

Orientations of Simplices Determined by Orderings on the Coordinates of their Vertices

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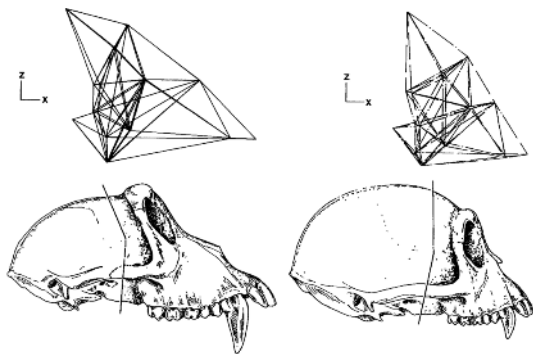
CCCG 2011



Research supported by the OMSMO (Oriented Matroids for Shape MOdeling) Project and the TEOMATRO Grant ANR-10-BLAN-0207

Motivation

Study of the **3D shape** of anatomical structures.



Applications:

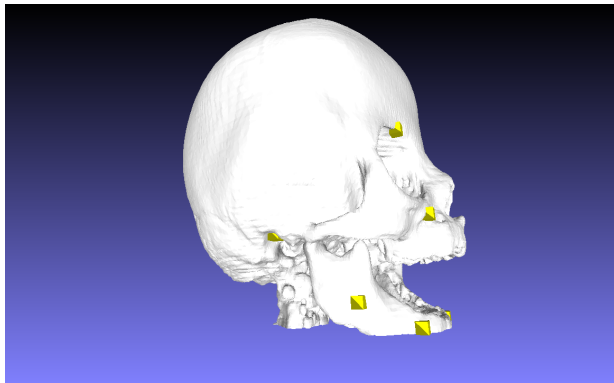
Anatomy, anthropology, paleontology, medicine

Motivation

- The expert defines 3D landmark points based on anatomical knowledge

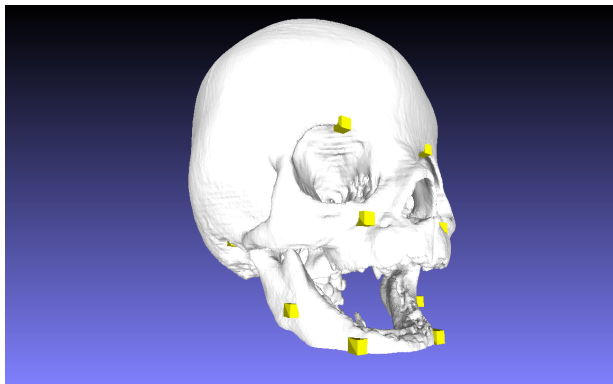
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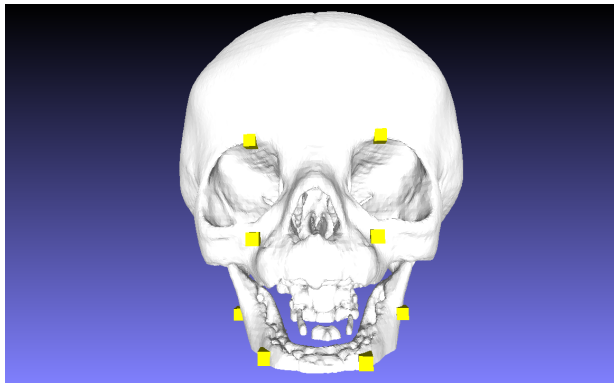
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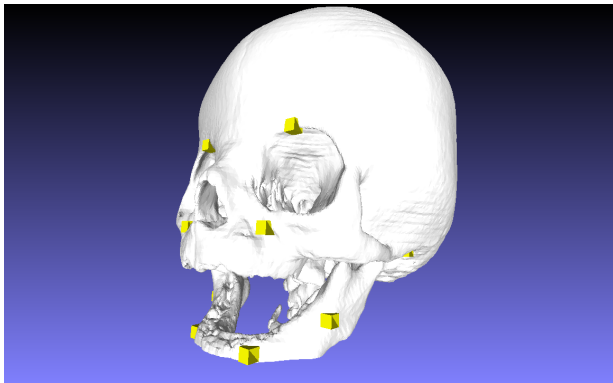
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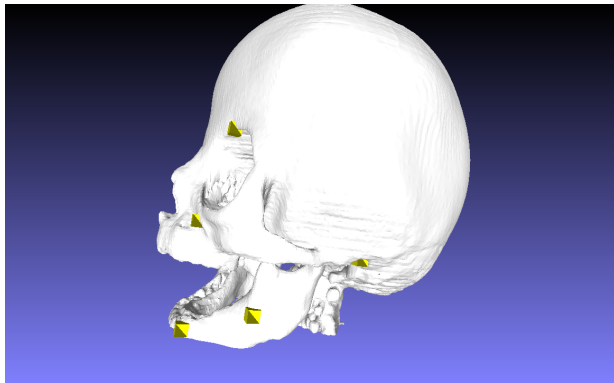
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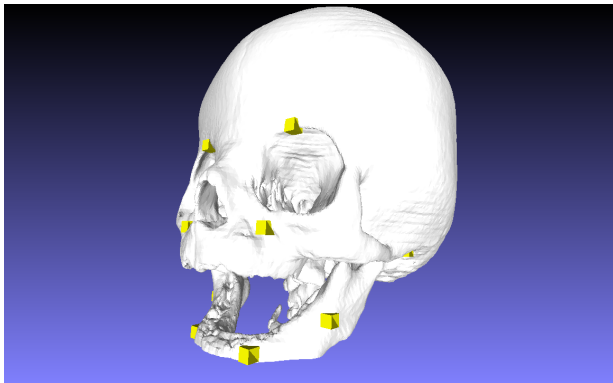
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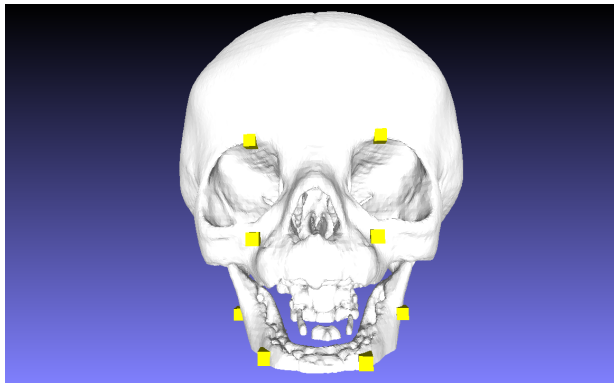
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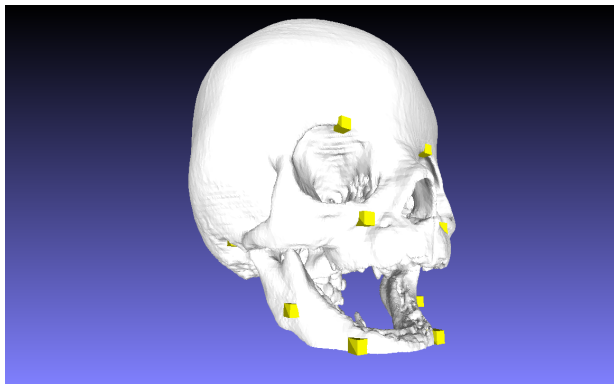
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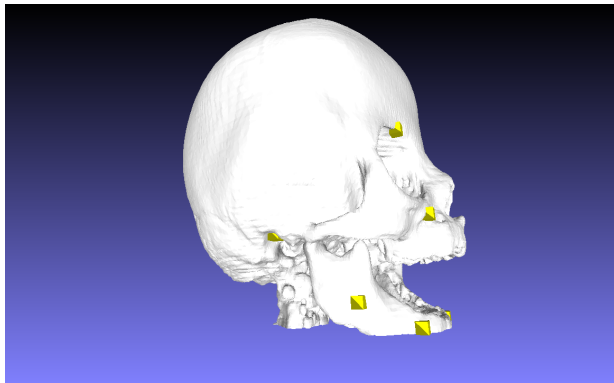
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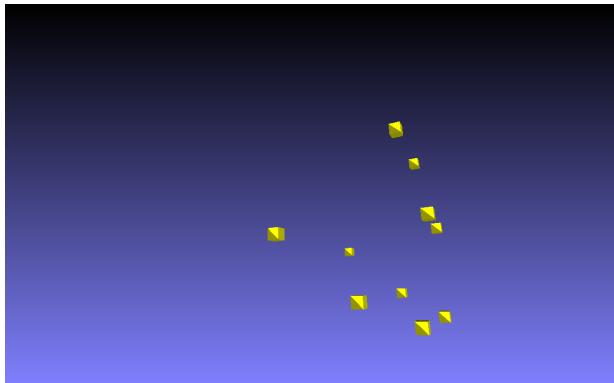
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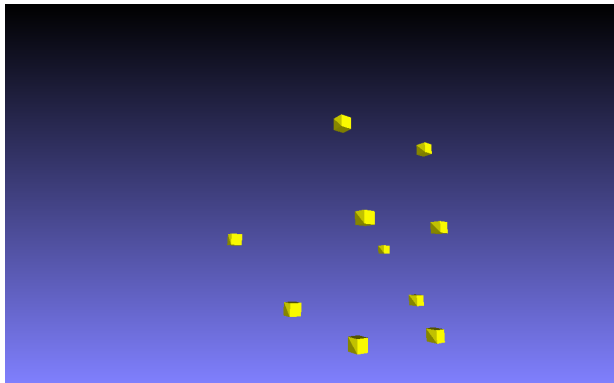
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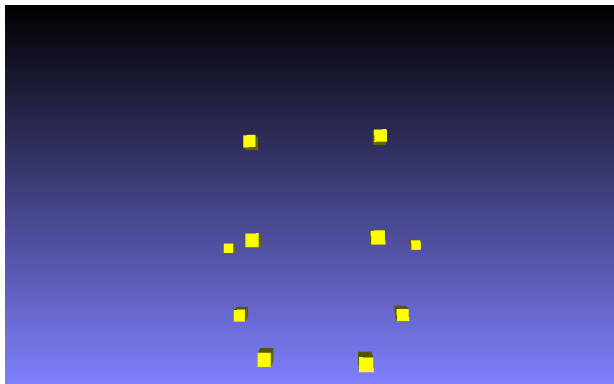
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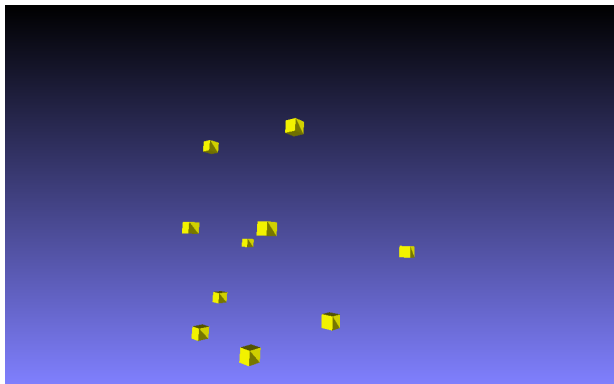
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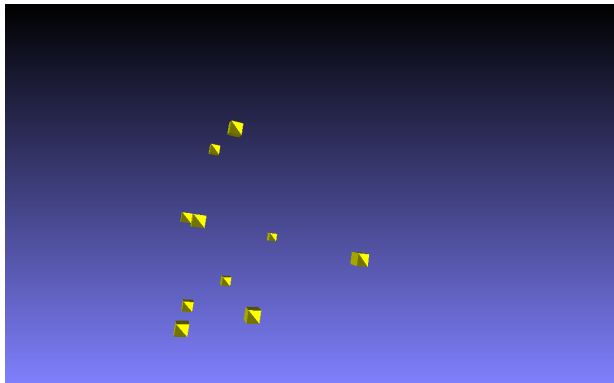
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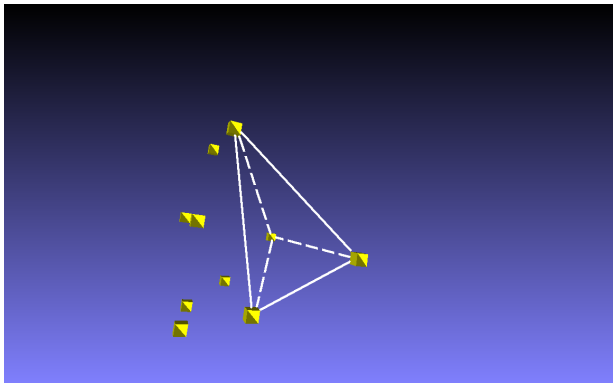
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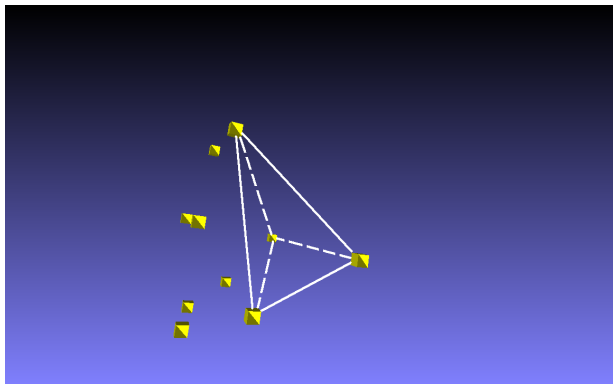
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- We encode the shape of the anatomical structure with the orientation of all quadruplets of points.

Motivation

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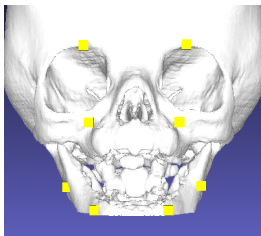


- We encode the shape of the anatomical structure with the orientation of all quadruplets of points.

⇒ combinatorial study of 3D anatomical structures

The problem

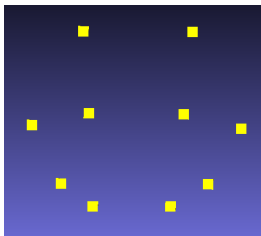
But for an anatomical structure, we can define ordering relations between the coordinates of the points;



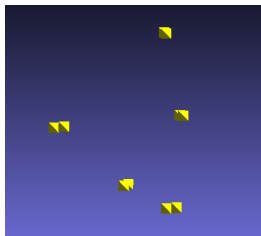
View from the front

The problem

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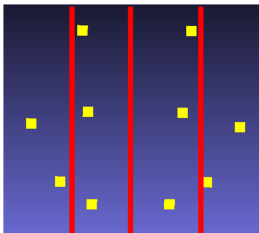
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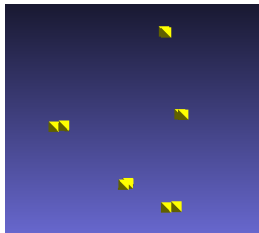
View from the right

The problem

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Some points are to the left of others



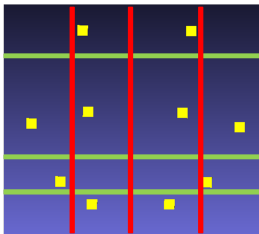
View from the front



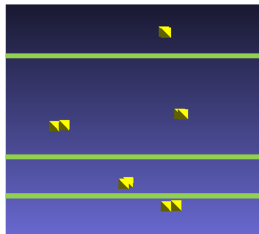
View from the right

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Some points are on top of others



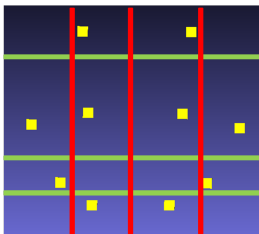
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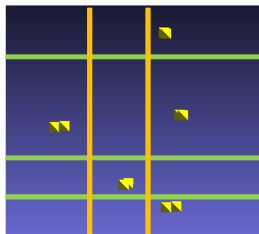
View from the right

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Some points are in front of others



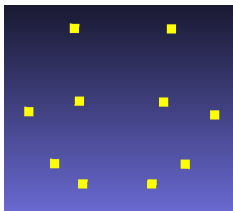
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View from the right

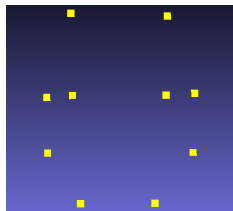
The problem

Landmark point positions change due to morphological variability or differences...



Skull 1

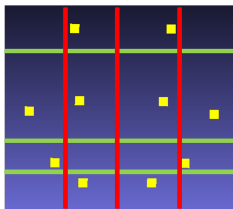
...



Skull k

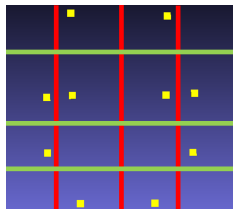
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Skull 1

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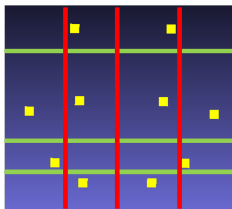


Skull k

but they still respect the orderings.

The problem

Landmark point positions change due to morphological variability or differences...



Skull 1

...



Skull k

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Question

Can we determine quadruplets of points whose orientation depend **only on the orderings** (i.e. independently of the coordinate values)?

Orientation of a simplex

Definition

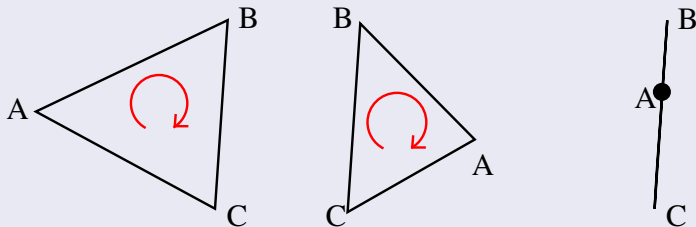
The orientation of a simplex ($\in \{+, -, 0\}$):

Orientation of a simplex

Definition

The orientation of a simplex ($\in \{+, -, 0\}$):

Triplet (A, B, C) :

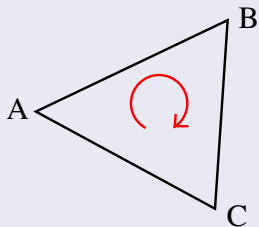


Orientation of a simplex

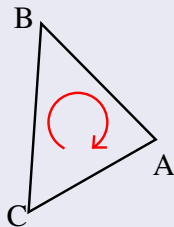
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Triplet (A, B, C) :



+



-



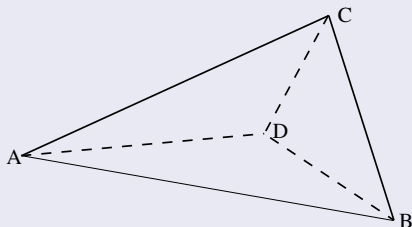
0

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Quadruplet (A, B, C, D) :

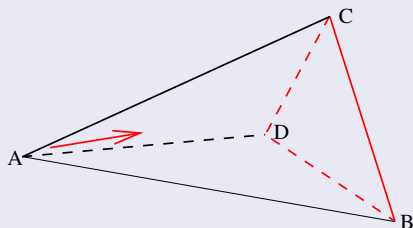


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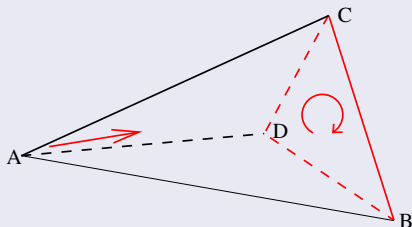
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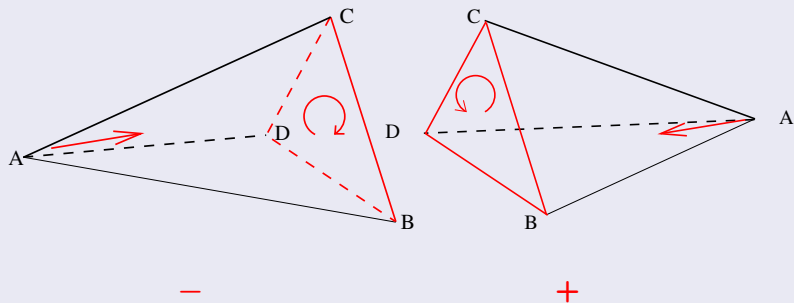
Orientation of the triplet (B, C, D)

Orientation of a simplex

Definition

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Orientation of a simplex

Definition

The orientation of a simplex ($\in \{+, -, 0\}$):

Orientations of simplices = chirotopes of an oriented matroid

Formalism

Notations

- M : a formal matrix

$$M = \begin{pmatrix} 1 & 1 & \dots & 1 \\ x_{1,1} & x_{2,1} & \dots & x_{n,1} \\ x_{1,2} & x_{2,2} & \dots & x_{n,2} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1,n-1} & x_{2,n-1} & \dots & x_{n,n-1} \end{pmatrix}$$

where $x_{j,i}$ is a formal variable

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Formalism

Notations

- M : a formal matrix
- \mathcal{P} : a set of n points P_j in a space of dimension $n - 1$
- Assigns M with $P_{j,i}$ (i -th coordinate of the point P_j)

$$M_{\mathcal{P}} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ P_{1,1} & P_{2,1} & \dots & P_{n,1} \\ P_{1,2} & P_{2,2} & \dots & P_{n,2} \\ \vdots & \vdots & \ddots & \vdots \\ P_{1,n-1} & P_{2,n-1} & \dots & P_{n,n-1} \end{pmatrix}$$

Orientation of \mathcal{P} = sign of $\det(M_{\mathcal{P}})$

Formalism

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- M : a formal matrix
- \mathcal{P} : a set of n points P_j in a space of dimension $n - 1$
- the real matrix $M_{\mathcal{P}}$

Orientation of \mathcal{P} = sign of $\det(M_{\mathcal{P}})$

Remark

Orientation of $\mathcal{P} = 0 \iff \mathcal{P}$ is contained in an hyperplane

Configuration of orderings

Definition

We call *configuration of $n - 1$ orderings on \mathcal{E}* , a set \mathcal{C} of $n - 1$ orderings on a set \mathcal{E} of size n .

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Example: a configuration \mathcal{C} of 3 orderings in $\{A, B, C, D\}$

$$\begin{array}{c}
 A <_x B <_x C <_x D \\
 B <_y D <_y C \quad \text{and} \quad B <_y A <_y C \\
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A set of points \mathcal{P} satisfies \mathcal{C} if

$$\forall i \in \{1, \dots, n-1\}, \forall e, f \in \mathcal{E}, \quad e <_i f \implies x_{e,i} < x_{f,i}$$

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$\mathcal{P} = \{P_1(0, 4, 3); P_2(2, 2, 3); P_3(3, 5, 0); P_4(5, 3, 1)\}$ satisfies \mathcal{C} :

$$\begin{array}{l} x(P_1) < x(P_2) < x(P_3) < x(P_4) \\ y(P_2) < y(P_4) < y(P_3) \quad \text{and} \quad y(P_2) < y(P_1) < y(P_3) \\ z(P_4) < z(P_1) \end{array}$$

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\mathcal{C} is *fixed* if for all \mathcal{P} satisfying \mathcal{C} , \mathcal{P} has always the same orientation.

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$$x_A = x_B$$



Fixed configuration

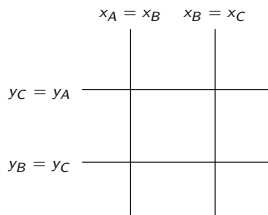
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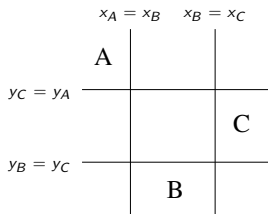
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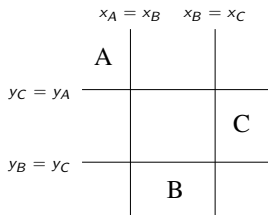
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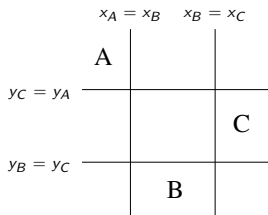
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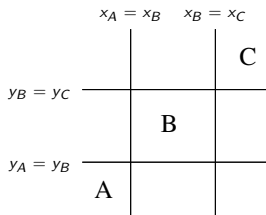
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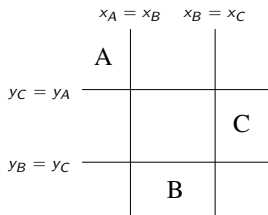
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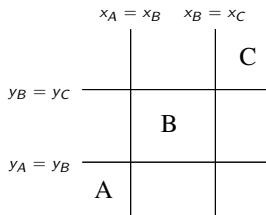
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non-fixed configuration

Equivalence

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Two configurations of $n - 1$ orderings are *equivalent* if they are equal up to a relabelling of \mathcal{E} , a permutation of orderings, and reversion(s) of orderings.

Equivalence

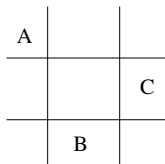
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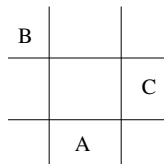
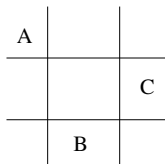
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a relabelling of \mathcal{E}

$$\begin{aligned} B <_x A <_x C \\ A <_y C <_y B \end{aligned}$$



Equivalence

Definition

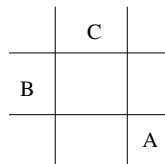
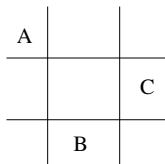
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a permutation of
orderings

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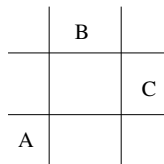
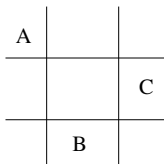
$$A <_x B <_x C$$

$$B <_y C <_y A$$

a reversion of an
ordering

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Sign of $\det(M)$: $\sigma_{\mathcal{C}}(\det(M))$

Definition

The *sign of $\det(M)$ w.r.t. \mathcal{C}* , denoted $\sigma_{\mathcal{C}}(\det(M))$, belongs to $\{\boxed{+}, \boxed{-}, \boxed{\pm}\}$:

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- if \mathcal{C} is **non-fixed**: there exist \mathcal{P}_1 and \mathcal{P}_2 satisfying \mathcal{C} such that $\det(M_{\mathcal{P}_1}) < 0$ and $\det(M_{\mathcal{P}_2}) > 0$.

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The problem (rewording)

Question (reminder)

Can we determine quadruplets of points whose orientation depend **only on the orderings** (i.e. independently of the coordinate values)?

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Determine the fixity of the configurations (determine if they are fixed or non-fixed).

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The problem (rewording)

Determine the fixity of the configurations (determine if they are fixed or non-fixed).

The problem (rewording 2)

Does there exist \mathcal{P} satisfying \mathcal{C} such that $\det(M_{\mathcal{P}}) = 0$?

Linear extensions

Definition

A *linear extension* of a configuration \mathcal{C} is a configuration where each ordering of \mathcal{C} is replaced by one of its linear extensions.

Linear extensions

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Example:

$$\begin{array}{c}
 \mathcal{C} \\
 A <_x B <_x C <_x D \\
 B <_y D <_y C \quad \text{and} \quad B <_y A <_y C \\
 D <_z A
 \end{array}$$

a linear extension of \mathcal{C}

$$\begin{array}{c}
 A <_x B <_x C <_x D \\
 B <_y D <_y A <_y C \\
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 \end{array}$$

Linear extensions

Proposition 1

\mathcal{C} is non-fixed $\iff \exists$ a non-fixed linear extension of \mathcal{C} .

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\mathcal{C} is fixed \iff all linear extension of \mathcal{C} are fixed.

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Proposition 1 (rewording)

\mathcal{C} is fixed \iff all linear extension of \mathcal{C} are fixed.

\implies We will concentrate only on linear configurations.

Computing $\sigma_c(\det(M))$

Definition

When $\det(M)$ can be written as

$$" \det(M) = \sum \prod (x_{e,i} - x_{f,i}) "$$

it is called *an expression of $\det(M)$*

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$$\det(M) = \det \begin{pmatrix} 1 & 1 & 1 \\ x_A & x_B & x_C \\ y_A & y_B & y_C \end{pmatrix}$$

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The *sign* $x_{e,i} - x_{f,i}$ w.r.t. \mathcal{C} , denoted $\sigma_{\mathcal{C}}(x_{e,i} - x_{f,i})$, belongs to

$\{\boxed{+}, \boxed{-}\}$ such that:

$$\sigma_{\mathcal{C}}(x_{e,i} - x_{f,i}) = \boxed{+} \text{ if } f <_i e \text{ in } \mathcal{C};$$

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Definition

The *sign of an expression of $\det(M)$* w.r.t. \mathcal{C} is

- $\boxed{+}$ or $\boxed{-}$ if it can be calculated
- $\boxed{?}$ if not

Computing $\sigma_{\mathcal{C}}(\det(M))$

Observation 1

If $\det(M)$ has such an expression whose sign is $\boxed{+}$ or $\boxed{-}$, then \mathcal{C} is fixed.

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If $\det(M)$ has such an expression whose sign is $\boxed{+}$ or $\boxed{-}$, then C is fixed.

Example:

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$\boxed{+}$

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$$\quad \quad \boxed{+} \quad \quad \quad \boxed{+}$$

we can not directly conclude

Key theorem / conjecture 1

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If $\det(M)$ has such an expression whose sign is $\boxed{+}$ or $\boxed{-}$, then \mathcal{C} is fixed.

Theorem / Conjecture 1

\mathcal{C} is fixed if and only if $\det(M)$ has an expression whose sign is $\boxed{+}$ or $\boxed{-}$.

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proved in dimension 2 and 3 ($n = 3$ and 4)

conjecture in higher dimensions

Characterization in dimension 2

Theorems 1 and 2

Up to equivalence, there are exactly two configurations of 2 orderings

$$A <_x B <_x C$$

$$A <_y C <_y B$$

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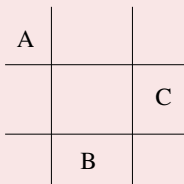
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Characterization in dimension 2

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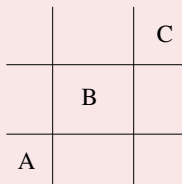
Up to equivalence, there are exactly two configurations of 2 orderings

$$\begin{aligned} A <_x B <_x C \\ A <_y C <_y B \end{aligned}$$



fixed configuration

$$\begin{aligned} A <_x B <_x C \\ A <_y B <_y C \end{aligned}$$



non-fixed configuration

Characterization of the fixed configurations in 3D

Theorem 3: fixed configurations

The following are equivalent:

- \mathcal{C} is fixed
- the sign of an expression of $(\det(M)) \in \{\boxed{+}, \boxed{-}\}$
- ① up to equivalence, \mathcal{C} satisfies

$$\begin{aligned} B <_x C <_x A \\ C <_y A <_y B \\ A <_z B <_z C \end{aligned}$$

and

- ② $\exists X \in \{A, B, C\}$ such that we have either
 - $X < D$ in all the orderings
 - or
 - $X > D$ in all the orderings

Fixed configurations in 3D

Up to equivalence, there are exactly 4 fixed configurations:

$$\begin{aligned} B <_x C <_x A <_x D \\ C <_y A <_y B <_y D \\ A <_z B <_z C <_z D \end{aligned}$$

$$\begin{aligned} B <_x C <_x D <_x A \\ C <_y A <_y B <_y D \\ A <_z B <_z C <_z D \end{aligned}$$

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An other characterization in 3D

 \mathcal{C}

$$B <_x D <_x C <_x A$$

$$C <_y A <_y B <_y D$$

$$A <_z B <_z D <_z C$$

a configuration induced by \mathcal{C}
w.r.t. the ordering $<_y$

$$D <_x C <_x A$$

$$A <_z D <_z C$$

An other characterization in 3D

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Theorem 4: non-fixed configurations

Let \mathcal{C}' be a configuration induced by \mathcal{C} on \mathcal{E}' w.r.t. $<_j$. Let $P \in \mathcal{E} \setminus \mathcal{E}'$.

\mathcal{C} is non-fixed if and only if

- \mathcal{C}' is non-fixed and
- P is extreme in the ordering $<_j$ of \mathcal{C} ,

An other characterization in 3D

Theorem 4: non-fixed configurations

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Example:

$$C <_x D <_x A <_x B$$

$$A <_y C <_y B <_y D$$

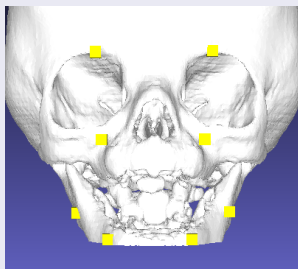
$$A <_z B <_z C <_z D$$

non-fixed configuration induced by \mathcal{C}
 extreme point

Experimentation

In this example

Set of skulls for morphometrical analysis of craniofacial morphology (dental classes)

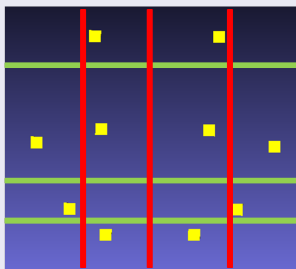


- 10 points 3D

Experimentation

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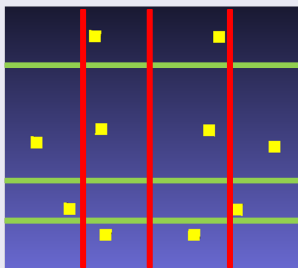


- 10 points 3D
- 210 configurations
- 8,112 linear extensions

Experimentation

In this example

Set of skulls for morphometrical analysis of craniofacial morphology (dental classes)

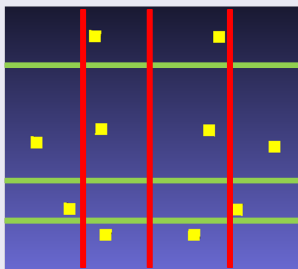


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- Software in C, very fast (450 ms)
- \implies 20 fixed configurations

Experimentation

In this example

Set of skulls for morphometrical analysis of craniofacial morphology (dental classes)



- 10 points 3D
- 210 configurations
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- Software in C, very fast (450 ms)
- \implies 20 fixed configurations

Goal

Find the quadruplets of points which characterize significantly the morphological differences.

Conjecture

Theorem / Conjecture 1

\mathcal{C} is fixed if and only if $\det(M)$ has an expression whose sign is
or .

proved in dimension 2 and 3 ($n = 3$ and 4)

conjecture in higher dimensions

Conjecture

Theorem / Conjecture 1

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or $\boxed{-}$.

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Thanks!