



4<sup>th</sup> Summer School on Parallel Kinematic Manipulators (PKM 2026)

**21-25 September 2026 – Montpellier, France**

**SCHEDULE**

	9:00 – 10:30 (1h30)	10:30 - 11:00	11:00-12.30 (1h30)	12:30 - 14:30	14:30 – 16:00 (1h30)	16:00 - 16:30	16:30 – 18:00 (1h30)	
Monday 21/09	Lecture 1 <b>Kinematics &amp; statics</b>	Coffee break	Lecture 2 <b>Kinematics &amp; singularity</b>	Lunch	Lecture 3 <b>CDPRs</b>	Coffee break	Project	
	Lecturer: <b>M. Carricato</b>		Speaker: <b>S. Caro</b>		Speaker: <b>M. Gouttefarde</b>		Simulation lab	
Tuesday 22/09	Lecture 4 <b>AI for Kinematics</b>	Coffee break	Lecture 5 <b>Design</b>	Lunch	Project	Coffee break	Project	
	Speaker: <b>J. P. Merlet</b>		Speaker: <b>O. Company</b>		Simulation lab		Simulation lab	
Wednesday 23/09	Lecture 6 <b>Continuum PKMs</b>	Coffee break	Lecture 7 <b>Control</b>	Lunch	Social Event		Lecture 8 <b>Industry</b>	Dinner
	Speaker: <b>S. Briot</b>		Speaker: <b>A. Chemori</b>				Speaker: <b>SYMETRIE</b>	
Thursday 24/09	Lecture 9 <b>Hybrid // Robots</b>	Coffee break	Lecture 10 <b>Type Synthesis</b>	Lunch	Project	Coffee break	Project	
	Speaker: <b>S. Kumar</b>		Speaker: <b>X. Kong</b>		Simulation lab		Simulation lab	
Friday 25/09	Lecture 11 <b>CDPR for Construction</b>	Coffee break	Lecture 12 <b>Dynamics</b>	Lunch & Farew ell recept ion				
	Speaker: <b>T. Bruckmann</b>		Speaker: <b>A. Müller</b>					

