# Program (updated on June 1st 2023)

								18:30 - 19:00
	BUS to Lazaret from							18:00 - 18:30
								17:30 - 18:00
	(M. Tavakoli)							17:00 - 17:30
				(E. Stindel)	Technical IV (T. Morimoto)	(L Dessi )	Lazaret Center	16:30 - 17:00
	Break (30')		& tree afternoon				at the	16:00 - 16:30
				Break (30")	Break (30°)	Sreak (30")		15:30 - 16:00
	Technical VIII (R. Taylor)							15:00 - 15:30
				Technical V IC Rivierel	100	Visual Servoing 2 (F. Nameothe)		14:30 - 15:00
	,	7.						14:00 - 14:30
	Lunch at Medical school							13:30 - 14:00
Lunch at Lazaret		Free day	Lunch at Lazaret	Lunch at Lazaret	Lunch at Lazaret	Lunchatlazaret		13:00 - 13:30
								12:30 - 13:00
<b>x</b> sion			1	(A. Menciassi)				12:00 - 12:30
Periodice and choice	sessions (during break)		(L. Lindenroth)	surgical robotics I	Technical III P. Jamini	Visual Servoing 1 (F. Nameoffie)		11:30 - 12:00
Break (60°) with poster	Industrial			Edward Sande				11:00 - 11:30
			Break [30"] with poster	Break (30") with poster	Break (30") with poster	Break (30°)		10:30 - 11:00
livings.			Poster Session teasing	Poster Session teasing	Poster Session teasing	Ir. De Monij		10:00 - 10:30
surgical robotics II	demonstrations					Surgical Robotics		9:30 - 10:00
Future trends in	WWW		M. de Bootray, P-E Chammas	8	Technical II (E. Vander Poorten)	introduction to		9:00 - 9:30
	BUS to Montpellier		Medical			(P. Poignet - N. Zemiti)		8130 - 9600
						Walness Talk		8:15 - 8:30
						Opening/registration		8:00 - 8:15
Tuesday Sept. 05	Monday Sept 04	Sunday Sept 03	Saturday Sept 02	Friday Sept 01	Thursday Aug. 31	Wendesday Aug. 30	Tuesday Aug. 29	

## Admission

The number of participants is restricted to 50. Priority will be given to Ph.D. students and Post-docs. However, a significant number of researchers and professionals, as well as students will be accepted.

Applicants must be registered by July 14<sup>th</sup>, 2023 (<a href="https://www.lirmm.fr/sssr-2023/register.html">https://www.lirmm.fr/sssr-2023/register.html</a>). A scientific committee will select the candidates. A letter of confirmation will be sent to accepted participants.

The lodging expenses and the meals will be supported by the organizers thanks to sponsor funding and completed by the registration fees of the participants. The travel will be at the participants' own expenses.



#### Contact

For further administrative information, please contact Virginie FECHE, LIRMM, <u>Virginie.Feche@lirmm.fr</u>
For further scientific information, please contact Philippe Poignet / Nabil Zemiti, LIRMM, <u>Philippe.Poignet@lirmm.fr</u> / <u>Nabil.Zemiti@lirmm.fr</u>













# 11th Summer School Surgical Robotics

August 30 - September 05, 2023 Montpellier (France)



Coordinated by
Philippe Poignet and Nabil Zemiti
LIRMM, CNRS – University of Montpellier
Isabelle Laffont and Astrid Herrero
Montpellier-Nîmes Medical School- University of
Montpellier, CHRU Montpellier

# http://www.lirmm.fr/sssr-2023

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Centre National de la Recherche Scientifique (CNRS) I-site MUSE - Université de Montpellier Ecole Doctorale I2S

# **Surgical robotics**

Robotics enables surgery to be less invasive and/or to enhance the performance of the surgeon. In minimally invasive surgery (MIS) for instance, robotics can improve the dexterity of conventional instruments, which is restricted by the insertion ports, by adding intra-cavity degrees of freedom. It can also provide the surgeon with augmented visual and haptic inputs. In open surgery, robotics makes it possible to use in real time pre-operative and per-operative image data to improve precision and reproducibility when cutting, drilling, milling bones, to locate accurately and remove tumours. In both cases, as in other surgical specialities, robotics allows the surgeon to perform more precise, reproducible and dextrous motion. It is also a promising solution to minimize his/her fatigue and to restrict his/her exposition to radiation. For the patient, robotics surgery may result in less risk, pain and discomfort, as well as a shorter recovery time. These benefits explain the increasing research efforts made all over the world since the early 90's.

Surgical robotics requires great skills in many engineering fields as the integration of robots in the operating room is technically difficult. It induces new problems such as safety, man-machine cooperation, real time sensing and processing, mechanical design, force and vision-based control... However, it is very promising as a mean to improve conventional surgical procedures, for example in neurosurgery and orthopedics, as well as providing innovative new ones in micro-surgery, image-guided therapy, MIS and Natural Orifice Transluminal Endoscopic Surgery (NOTES).

The highly interdisciplinary nature of surgical robotics requires close cooperation between medical staff and researchers in mechanics, computer sciences, control and electrical engineering. This cooperation has resulted in many prototypes for a wide variety of surgical procedures. A few robotics systems are yet available on a commercial basis and have entered the operating room namely in neurosurgery, orthopedics and MIS.

Depending on the application, surgical robotics gets more or less deeply into the following fields: multi-modal information processing; modelling of rigid and deformable anatomical parts; pre-surgical planning and simulation of robotic surgery; design and control of guiding systems for assistance of the surgeon gesture. During the Summer school, these fields will be addressed by surgeons and researchers working in leading hospitals and labs. They will be completed by engineers who will give insight into practical integration problems.

These courses are addressed to PhD students, post-docs and researchers already involved in the area or interested by the new challenges of such an emerging area interconnecting technology and surgery. Basic background in mechanical, computer science, control and electrical engineering is recommended. This Summer School follows eight previous editions held in Montpellier on a biennial basis since 2003.

#### Content

The lectures will be organized in four parts:

- Fundamental aspects of surgical robotics (2 days): medical imaging, modelling, control, design and safety, planning and registration, haptics;
- Applications (2 days): technical point of view (from design to experiment), and surgical point of view (orthopedics, urology, abdominal surgery, ENT);
- Industrial forum & clinical hands-on session (1/2 day) with exhibition of equipments, presentations of applications, and demonstrations; visit of the LIRMM facilities; clinical hands-on and serious game, ...
- Future trends (1/2 day): perspectives in small size robots and mechatronic devices for surgery and therapy; perspectives in NOTES.

Time will be reserved for the participants to present their own research work.

## **Invited lecturers**

Chosen among the most well-known experts worldwide, the lecturers have a significant theoretical and practical background in Surgical Robotics. They represent the clinical, scientific and engineering communities:

Marie de Boutray, CHU-LIRMM, Montpellier, France Pierre-Emmanuel Chammas, CHU-LIRMM, Montpellier, France

**Elena De Momi**, Politecnico di Milano, Milan, Italy **Jaydev Desai**, Georgia Tech, Atlanta, USA **Christian Duriez**, INRIA, Villeneuve d'Ascq, France

Paolo Fiorini, University of Verona, Italy Jean-Pierre Henry STAN Institute, Nancy, France Astrid Herrero, CHU-Medical School, Montpellier, France Pierre Jannin, LTSI, Rennes, France Lukas Lindenroth, King's College London, UK Arianna Menciassi, Scuola Superiore Sant'Anna, Pisa, Italy Tania Morimoto, University of California, San Diego, USA Florent Nageotte, ICube, Strasbourg, France Philippe Poignet, LIRMM, Montpellier, France Pierre Renaud, ICube, Strasbourg, France Cameron Riviere, Carnegie Mellon University, USA Eric Stindel, CHU-LATIM, Brest, France Mahdi Tavakoli, University of Alberta, Canada Russ Taylor, John Hopkins University, Baltimore, USA Emmanuel Vander Poorten, KU Leuven, Belgium Nabil Zemiti, LIRMM, Montpellier, France

#### **Lectures and school materials**

All lectures will be given in English. The lecturers' slides will be available online at the time of the class. All the School material (including slides of students' presentations) will be available by the end of September on the website of the Summer School together with significant papers of the lecturers as well as videos.

## **ECTS**

The 32-hour courses of the Summer School will be accredited by the *Doctoral School on Information, Systems and Structure* (I2S) of the University of Montpellier (a *Doctoral School* in the French Universities manages the Ph.D. degree). 5 ECTS credit points will be awarded to student attendees.

## Accommodation

The lectures will be given at the "Lazaret", which is located at Sète (seaside resort near Montpellier) (www.lirmm.fr/sssr-2023/venue.html). The attendees will be sharing apartments for two to three persons.

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