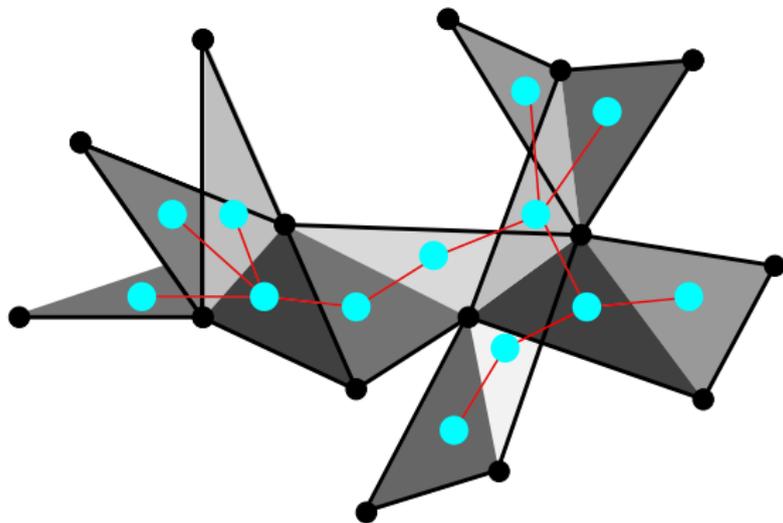
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 - **Open** Compute the treewidth of a planar graph.

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- The tables (S_i, a_i) at node X_i can be computed from the tables of its children as follows. For each S_i independent set of G_i :
 - If X_j is a child of X_i , an independent set S_j of G_j is **feasible** for S_i if $X_j \cap S_i = X_j \cap S_j$.
 - For each children X_j of X_i , let S_j be feasible for S_i s.t. (S_j, a_j) is defined and a_j is **maximized**.
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 - We set $a_i := |S_i| + \sum_j (a_j - |S_i \cap S_j|)$.
- Running time for each node X_i : $O(2^{2|X_i|})$.
- Overall running time: $2^{O(\text{tw}(G))} \cdot n$.

Courcelle's Theorem - algorithmic importance of treewidth

What we have seen with MAX. INDEPENDENT SET can be generalized to a wide family of problems:

Theorem (Courcelle. 1988)

Graph problems expressible in Monadic Second Order Logic (MSOL) can be solved in time $f(k) \cdot n^{O(1)}$ in graphs with n vertices and $tw \leq k$.

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- Running time (tight):

$$2^{2^{\dots 2^k}} \cdot n^{O(1)}.$$

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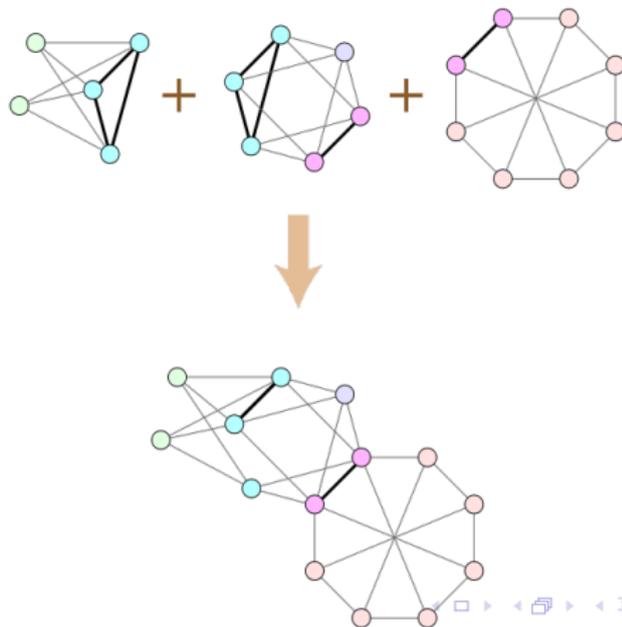
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Structure of H -minor-free graphs: roughly “bidimensional”

- Some (simplified) preliminaries:
 - **h -clique-sum** of two graphs G_1 and G_2 :
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Proof. By the Graph Minors Theorem, there exists a finite list of minimal excluded minors $\{F_1, \dots, F_\ell\}$ for the class \mathcal{G} . Then we can do minor testing and check whether $F_i \preceq_m G$ in time $O(n^2)$ for each $1 \leq i \leq \ell$.

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- But... what about the constant $h = f(|V(H)|)$??

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Fix a graph H . There exists a constant $h = f(|V(H)|)$ such that any H -minor-free graph G can be decomposed (in a **tree-like** way) into h -clique-sums from **h -almost-embeddable** graphs.

- Using this **tree-like** structure, a number of hard optimization problems can be solved **efficiently** in H -minor-free graphs using **DP**.
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★ Very recently, this constant has been made **explicit** and “**reasonable**”!

[Geelen, Huynh, and Richter. 2013]

[Mazoit. 2013]

Next subsection is...

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- Dynamic programming on tree decompositions
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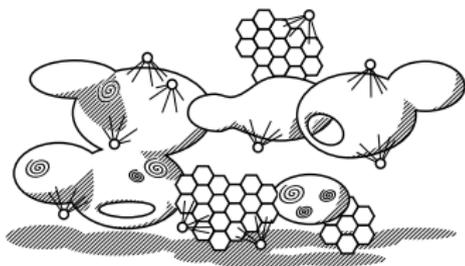


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Structure of sparse graphs - a nice picture by Felix Reidl

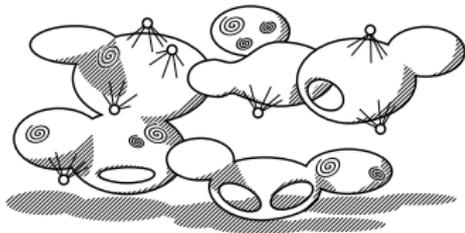
H -topological-
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treewidth-bounding



H -minor-free



bidimensional,
separation property



bounded genus



quasi-compact



planar



“distance-property”

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A few representative problems

VERTEX COVER

Input: A graph $G = (V, E)$ and a positive integers k .

Parameter: k .

Question: Does there exist a subset $C \subseteq V$ of size at most k such that $G[V \setminus C]$ is an independent set?

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A few representative problems (II)

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- We say that a parameter P is *closed under taking of minors/contractions* (or, briefly, *minor/contraction closed*) if for every graph H , $H \preceq_m G$ / $H \preceq_{cm} G$ implies that $P(H) \leq P(G)$.

Examples of minor/contraction closed parameters

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Important message grid-minors are the certificate of large treewidth.

Grid Exclusion Theorems on sparse graphs

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In sparse graphs: linear dependency between treewidth and grid-minors

How to use Grid Theorems algorithmically?

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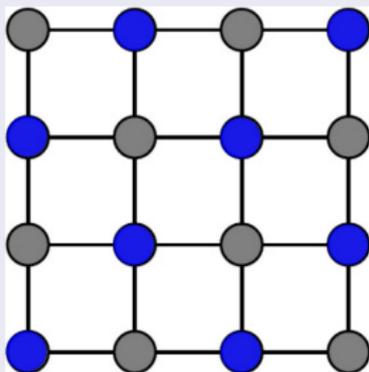
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Example: FPT algorithm for Planar Vertex Cover

A **vertex cover** C of a graph G , $\mathbf{vc}(G)$, is a set of vertices such that every edge of G has at least one endpoint in C .



Example: FPT algorithm for Planar Vertex Cover

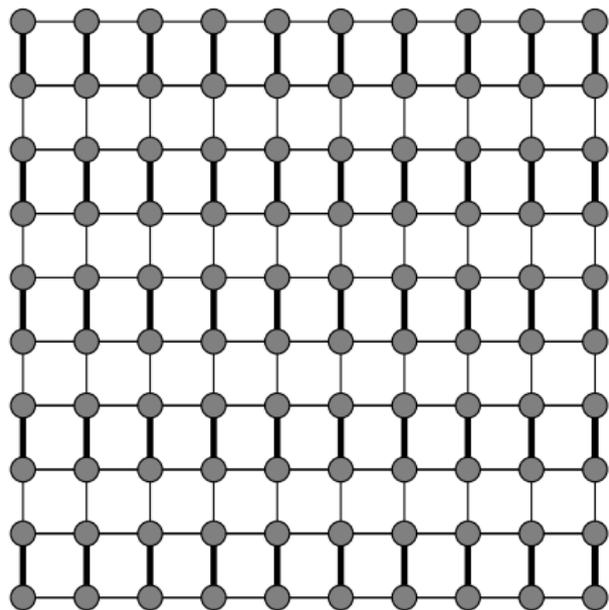
INPUT: Planar graph G on n vertices, and an integer k .

OUTPUT: Either a vertex cover of G of size $\leq k$, or a proof that G has no such a vertex cover.

RUNNING TIME: $2^{O(\sqrt{k})} \cdot n^{O(1)}$.

Objective subexponential FPT algorithm for PLANAR VERTEX COVER.

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$$\text{vc}(H_{l,l}) \geq \frac{l^2}{2}$$

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Example: FPT algorithm for Planar Vertex Cover

Let G be a planar graph of treewidth $\geq 6 \cdot \ell$ \implies G contains the $(\ell \times \ell)$ -grid $H_{\ell,\ell}$ as a minor

- The size of any vertex cover of $H_{\ell,\ell}$ is at least $\ell^2/2$.
- Recall that VERTEX COVER is a **minor closed** parameter.
- Since $H_{\ell,\ell} \preceq_m G$, it holds that $\mathbf{vc}(G) \geq \mathbf{vc}(H_{\ell,\ell}) \geq \ell^2/2$.

We are already very close to an algorithm...

Recall:

- k is the parameter of the problem.
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This gives a **subexponential FPT algorithm!**

Was Vertex Cover really just an example...?

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- ★ Only the **linear** Grid Theorem!

Arguments go through up to **H-minor-free** graphs.

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- An illustrative example
- **Meta-algorithms**
- Further extensions

Minor Bidimensionality:

[Demaine, Fomin, Hajiaghayi, Thilikos. 2005]

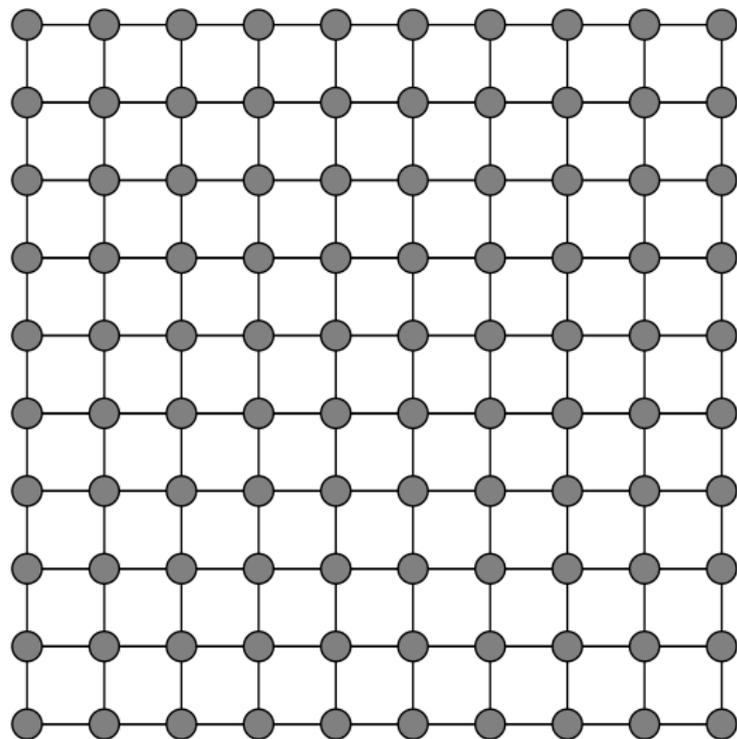
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① \mathbf{p} is closed under taking of minors (*minor closed*), and

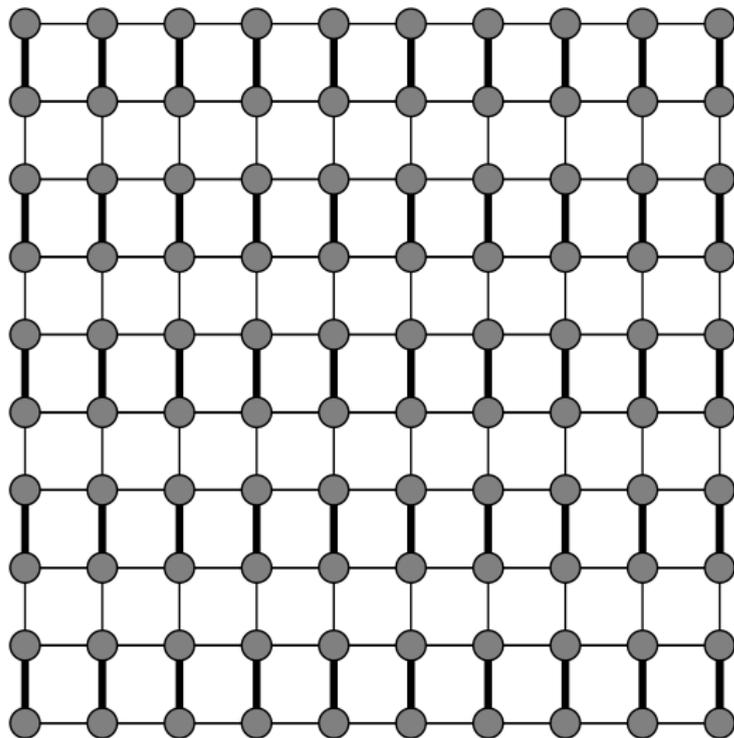
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VERTEX COVER OF A GRID



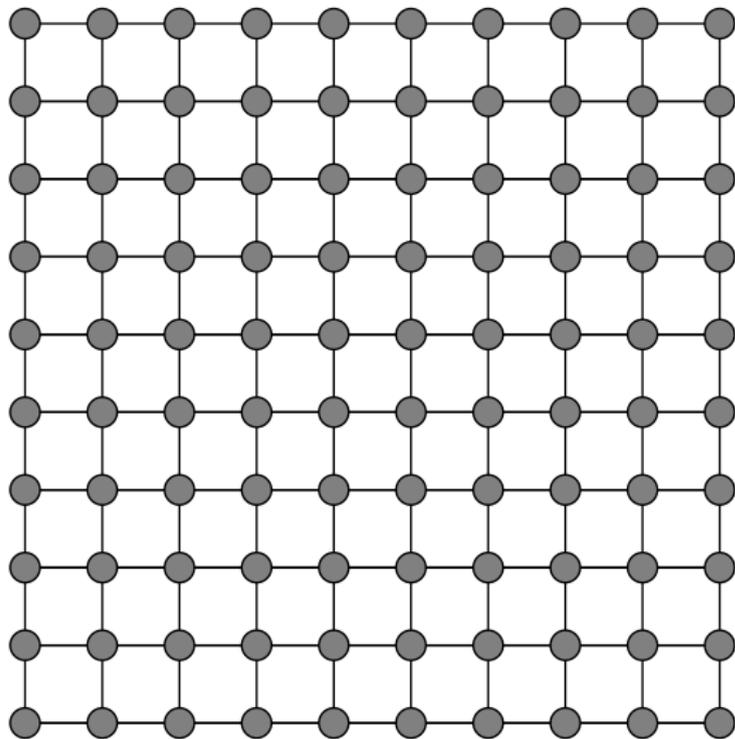
$H_{r,r}$ for $r = 10$

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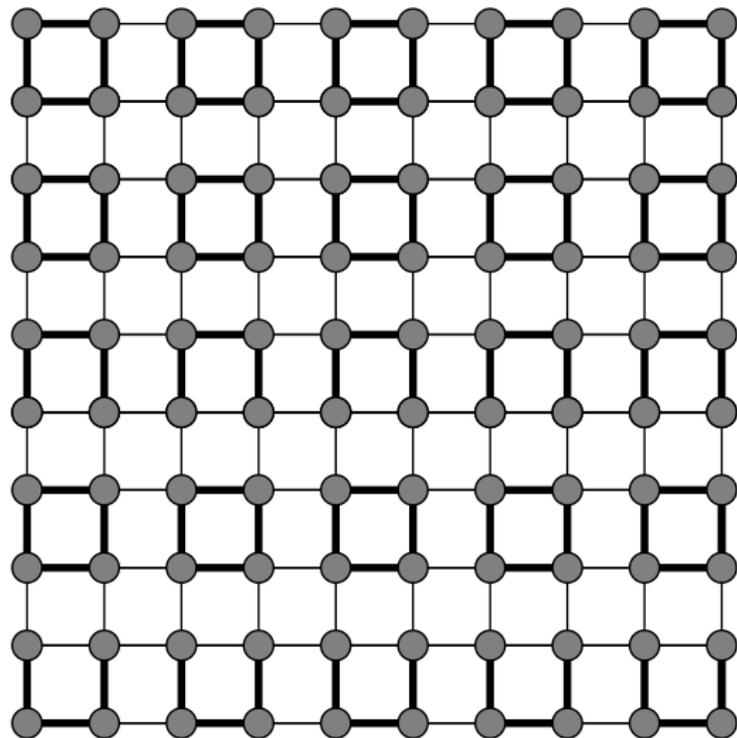


$$vc(H_{r,r}) \geq r^2/2$$

FEEDBACK VERTEX SET OF A GRID



FEEDBACK VERTEX SET OF A GRID



$$fvs(H_{r,r}) \geq r^2/4$$

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- If we have a DP algorithm for bounded treewidth running in time c^t or t^t , then it implies $2^{O(\sqrt{k})}$ or $2^{O(\sqrt{k} \log k)}$ algorithm.

Piecing everything together

Theorem

Let G be an H -minor-free graph, and let \mathbf{p} be a minor bidimensional graph parameter computable in time $2^{O(\text{tw}(G))} \cdot n^{O(1)}$.

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- Randomized algorithms using Cut&Count.

[Cygan et al. 2011]

- Deterministic algorithms based on rank of matrices.

[Boadlaender et al. 2012]

- Deterministic algorithms based on matroids.

[Fomin et al. 2013]

Minor Bidimensionality provides a meta-algorithm

- This result applies to all minor closed parameters:

VERTEX COVER, FEEDBACK VERTEX SET, LONG PATH,
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Minor Bidimensionality provides a meta-algorithm

- This result applies to all **minor closed** parameters:

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- What about **contraction closed** parameters??

DOMINATING SET, CONNECTED VERTEX COVER,
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Contraction Bidimensionality:

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Definition

A parameter \mathbf{p} is *contraction bidimensional* if

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What is a $(k \times k)$ -grid-like graph...?

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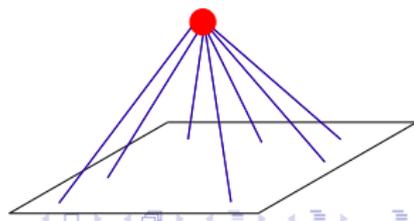
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- ★ For **apex-minor-free graphs**, this is a $(k \times k)$ -augmented grid, i.e., partially triangulated grid augmented with additional edges such that each vertex is incident to $O(1)$ edges to non-boundary vertices of the grid.

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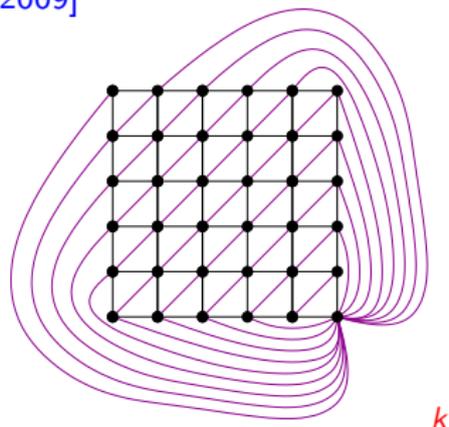
H is an **apex graph** if $\exists v \in V(H)$: $H - v$ is planar



Contraction bidimensionality: new definition

Finally, the right “ $(k \times k)$ -grid-like graph” was found:

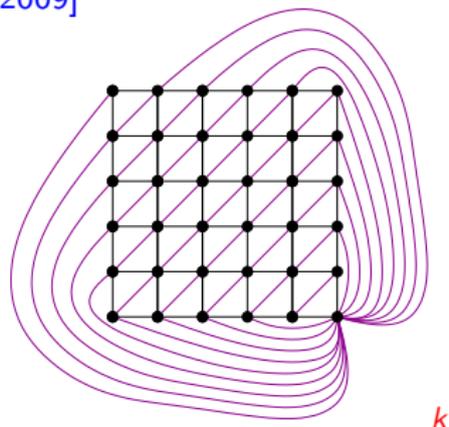
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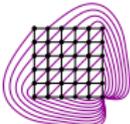
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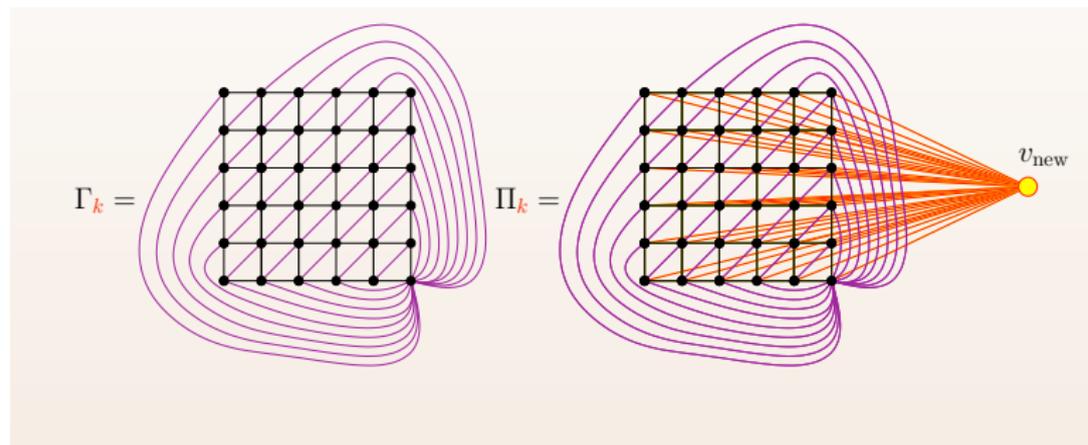
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As for **minor bidimensionality**, we need to prove that

► If $\text{tw}(G) = \Omega(k)$ then G contains  k as a **contraction**.

Two important grid-like graphs

Two pattern graphs Γ_k and Π_k :



$\Pi_k = \Gamma_k +$ a new universal vertex v_{new} .

The “contraction-certificates” for large treewidth

Theorem (Fomin, Golovach, Thilikos. 2009)

*For any integer $\ell > 0$, there is c_ℓ such that every connected graph of treewidth at least c_ℓ , contains K_ℓ , Γ_ℓ , or Π_ℓ as a **contraction**.*

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Further applications of Bidimensionality

- 1 **Bidimensionality + DP** \Rightarrow Subexponential FPT algorithms

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- ④ **Bidimensionality + new Grid Theorems** \Rightarrow **Geometric graphs**

[Fomin, Lokshtanov, Saurabh. 2012]

[Grigoriev, Koutsoukas, Thilikos. 2013]

Gràcies!

