

Finding subdivisions of spindles on digraphs

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Outline of the talk

- 1 Introduction
- 2 Our results
- 3 NP-hardness reduction
- 4 Polynomial-time algorithm
- 5 Sketch of the FPT algorithms
- 6 Conclusions

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Digraph subdivisions

In this talk we focus on **directed graphs**, or **digraphs**.

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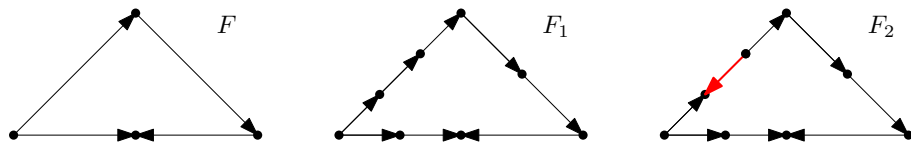
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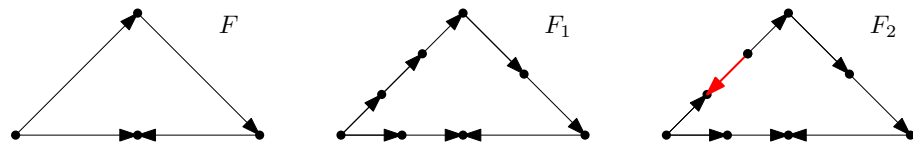
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We are interested in the following problem:

DIGRAPH SUBDIVISION

Instance: Two digraphs G and F .

Question: Does G contain a subdivision of F as a subdigraph?

Recent work on finding digraph subdivisions

This problem has been introduced by [Bang-Jensen, Havet, Maia. 2015]

Let F be a fixed digraph.

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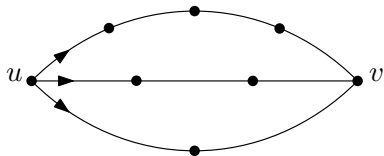
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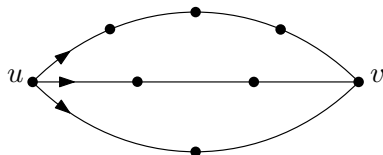
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When $|V(F)| = 4$, there are only 5 open cases. [Havet, Maia, Mohar. 2017]

We focus on finding subdivisions of spindles

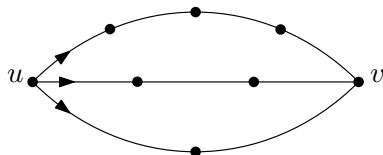


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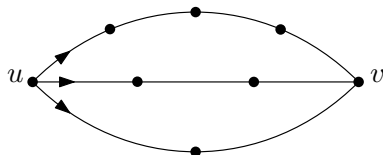
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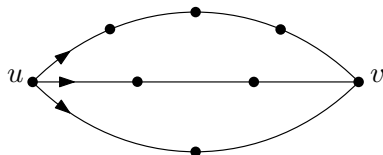


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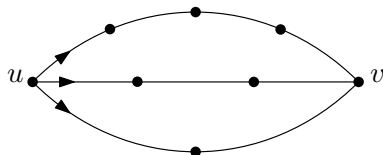
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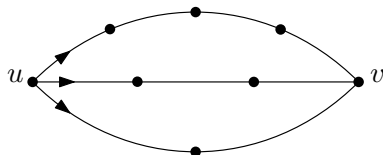
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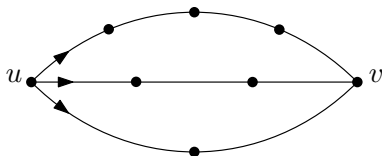
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G contains a subdivision of a $(1 \times \ell)$ -spindle \iff
the length of a LONGEST PATH in G is at least ℓ .

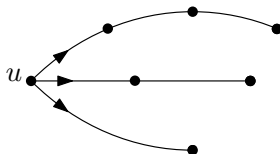
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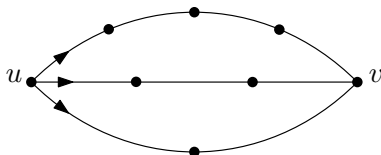
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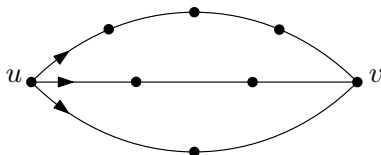
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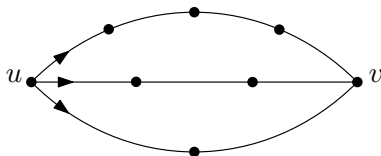


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Is a running time $f(|V(F)|) \cdot n^{O(1)}$ possible, for some function f ?

This question had been asked by [Bang-Jensen, Havet, Maia. 2015]

Parameterized complexity in one slide

- The area of **parameterized complexity** was introduced in the 90's by Downey and Fellows.
- Idea given an NP-hard problem with **input size n** , fix one **parameter k** of the input to see whether the problem gets more “tractable”.

Example: k = length of a LONGEST PATH.

- Given a (NP-hard) problem with input of size n and a parameter k , a **fixed-parameter tractable (FPT)** algorithm runs in time

$$f(k) \cdot n^{O(1)}, \text{ for some function } f.$$

Examples: k -VERTEX COVER, k -LONGEST PATH.

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Our results (I): optimization problems

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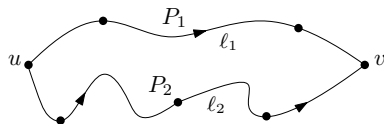
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2-spindle: spindle with exactly two paths.

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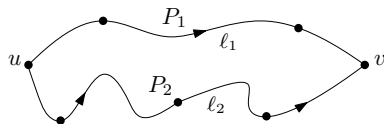
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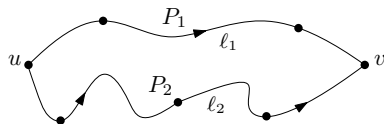
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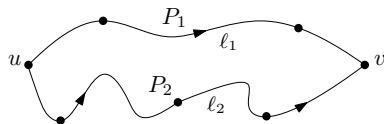
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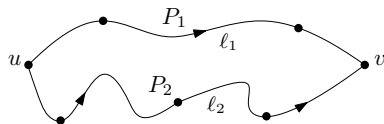
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Both FPT algorithms are **asymptotically optimal** under the **ETH**.

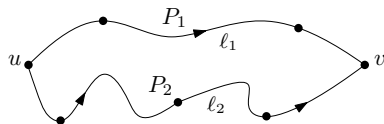
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ETH: \nexists algorithm solving **3-SAT** on a formula with n variables in time $2^{o(n)}$.

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We prove the case $\ell = 4$, by reduction from 3-DIMENSIONAL MATCHING:

Given three sets A, B, C of the same size and a set of triples $\mathcal{T} \subseteq A \times B \times C$, decide whether there exists a set $\mathcal{T}' \subseteq \mathcal{T}$ of pairwise disjoint triples with $|\mathcal{T}'| = |A|$.

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Our reduction is strongly inspired by [Brewster, Hell, Pantel, Rizzi, Yeo. 2003]

Reduction for $\ell = 4$

Given (A, B, C, \mathcal{T}) of 3-DIMENSIONAL MATCHING, with $|A| = n$ and $\mathcal{T} = m$, we construct G of MAX $(\bullet \times \ell)$ -SPINDLE SUBDIVISION as follows:

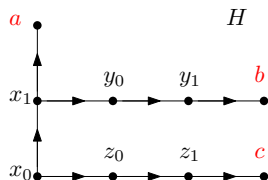
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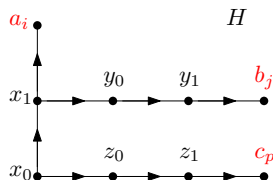
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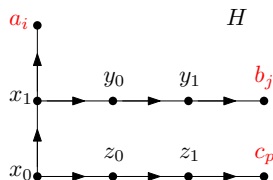
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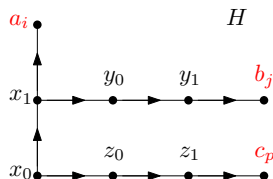


We add a new vertex s (source) and a vertex t (sink) that we connect to every other vertex. They will be the **endpoints** of the desired spindle.

Reduction for $\ell = 4$

For $i \in [n]$, we add to G three vertices a_i, b_i, c_i (elements of sets A, B, C).

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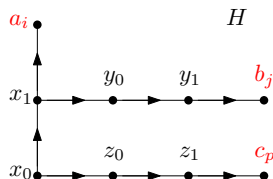


Claim (A, B, C, \mathcal{T}) is a YES-instance of 3-DIM. MATCHING \iff
 G contains a subdivision of a $(n + 2m \times 4)$ -spindle.

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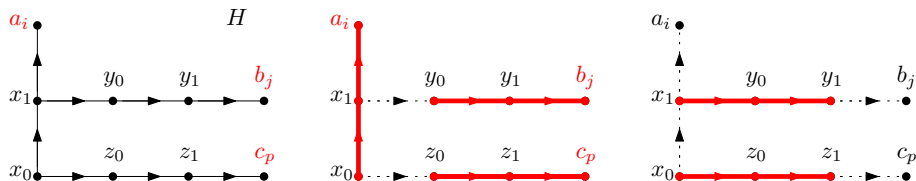


By construction of G , a $(n + 2m \times 4)$ -spindle **covers all $V(G)$** , so it is equivalent to **partitioning $G \setminus \{s, t\}$** into **2-paths** (paths with 2 arcs).

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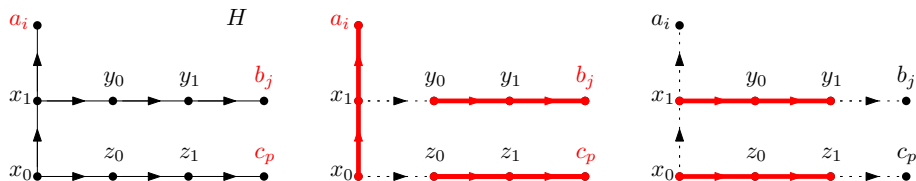


Key property: for every copy of H , there are **exactly two ways** the 2-paths can intersect H . This defines whether each triple $T \in \mathcal{T}$ is **chosen or not**.

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Modification for $\ell > 4$: we define the digraph G in the same way, except that we **subdivide the arcs outgoing from s** exactly $\ell - 4$ times.

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Cases that can be solved in polynomial time

MAX $(\bullet \times \ell)$ -SPINDLE SUBDIVISION

For a fixed $\ell \geq 1$, given an input digraph G , find the largest k such that G contains a subdivision of a $(k \times \ell)$ -spindle.

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Let $\ell \geq 1$ be fixed. MAX $(\bullet \times \ell)$ -SPINDLE SUBDIVISION is in P if $\ell \leq 3$, and NP-hard if $\ell \geq 4$, even restricted to DAGs.

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- $\ell = 1$: can be solved by a flow algorithm.
- $\ell = 2$: guess two vertices, delete arcs between them, and then flow.
- $\ell = 3$: we reduce the problem to computing a maximum matching in an auxiliary undirected graph, as follows...

Idea of the case $\ell = 3$

A **directed path** P is **nontrivial** if its endpoints are distinct.

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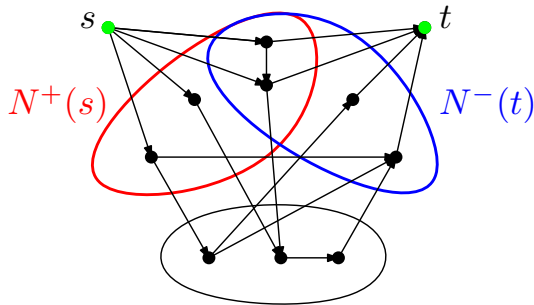
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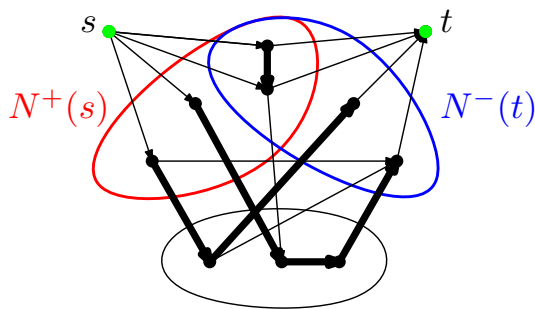


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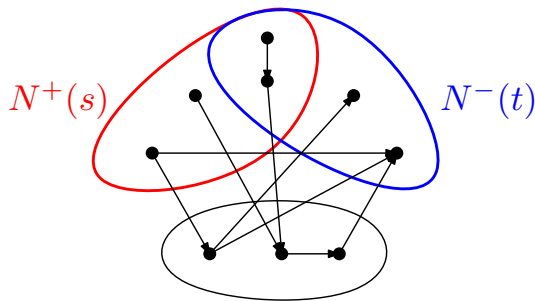


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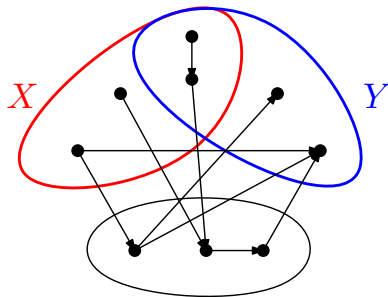


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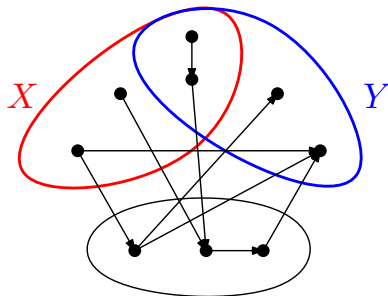
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Main ingredient for the case $\ell = 3$

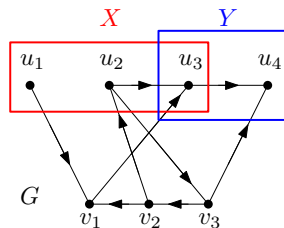
Proposition

Let G be a digraph and $X, Y \subseteq V(G)$. The *maximum number of vertex-disjoint directed nontrivial paths* from X to Y can be computed in *polynomial time*.



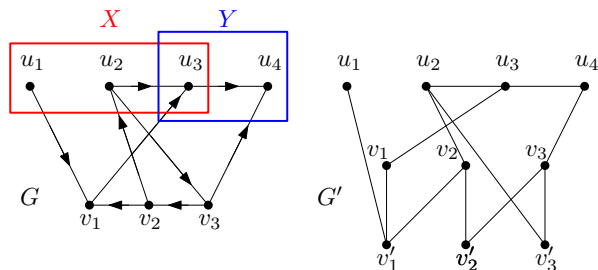
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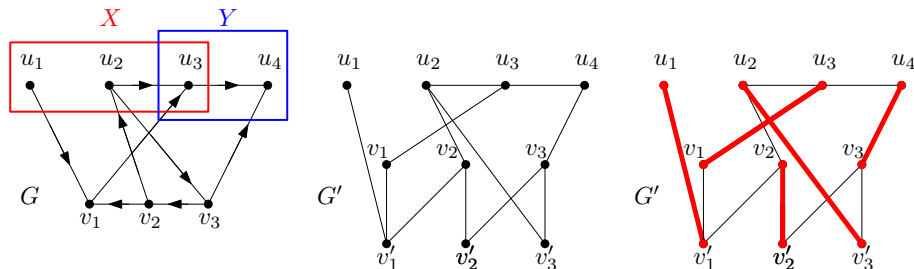
$V(G') = V(G) +$ a copy v' of each vertex $v \notin X \cup Y$.

$E(G')$: For each $v \notin X \cup Y$, add to G' the edge $\{v, v'\}$.

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Claim G contains k vertex-disjoint directed nontrivial paths from X to Y
 $\iff G'$ has a matching of size $k + |V(G) \setminus (X \cup Y)|$.

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Matroids

A pair $\mathcal{M} = (E, \mathcal{I})$, where E is a ground set and \mathcal{I} is a family of subsets of E , is a **matroid** if it satisfies the following three axioms:

- 1 $\emptyset \in \mathcal{I}$.
- 2 If $A' \subseteq A$ and $A \in \mathcal{I}$, then $A' \in \mathcal{I}$.
- 3 If $A, B \in \mathcal{I}$ and $|A| < |B|$, then $\exists e \in B \setminus A$ such that $A \cup \{e\} \in \mathcal{I}$.

The sets in \mathcal{I} are called the **independent sets** of the matroid.

Representative sets in matroids

Two independent sets A, B of \mathcal{M} **fit** if $A \cap B = \emptyset$ and $A \cup B$ is independent.

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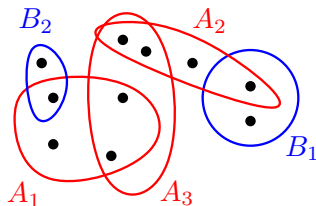
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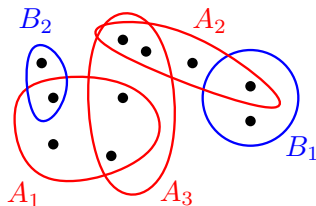


$$\mathcal{A} = \{A_1, A_2, A_3\}, \quad p = 4, q = 2$$
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We consider the **uniform matroid** with ground set $V(G)$ and rank $\ell + q$, with $0 \leq q \leq 2\ell$.

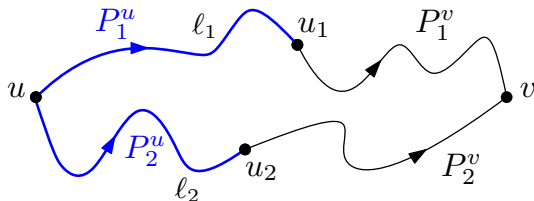
Finding a 2-spindle of large total size

If a subdigraph S of G is a subdivision of a (ℓ_1, ℓ_2) -spindle, with $\min\{\ell_1, \ell_2\} \geq 1$ and $\ell_1 + \ell_2 = \ell$, we say that S is a **good spindle**.

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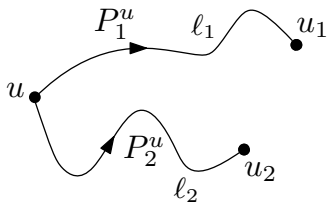
Idea We will **q -represent** the “first part” of the desired spindle (paths P_u^1 and P_u^2), for every $u, u_1, u_2 \in V(G)$, $\ell_1, \ell_2 \leq \ell$, and $0 \leq q \leq 2\ell$.



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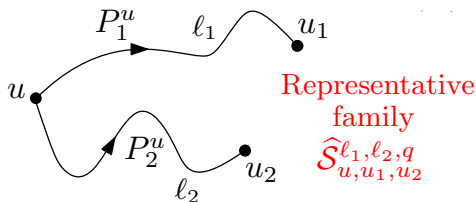
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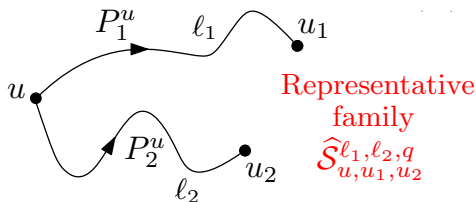
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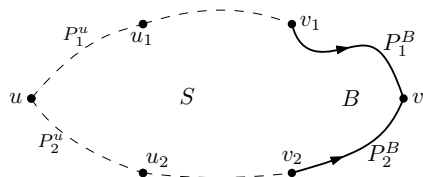


Using the recent techniques of [Fomin, Lokshtanov, Panolan, Saurabh. 2016], $|\hat{\mathcal{S}}_{u,u_1,u_2}^{\ell_1,\ell_2,q}| = 2^{O(\ell)}$ and can be computed in **time $2^{O(\ell)} \cdot n^{O(1)}$** .

Key property: these families indeed represent the solutions

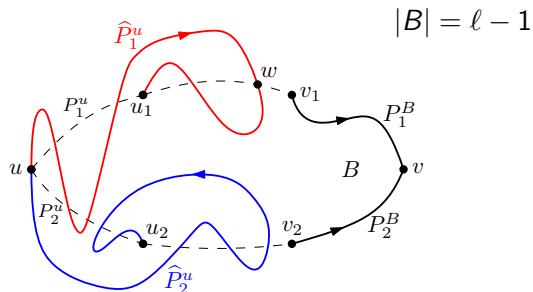
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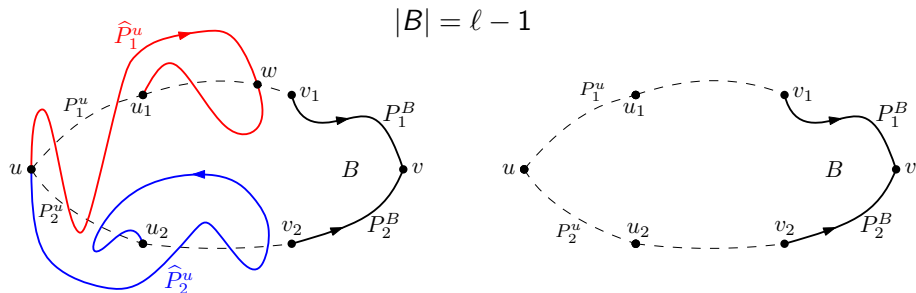
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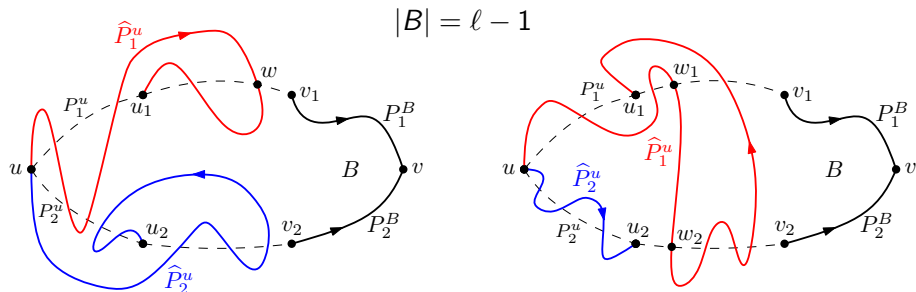
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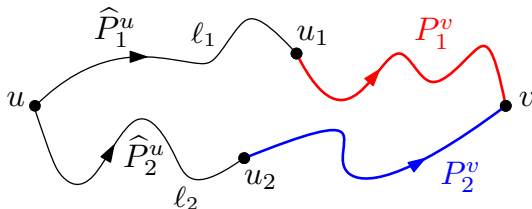
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Wrapping up the algorithm

- 1 For every $u, u_1, u_2 \in V(G)$, $\ell_1, \ell_2 \leq \ell$, and $0 \leq q \leq 2\ell$, we compute a q -representative family $\hat{S}_{u, u_1, u_2}^{\ell_1, \ell_2, q}$ in time $2^{O(\ell)} \cdot n^{O(1)}$.

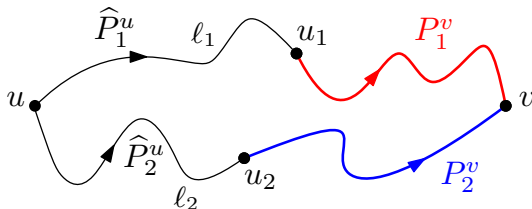
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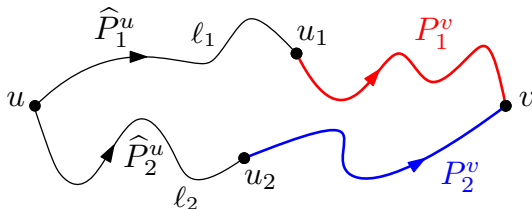
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Overall running time: $2^{O(\ell)} \cdot n^{O(1)}$.

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