Subexponential Parameterized Algorithms for Bounded-Degree Connected Subgraph Problems on Planar Graphs

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The *bidimensionality* theory [2] provides a general framework to obtain subexponential parameterized algorithms for a broad family of NP-hard problems on planar graphs (and more generally, for *sparse* families of graphs). The aim of this talk is to illustrate this methodology with the following parameterized problem (for $d \ge 2$):

MAXIMUM *d*-DEGREE-BOUNDED CONNECTED SUBGRAPH (MDBCS_{*d*}) **Input** : A graph *G* and a non-negative integer *k*. **Parameter** : *k*. **Question** : Does *G* contain a connected subgraph *H* with $\Delta(H) \leq d$ and $|E(H)| \geq k$?

Notice that if d = 2, MDBCS_d is equivalent to the LONGEST PATH (or CYCLE, if G is Hamiltonian) problem and can be seen as a generalisation of it. This problem is one of the classical NP-hard problems listed by Garey and Johnson in [3], and it has been recently proved in [1] that MDBCS_d is not in APX for any $d \ge 2$. It turns out that without the connectivity constraint, this problem is known to be solvable in polynomial time (for any d) using matching techniques [4].

Our target is to obtain a $2^{\mathcal{O}(\sqrt{k})} \cdot \mathcal{O}(n)$ step algorithm (with n = |V(G)|) for MDBCS_d when the input is restricted to planar graphs. The same strategy can be extended to several problems asking for a maximum connected subgraph satisfying certain degree constraints. Loosely speaking, the idea is as follows. We define the following parameter on simple undirected graphs :

 $\operatorname{medbcs}_d(G) = \max\{|E(H)| \mid H \subseteq G \land H \text{ is connected } \land \Delta(H) \leq d\}.$

Then we distinguish two cases according to the *branchwidth* of G (**bw**(G) for short) :

- If $\mathbf{bw}(G)$ is big (greater than \sqrt{k}), we must exhibit a certificate that $\mathbf{medbcs}_d(G)$ is also big (proving that the parameter is *minor-closed* and looking at its behaviour on the square grid), and then the answer to the parameterized problem is automatically YES.
- Otherwise, if $\mathbf{bw}(G)$ is *small* (smaller than \sqrt{k}), we compute $\mathbf{medbcs}_d(G)$ efficiently using Catalan structures and dynamic programming techniques over an optimal branch decomposition of G.

References

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