MAGPIE TUTORIAL

First steps with gem5

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Roadmap

- Requirements for this tutorial
- Preparing gem5 to simulate an application
 - Operating system configuration
 - Application compilation
 - Hard drive (disk image) preparation
- Automate the application execution
 - Shell scripts
- Accelerate execution with checkpoints

REQUIREMENTS FOR THIS TUTORIAL

3

Connection to the remote server

- Open 2 terminals
- Connection to the remote server in each terminal

\$ ssh etu-f_compas2017-XX@muse-login.hpc-lr.univ-montp2.fr

• MAGPIE configuration in one terminal only:

\$ source \$HOME/work/env.sh # Could takes few seconds
\$ python --version (returns Python 2.7.12)

gem5 pre-setup

 For those who are on their laptop with administrative rights, download a script at this URL:

https://frama.link/compas17_nfs

- Install the following package: sshfs
- Execute this script on your own machine
 - Requires administrative rights to mount remote filesystem (enter your remote access password 3 times)

GEM5 SETUP

6

Operating system configuration

- gem5 needs a compiled kernel and a disk image with full operating system stuff
- Default kernels are provided in \$M5_PATH/binaries
 - 32 bits:vexpress.aarch32.ll_20131205.0-gem5
 - 64 bits : vexpress.aarch64.20140821
- Disk image with complete Ubuntu system are also given in \$M5_PATH/disks
 - Ubuntu 11.04 32 bits: aarch32-ubuntu-natty-headless.img
 - Ubuntu 14.04 64 bits: aarch64-ubuntu-trusty-headless.img

Operating system configuration

- Linux also needs a DTB file (Device Tree Blob/Binary)
- Contains hardware information required by Linux
 - Number of CPUs, frequency, DVFS information
 - Level of caches, size, line size
 - Bus frequency
 - Address range for devices

• . . .

- Located in \$M5_PATH/binaries
 - Ex: vexpress.aarch32.11_20131205.0-gem5.1cpu.dtb

Application cross-compilation

- MAGPIE is designed to work with ARM Instruction Set Architecture (ISA)
 - Could be extended though
- Our machines are (mostly) x86
- We need a cross-compilation: generate ARM assembly from another ISA (i.e., x86)

Application cross-compilation

- Cross-compiler available on remote machine (32-bits)
- \$ arm-unknown-linux-gnueabi-gcc --version
 - Note: this compiler is for ARM 32-bits only
- Replace gcc by this one to produce ARM 32-bits executables
- Always compile with -static flag
 - This gem5 version doesn't support dynamic linking

Application cross-compilation

- Example: \$MAGPIE/app/hello_magpie.c
- \$ arm-unknown-linux-gnueabi-gcc -static -o \$HOME/app/hello_magpie \$MAGPIE/app/hello_magpie.c

Verification

\$ file \$HOME/app/hello_magpie
ELF 32-bit LSB executable, ARM, EABI5 version 1
(SYSV), statically linked, for GNU/Linux 3.12.72,
not stripped

• This is also available on your <u>local machine</u> in /tmp/app

Disk image modification

- Disk images are just ISO file : we can mount, read and write into them
- The following commands require administrative rights
 - That won't work on this server
- We are just showing you how to proceed

Disk image modification

- For this tutorial we use this disk image: linuxaarch32-ael.img (32-bits)
 - Located in \$HOME/disks on the remote server

\$ ls \$HOME/disks
linux-aarch32-ael.img

Available on your <u>local machine</u> in /tmp/disks

\$ ls /tmp/disks
linux-aarch32-ael.img

This is the same file !

Disk image modification

- Mount the disk image:
- \$ sudo mount -o loop,offset=32256
 /path/to/linux-aarch32-ael.img /mnt
- Copy the executable inside:
- \$ sudo cp /path/to/hello_magpie /mnt/benchmark
- Finally, unmount and synchronize:
- \$ sudo umount /mnt && sudo sync

gem5 setup conclusion

- Operating system:
 - in \$M5_PATH/binaries
 - With DTB files
- Application is statically compiled for ARM-32 bits
- Disk image is in \$M5_PATH/disks
 - And \$HOME/disks
 - Application is copied to the disk image in /benchmark

AUTOMATE APPLICATION EXECUTION

Automate application execution

- gem5 provides an interface to execute commands inside the operating system: rcs files
- Shell script automatically executed after the boot phase
- Example in \$GEM5/configs/boot/hello.rcS

#!/bin/sh
echo "Hello World"
/sbin/m5 exit # Special instruction to exit gem5

Automate application execution

- Open a new file in \$HOME/app/hello_magpie.rcS
 - vi, vim, emacs or nano are installed
- Our hello_magpie application is located in /benchmark
- What would be the content of this file ?

```
#!/bin/sh
cd /benchmark  # Change directory
./hello_magpie  # Launch application
/sbin/m5 exit  # Special instruction to exit gem5
```

- This will be executed after booting
- The simulation will automatically exit when finished

USE CHECKPOINTS

What's a checkpoint ?

- Booting Linux in gem5 could be very long
 - ~30 minutes with 1 core & fine-grained simulation
 - One way to mitigate this: checkpoints
- Checkpoints are snapshots of the system state
 - Taken with coarse-grained simulation
 - Restore from checkpoint with high level of details



Taking a checkpoint

- Restrictions when taking checkpoint and restoring
 - Use the same amount of main memory
 - Use the same disk image
 - Use the same number of cores
- How to take a checkpoint for MAGPIE:



• Use your disk image if possible: \$HOME/disks/linuxaarch32-ael.img

Output folder !

Taking a checkpoint

```
• gem5's output:
```

```
gem5 Simulator System. http://gem5.org
[...]
**** REAL SIMULATION ****
[...]
Writing checkpoint
info: Entering event queue @ 2789663483500.
Starting simulation...
Exiting @ tick 2791525410000 because m5_exit
instruction encountered
```

• Checkpoint is located in \$CHKPT/chkpt-1core-2GB

```
$ ls $CHKPT/chkpt-1core-2GB
[...]
cpt.2789663483500
```

CONCLUSION

Conclusion

- Linux kernel is already compiled and ready
- Application has been cross-compiled for ARM-32
- Disk image has been modified and now contains our application
- The rcs file automates the execution of our application
- A checkpoint has been taken to accelerate the simulation