Introduction to logic in graphs and algorithmic meta-theorems

Ignasi Sau

LIRMM, Université de Montpellier, CNRS, France

20th JCALM LIRMM, Montpellier, December 13-14, 2023







JCALM: Journées de Combinatoire et d'Algorithmes du Littoral Méditerranéen.

Take place once or twice a year since 2006.

Involved research teams:

- DALGO and ACRO teams at LIS in Marseille.
- AIGCo team (among others) at LIRMM in Montpellier.
- COATI common project at I3S and INRIA Sophia-Antipolis.
- GAPCOMB team at UPC in Barcelona.

Current JCALM

Topic: Logic and graph algorithms

Programme

Wednesday December 13th

- 09:30-10:20: Café+croissants et accueil des participant-e-s (cafétéria du LIRMM, bâtiment 4)
- 10:20-11:20: Ignasi Sau, Introduction to logic in graphs and algorithmic meta-theorems
- 11:30-12:30: Hugo Jacob, First-order model-checking on sparse graph classes
- 12:30-14:00: Repas (cafétéria du LIRMM, bâtiment 4)
- 14:00-15:00: Eunjung Kim, First-order model-checking on graphs of bounded twin-width
- 15:10-16:10: Dimitrios Thilikos, Logic and algorithms for graph minors
- 16:10-16:40: Café+croissants
- 16:40–17:30: Open problems
- Soirée: dîner en centre ville de Montpellier

Thursday December 14th

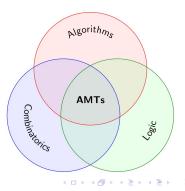
- 09:30-10:20: Café+croissants (cafétéria du LIRMM, bâtiment 4)
- 10:20-11:20: Matthieu Rosenfeld, Monadic second-order logic and treewidth
- 11:30-12:30: Giannos Stamoulis, Elementary first-order model-checking

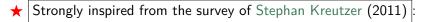
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- Logical component: given by a logic *L* (such as first-order or second-order logic).
- Structural (combinatorial) component: given by a class C (such as planar graphs, or graphs of bounded degree).





"Algorithmic Meta-Theorems"



- 2 AMTs for monadic second-order logic
- 3 AMTs for first-order logic

1 Introduction to logic (in graphs)

2 AMTs for monadic second-order logic





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 \triangleright MSO[σ]: class of formulas of monadic second-order logic over σ :

• Additional rule: if X is a second-order variable and $\varphi \in MSO[\sigma]$, then $\exists X \varphi \in MSO[\sigma]$ and $\forall X \varphi \in MSO[\sigma]$.

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 - If \overline{x} is a tuple and R a relation, $R\overline{x}$ denotes containment (\in, \subseteq) in R.
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 Quantifiers: ∃ (existential) and ∀ (universal).
- ▷ Abbreviations:
 - $x \neq y$, instead of $\neg x = y$.
 - $\varphi \rightarrow \psi$ instead of $(\neg \varphi \lor \psi)$.

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 \triangleright If we deal with (non-annotated) graphs: $\sigma = E$ (i.e., the edge relation).

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In this formula, X is a free variable.

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In this formula, X is a free variable. A pair (G, U), where $U \subseteq V(G)$, satisfies $(G, U) \models \varphi$ if and only if U is a dominating set in G (every vertex not in U has a neighbor in U).

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Expresses that a graph contains a dominating set of size k.

Independent set versus dominating set

• Independent set of size k:

$$\exists x_1 \ldots \exists x_k \ \bigwedge_{1 \le i < j \le k} (x_i \ne x_j \land \neg E x_i x_j)$$

• Dominating set of size k:

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This suggests that the DOMINATING SET problem might be harder than the INDEPENDENT SET problem, as we shall see later...

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 $(G, U_1, U_2) \models \varphi$ if and only if (U_1, U_2) is a bipartition of V(G).

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$$\tau := \exists C_1 \exists C_2 \exists C_3 (\forall x \bigvee_{i=1}^3 C_i x) \land \forall x \forall y (Exy \to \bigwedge_{i=1}^3 \neg (C_i x \lor C_i y))$$

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A graph $G \models \tau$ if and only if G is 3-colorable.

Let \mathcal{L} be a fixed logic. We define the MODEL-CHECKING problem of \mathcal{L} :

MC(\mathcal{L}) Input: A structure A and a sentence $\varphi \in \mathcal{L}$. Question: $A \models \varphi$? Let \mathcal{L} be a fixed logic. We define the MODEL-CHECKING problem of \mathcal{L} :

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Related problem:

SATISFIABILITY(\mathcal{L}) **Input:** A sentence $\varphi \in \mathcal{L}$. **Question:** Does there exist a structure *A* such that $A \models \varphi$?

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Is it the end of the story? We need to parameterize the problem!

Idea Measure the complexity of an algorithm in terms of the input size and an additional integer parameter.

This theory started in the late 80's, by Downey and Fellows:





Today, it is a well-established area with hundreds of articles published every year in the most prestigious TCS journals and conferences.

Parameterized problems

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- k-VERTEX COVER: Does a graph G contain a set $S \subseteq V(G)$, with $|S| \leq k$, containing at least an endpoint of every edge?
- INDEPENDENT SET: Does a graph G contain a set $S \subseteq V(G)$, with $|S| \ge k$, of pairwise non-adjacent vertices?
- VERTEX *k*-COLORING: Can the vertices of a graph be colored with $\leq k$ colors, so that any two adjacent vertices get different colors?

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These three problems are NP-hard, but are they equally hard?

• *k*-VERTEX COVER: Solvable in time $\mathcal{O}(2^k \cdot (m+n))$

• INDEPENDENT SET: Solvable in time $\mathcal{O}(k^2 \cdot n^k)$

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• VERTEX *k*-COLORING: NP-hard for fixed k = 3.

The problem is para-NP-hard

Why *k*-INDEPENDENT SET may not be FPT?

k-INDEPENDENT SET: Solvable in time $k^2 \cdot \mathbf{n}^k = f(k) \cdot \mathbf{n}^{g(k)}$

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Working hypothesis of paramet. complexity: <u>k-INDEP</u>. SET is not FPT (in classical complexity: SAT cannot be solved in poly-time) Let A, B be two parameterized problems.

How to transfer hardness among parameterized problems?

Let A, B be two parameterized problems.

A parameterized reduction from A to B is an algorithm such that:

Instance
$$(x, k)$$
 of A time $f(k) \cdot |x|^{\mathcal{O}(1)}$

Instance
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 of B

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Instance (x, k) of A time $f(k) \cdot |x|^{\mathcal{O}(1)}$ Instance (x', k') of B((x, k) is a YES-instance of $A \Leftrightarrow (x', k')$ is a YES-instance of B. ($k' \leq g(k)$ for some computable function $g : \mathbb{N} \to \mathbb{N}$. Let A, B be two parameterized problems.

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W[1]-hard problem: \exists parameterized reduction from *k*-INDEP. SET to it. W[2]-hard problem: \exists param. reduction from *k*-DOMINATING SET to it. Let A, B be two parameterized problems.

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W[1]-hard problem: \exists parameterized reduction from *k*-INDEP. SET to it. W[2]-hard problem: \exists param. reduction from *k*-DOMINATING SET to it. W[*i*]-hard: strong evidence of not being FPT. Let A, B be two parameterized problems.

Instance (x, k) of A time $f(k) \cdot |x|^{\mathcal{O}(1)}$

A parameterized reduction from A to B is an algorithm such that:

(x, k) is a YES-instance of A ⇔ (x', k') is a YES-instance of B.
k' ≤ g(k) for some computable function g : N → N.

W[1]-hard problem: \exists parameterized reduction from *k*-INDEP. SET to it. W[2]-hard problem: \exists param. reduction from *k*-DOMINATING SET to it. W[*i*]-hard: strong evidence of not being FPT. Hypothesis: FPT \neq W[1]

Instance (x', k') of B

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The "right" problem to consider is the following :

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MC(\mathcal{L})
Input: A structure A and a sentence \varphi \in \mathcal{L}.
Parameter: |\varphi|.
Question: A \models \varphi?
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The "right" problem to consider in graphs is the following :

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k-INDEP. SET is W[1]-hard

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k-INDEP. SET is W[1]-hard \Rightarrow MC(FO) is W[1]-hard (and XP).

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MC(\mathcal{L})

Input: A graph G and a sentence \varphi \in \mathcal{L}.

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Question: G \models \varphi?
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We restrict the input graph G to belong to some particular graph class C.

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MC(\mathcal{L} , **p**) **Input:** A graph G and a sentence $\varphi \in \mathcal{L}$. **Parameter:** $|\varphi| + \mathbf{p}(G)$. **Question:** $G \models \varphi$?

Holy grail: for which \mathcal{L} and \mathcal{C} is $MC(\mathcal{L}, \mathcal{C})$ FPT?

$$f(|\varphi|, \mathbf{p}(G)) \cdot |G|^{\mathcal{O}(1)}$$

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Introduction to logic (in graphs)

2 AMTs for monadic second-order logic





MSO model-checking

```
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As some of you may imagine: we take $\mathbf{p} = \frac{\mathsf{treewidth}}{\mathsf{treewidth}}$.

- 1972: Bertelè and Brioschi (dimension).
- 1976: Halin (*S*-functions of graphs).
- 1984: Arnborg and Proskurowski (partial *k*-trees).
- 1984: Robertson and Seymour (treewidth).

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- 1976: Halin (*S*-functions of graphs).
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- 1984: Robertson and Seymour (treewidth).

Treewidth measures the (topological) similarity of a graph with a forest.

Example of a 2-tree:

For $k \ge 1$, a *k*-tree is a graph that can be built starting from a (k + 1)-clique and then iteratively adding a vertex connected to a *k*-clique.



[Figure by Julien Baste]

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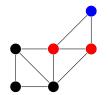
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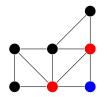
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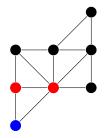
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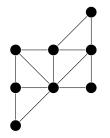
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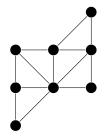
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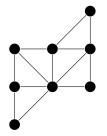


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For $k \ge 1$, a *k*-tree is a graph that can be built starting from a (k + 1)-clique and then iteratively adding a vertex connected to a *k*-clique.

A partial k-tree is a subgraph of a k-tree.

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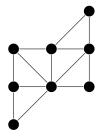
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Construction suggests the notion of tree decomposition: small separators.

• Tree decomposition of a graph G:

```
pair (T, \{X_t \mid t \in V(T)\}), where 
T is a tree, and 
X_t \subseteq V(G) \quad \forall t \in V(T) \text{ (bags)},
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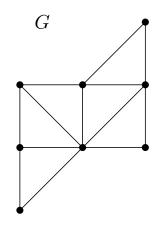
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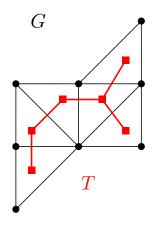
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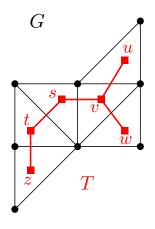
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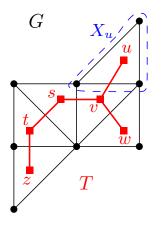
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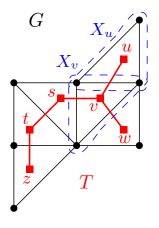
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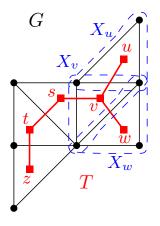
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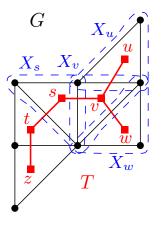
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pair $(T, \{X_t \mid t \in V(T)\})$, where *T* is a tree, and $X_t \subseteq V(G) \quad \forall t \in V(T) \text{ (bags),}$

satisfying the following:

- $\bigcup_{t\in V(T)} X_t = V(G)$,
- $\forall \{u, v\} \in E(G), \exists t \in V(T)$ with $\{u, v\} \subseteq X_t$.
- ∀v ∈ V(G), bags containing v define a connected subtree of T.
- Width of a tree decomposition: $\max_{t \in V(T)} |X_t| - 1.$
- Treewidth of a graph *G*, tw(*G*): minimum width of a tree decomposition of *G*.



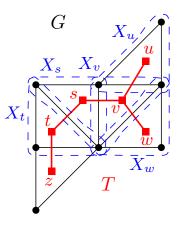
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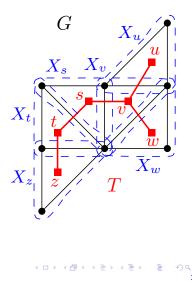
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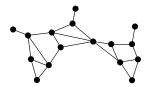
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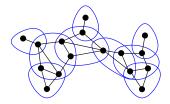
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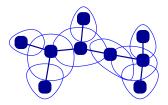
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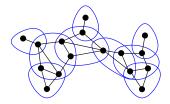
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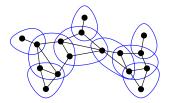


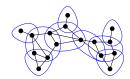


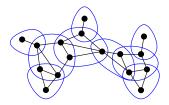


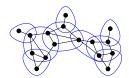




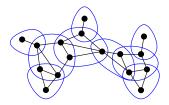


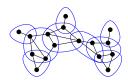
















Courcelle's theorem

(Credit also goes to Arnborg, Lagergreen, and Seese.)

The following problem is fixed-parameter tractable:

```
MC(MSO, tw)

Input: A graph G and a sentence \varphi \in MSO.

Parameter: |\varphi| + tw(G).

Question: G \models \varphi?
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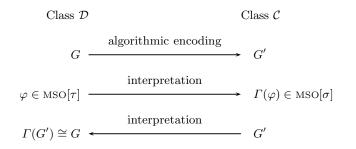
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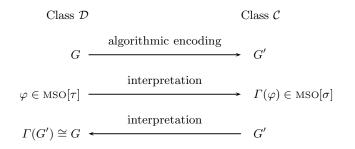
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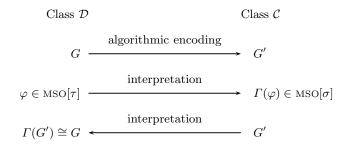
- Can be seen as an abstraction of the notion of dynamic programming.
- Also applies to the extension of MSO by modular counting: CMSO.
 [Courcelle. 1990]
- Can be generalized to optimize a linear function of free second-order variables.
 [Arnborg, Lagergreen, Seese. 1991]



Suppose that MC(MSO, C) is FPT



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For Courcelle's theorem: interpret "tw $\leq k$ " into the class of labeled trees.

Is treewidth the limit of tractability of MSO?

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Is treewidth the limit of tractability of MSO? Cliquewidth!

Another crucial parameter: cliquewidth.

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A graph G has cliquewidth at most k if it can be obtained by the following operations, for $i, j \in [k]$, with $i \neq j$:

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Small cliquewidth does not mean "being tree-like" (such as small treewidth), but having a structure with a "tree-like decomposition".

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Is the above theorem strictly more general than Courcelle's theorem?

MSO_1 and MSO_2

 MSO_1 in graphs: we allow quantification on sets of vertices.

 MSO_2 in graphs: we allow quantification on sets of vertices and edges.

MSO₂ in graphs: we allow quantification on sets of vertices and edges.

Two typical ways to encode a graph G:

Standard encoding: universe = V(G), with the binary "edge" relation.

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 \triangleright Is it possible that MC(MSO₂, cw) is FPT?

EDGE DOMINATING SET, HAMILTONIAN CYCLE, and GRAPH COLORING are MSO₂-definable and W[1]-hard parameterized by cliquewidth. [Fomin, Golovach, Lokshtanov, Saurabh. 2010] For MSO we cannot go really further than bounded treewidth/cliquewidth: 3-COLORABILITY is NP-complete on planar graphs of degree at most 4.

[Garey, Johnson, Stockmeyer. 1974]

Introduction to logic (in graphs)

2 AMTs for monadic second-order logic

3 AMTs for first-order logic

MC(FO) Input: A graph *G* and a sentence $\varphi \in$ FO. Parameter: $|\varphi|$. Question: $G \models \varphi$?

As we said, this problem is in XP: solvable in time $|G|^{f(|\varphi|)}$.

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MC(FO, C) Input: A graph $G \in C$ and a sentence $\varphi \in FO$. Parameter: $|\varphi|$. Question: $G \models \varphi$?

Question: for which (parameterized) graph classes C is MC(FO, C) FPT?

Crucial property of FO: locality

▷ A first-order formula $\varphi(x)$ on graphs is *r*-local if, for every graph *G* and every $v \in V(G)$,

$$G \models \varphi(\mathbf{v}) \Leftrightarrow G[N_{\mathbf{r}}[\mathbf{v}]] \models \varphi],$$

where $N_r[v]$ denotes the set of vertices at distance at most r from v in G.

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> A basic local sentence is a first-order sentence of the form

$$\exists x_1 \ldots \exists x_k \left(\bigwedge_{1 \le i < j \le k} \operatorname{dist}(x_i, x_j) > 2r \land \bigwedge_{i=1}^k \psi(x_i) \right),$$

where $\psi(x_i)$ is a local first-order formula.

Theorem (Gaifman. 1982)

Every first-order sentence is equivalent to a Boolean combination of basic local sentences, which can be effectively computed given the sentence.

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This translation may involve a non-elementary blow-up in the size of the sentence.

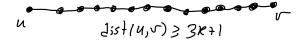
[Dawar, Grohe, Kreutzer, Schweikardt. 2007]

$$\varphi_{k} := \exists x_{1} \dots \exists x_{k} \forall y \left(\bigvee_{i=1}^{k} (x_{i} = y \lor Eyx_{i}) \right)$$

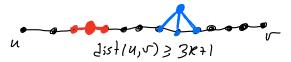
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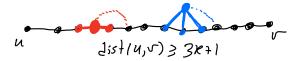
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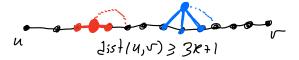


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To convert it into "Gaifman normal form": if diameter $\geq 3k + 1 \rightarrow$ 'no'.

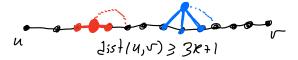


 φ_k is equivalent to the conjunction of these two basic local sentences:

• Diameter at most 3k: $\psi := \neg \exists x_1 \exists x_2 \operatorname{dist}(x_1, x_2) \ge 3k + 1$.

$$\varphi_k := \exists x_1 \ldots \exists x_k \forall y \left(\bigvee_{i=1}^k (x_i = y \lor Eyx_i)\right)$$

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 ∃x_χ(x), where χ(x) is the (3k + 1)-local formula

$$\exists y_1 \in N_{3k+1}(x) \dots \exists y_k \in N_{3k+1}(x) \forall z \in N_{3k+1}(x) \left(\bigvee_{i=1}^k (y_i = z \lor Ezy_i)\right)$$

Theorem (Seese. 1996)

Let $d \in \mathbb{N}$ and let C_d be the class of graphs of degree bounded by d. Then $MC(FO, C_d)$ is FPT.

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Proof:

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• For every $v \in V(G)$, we test whether $G[N_r[v]] \models \psi$. Since $G[N_r[v]]$ has constant size, easy to do!

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- For every v ∈ V(G), we test whether G[N_r[v]] ⊨ ψ.
 Since G[N_r[v]] has constant size, easy to do!
- Finally, we greedily try to find k such "good" vertices far apart.

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Let $d \in \mathbb{N}$ and let C_d be the class of graphs of degree bounded by d. Then $MC(FO, C_d)$ is FPT.

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- If *G*[*N_r*[*v*]] has constant size, easy to do!
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- But also if $tw(G[N_r[v]]) \leq f(r)$:

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 bounded degree [Seese, 1996]
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 locally bounded treewidth [Frick & Grohe, 2001]
 excluding a minor [Flum & Grohe, 2001]

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 nowhere dense [Grohe, Kreutzer, Siebertz, 2017]
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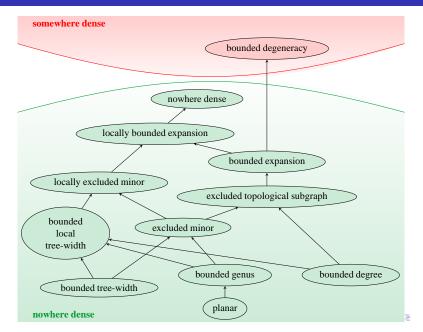
 structurally bounded degree [Gajarský, Hliněný, Lokshtanov, Obdržálek, Ramanujan, 2016]
 structurally bounded expansion [Gajarský, Kreutzer, Nešetřil, Ossona de Mendez, Mi. Pilipczuk, Siebertz, Toruńczyk, 2018]

 structurally nowhere dense [Dreier, Mählmann, Siebertz, 2023]
 structurally bounded local cliquewidth [Bonnet, Dreier, Gajarský, Kreutzer, Mählmann, Simon, Toruńczyk, 2022]

 monadically stable [Dreier, Eleftheriadis, Mählmann, McCarty, Mi. Pilipczuk, Toruńczyk, 2023]
 monadically NIP/dependent ?

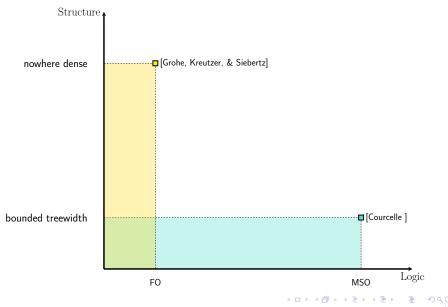
MSO

FO model-checking on sparse graph classes

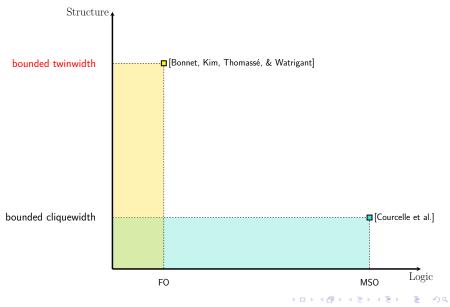


41

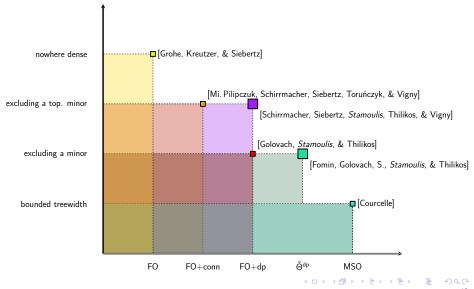
Simplified picture for monotone graph classes



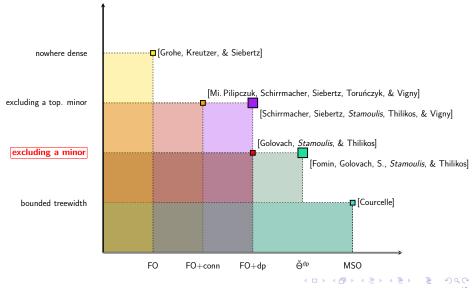
Simplified picture for hereditary graph classes



A lot of interesting stuff between FO and MSO

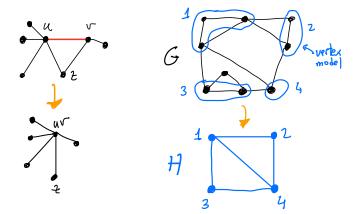


A lot of interesting stuff between FO and MSO



Graph minors

A graph *H* is a minor of a graph *G*, denoted by $H \leq_m G$, if *H* can be obtained by a subgraph of *G* by contracting edges.



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Minor-closed graph classes

A graph class \mathcal{C} is minor-closed (or closed under minors) if

 $G \in \mathcal{C} \Rightarrow H \in \mathcal{C}$ for every $H \leq_m G$.

Minor-closed graph classes

A graph class C is minor-closed (or closed under minors) if

 $G \in \mathcal{C} \Rightarrow H \in \mathcal{C}$ for every $H \leq_m G$.

Examples of minor-closed graph classes:

- Independent sets.
- Forests.
- Subgraphs of series-parallel graphs.
- Planar graphs.
- Graphs embeddable in a fixed surface.
- Linklessly embeddable graphs.
- Knotlessly embeddable graphs.

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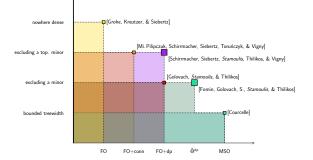
A graph class C is minor-closed (or closed under minors) if

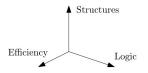
 $G \in \mathcal{C} \Rightarrow H \in \mathcal{C}$ for every $H \leq_m G$.

Theorem (Robertson, Seymour. 1983-2004)

Every minor-closed graph class C can be characterized by a finite list of excluded minors.

Missing axis: efficiency dimension





$$f(|\varphi|, \mathbf{p}(G)) \cdot |G|^{\mathcal{O}(1)}$$

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