

# Extending the Range of Temporal Specifications of the Run-Time Event Calculus

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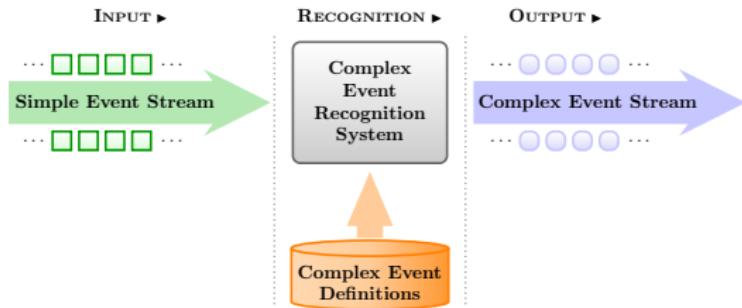
<sup>2</sup>National and Kapodistrian University of Athens, Greece

<sup>3</sup>University of Piraeus, Greece

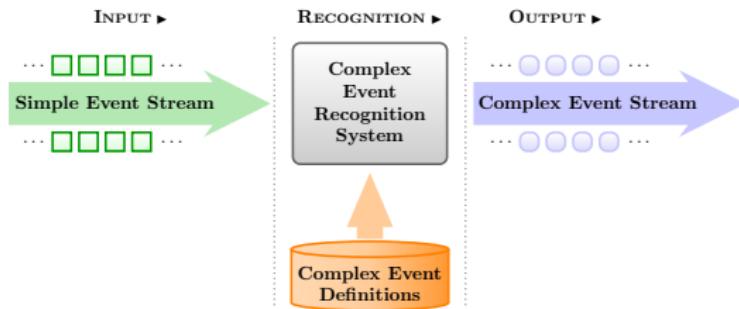
<http://cer.iit.demokritos.gr/>



# Composite Event Recognition



# Composite Event Recognition



<https://cer.iit.demokritos.gr> (activity recognition)

# Event Calculus

- ▶ A logic programming language for representing and reasoning about events and their effects.
- ▶ Key components:
  - ▶ event (typically instantaneous).
  - ▶ fluent: a property that may have different values at different points in time.

## Event Calculus

- ▶ A logic programming language for representing and reasoning about events and their effects.
- ▶ Key components:
  - ▶ event (typically instantaneous).
  - ▶ fluent: a property that may have different values at different points in time.
- ▶ Built-in representation of inertia:
  - ▶  $F = V$  holds at a particular time-point if  $F = V$  has been *initiated* by an event at some earlier time-point, and not *terminated* by another event in the meantime.

# Run-Time Event Calculus (RTEC)

**initiatedAt**( $F = V$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{In_1}$ ,  $T$ )[,  
conditions].

...

**initiatedAt**( $F = V$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{In_i}$ ,  $T$ )[,  
conditions].

**terminatedAt**( $F = V$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{T_1}$ ,  $T$ )[,  
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...

**terminatedAt**( $F = V$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{T_j}$ ,  $T$ )[,  
conditions].

where

conditions:       ${}^{0-K} \mathbf{happensAt}(E_k, T),$   
                       ${}^{0-M} \mathbf{holdsAt}(F_m = V_m, T),$   
                       ${}^{0-N} \text{atemporal-constraint}_n$

## Activity Recognition

```
initiatedAt(interaction( $P_1, P_2$ )=greeting,  $T$ ) \leftarrow
happensAt(active( $P_1$ ),  $T$ ), happensAt(active( $P_2$ ),  $T$ ),
holdsAt(distance( $P_1, P_2$ )=mid,  $T$ ),
holdsAt(orientation( $P_1, P_2$ )=facing,  $T$ ).
```

## Activity Recognition

**initiatedAt**( $\text{interaction}(P_1, P_2) = \text{greeting}$ ,  $T$ )  $\leftarrow$   
**happensAt**( $\text{active}(P_1)$ ,  $T$ ), **happensAt**( $\text{active}(P_2)$ ,  $T$ ),  
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**terminatedAt**( $\text{interaction}(P_1, P_2) = \text{greeting}$ ,  $T$ )  $\leftarrow$   
**happensAt**( $\text{walking}(P_1)$ ,  $T$ ),  
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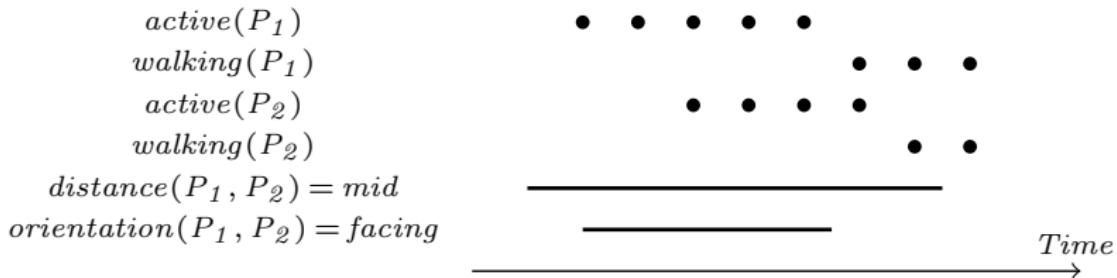
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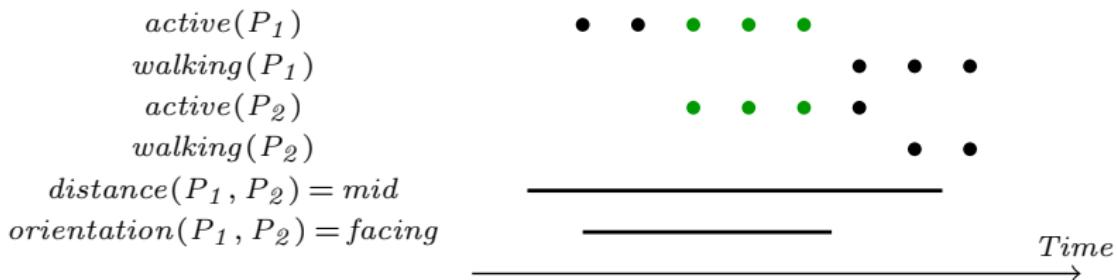


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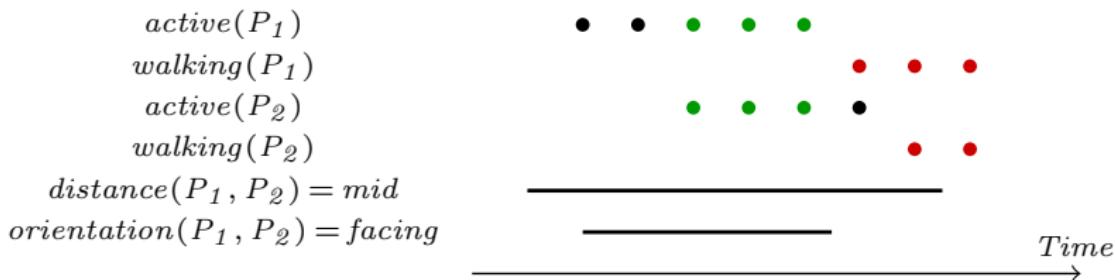


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$\text{interaction}(P_1, P_2) = \text{greeting}$

$\text{active}(P_1)$



$\text{walking}(P_1)$



$\text{active}(P_2)$



$\text{walking}(P_2)$



$\text{distance}(P_1, P_2) = \text{mid}$

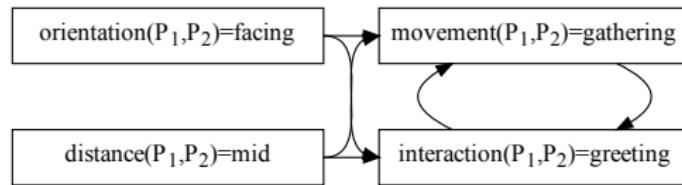


$\text{orientation}(P_1, P_2) = \text{facing}$

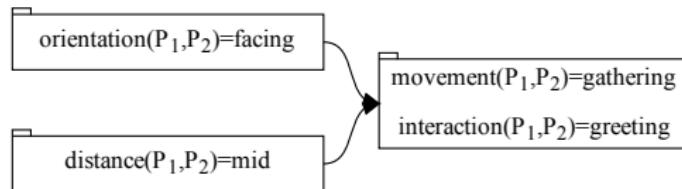
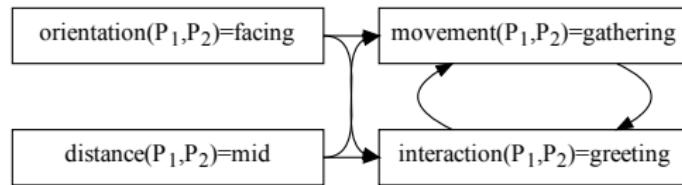


Time

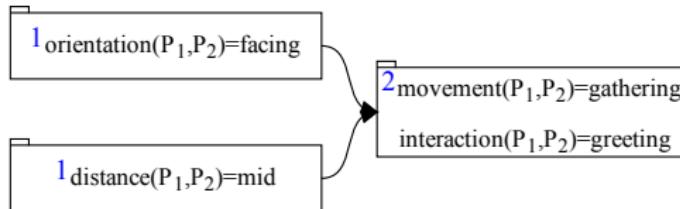
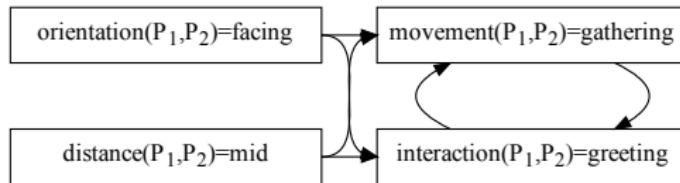
# Semantics



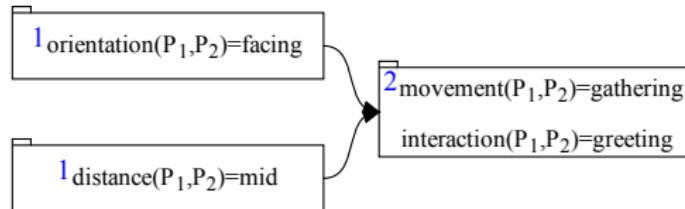
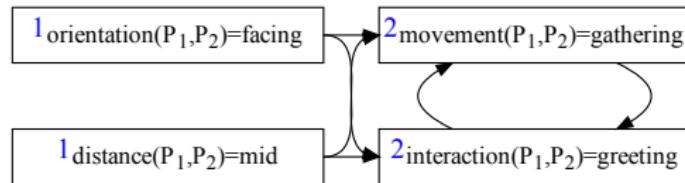
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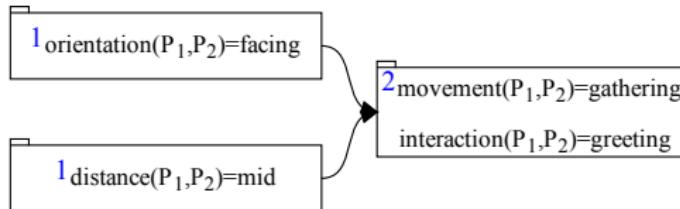
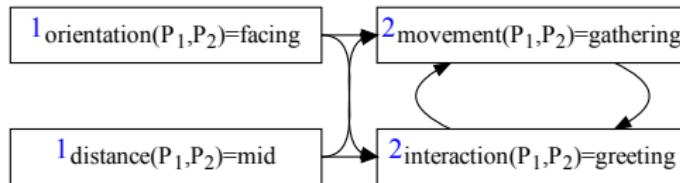
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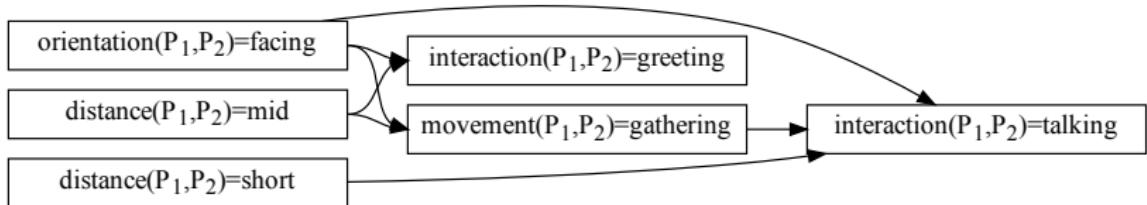
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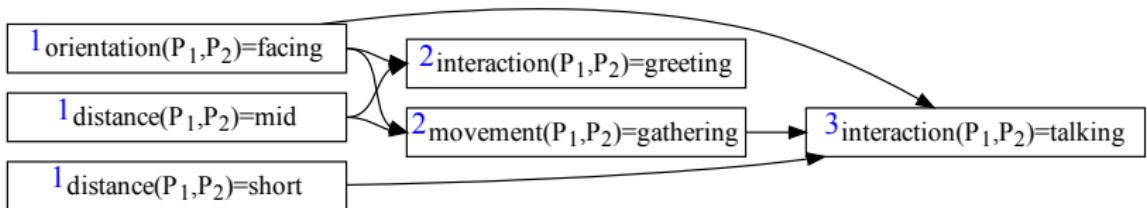
## Semantics

An event description of RTEC is a **locally stratified logic program**.

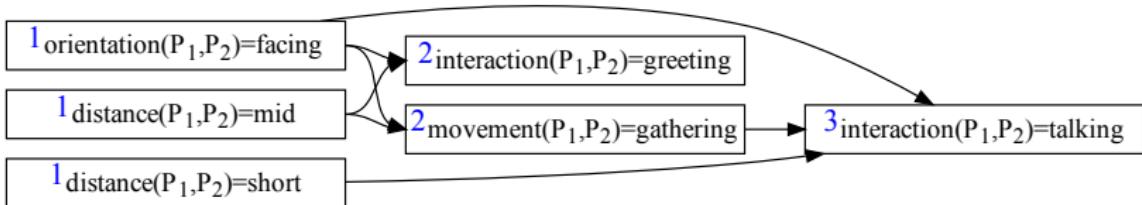
# Problem Statement (1)



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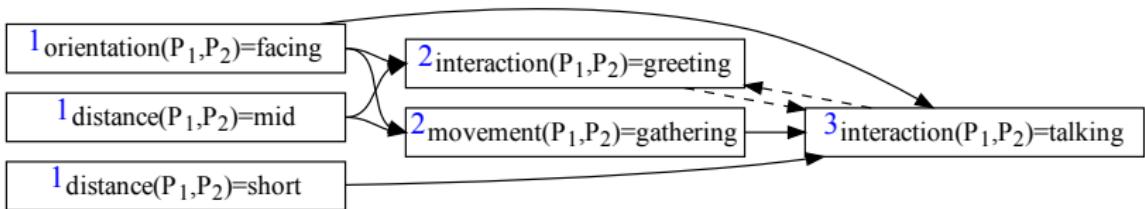


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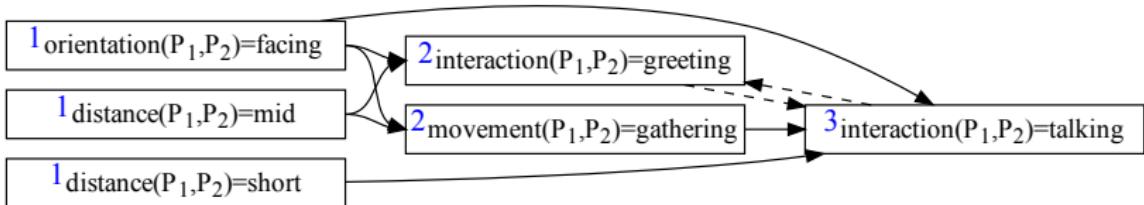
- ▶ A fluent may have at most one value at any time; an initiation of  $F = V_1$  implies a termination of  $F = V_2$ , where  $V_1 \neq V_2$ .

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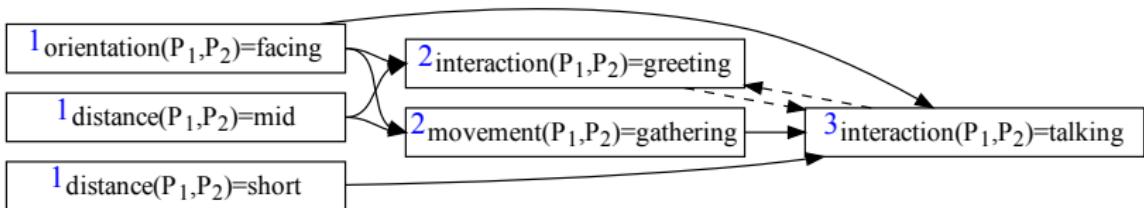
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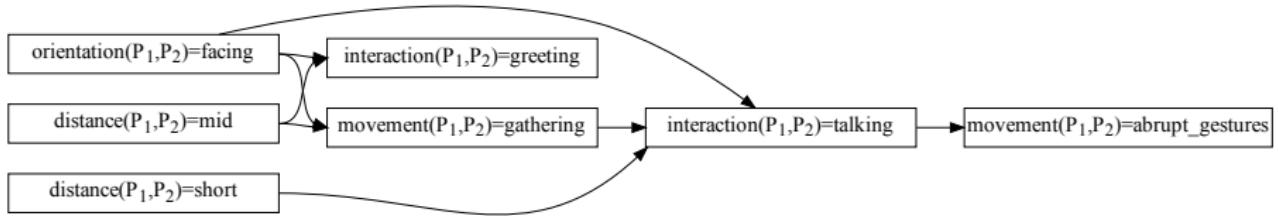
- ▶ A fluent may have **at most one value** at any time; an initiation of  $F = V_1$  implies a termination of  $F = V_2$ , where  $V_1 \neq V_2$ .
- ▶ Implicit dependencies between fluent-value pairs with the same fluent **may prohibit bottom-up processing**.

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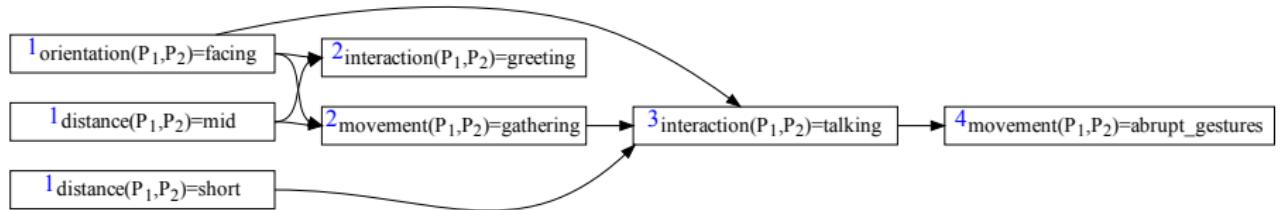


- ▶ A fluent may have **at most one value at any time**; an initiation of  $F = V_1$  implies a termination of  $F = V_2$ , where  $V_1 \neq V_2$ .
- ▶ Implicit dependencies between fluent-value pairs with the same fluent **may prohibit bottom-up processing**.
- ▶ **Solution:** assign to fluent-value pairs of  $interaction(P_1, P_2)$  a higher level than  $movement(P_1, P_2) = gathering$ .

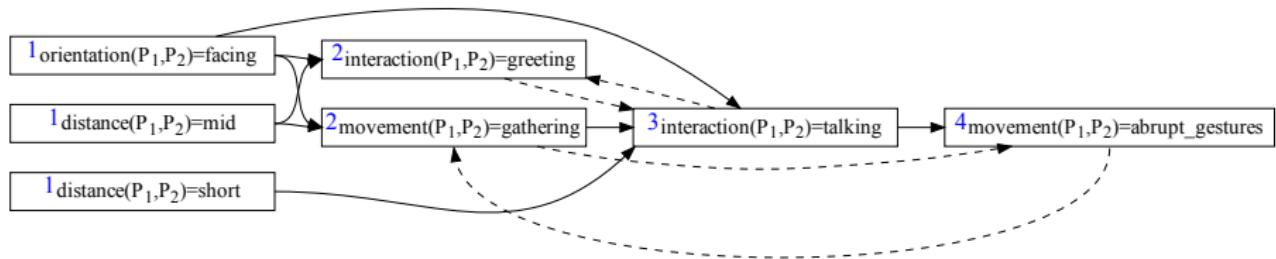
## Problem Statement (2)



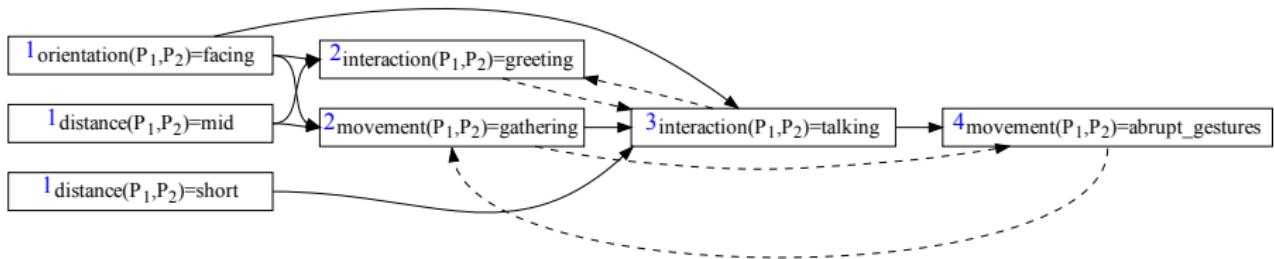
## Problem Statement (2)



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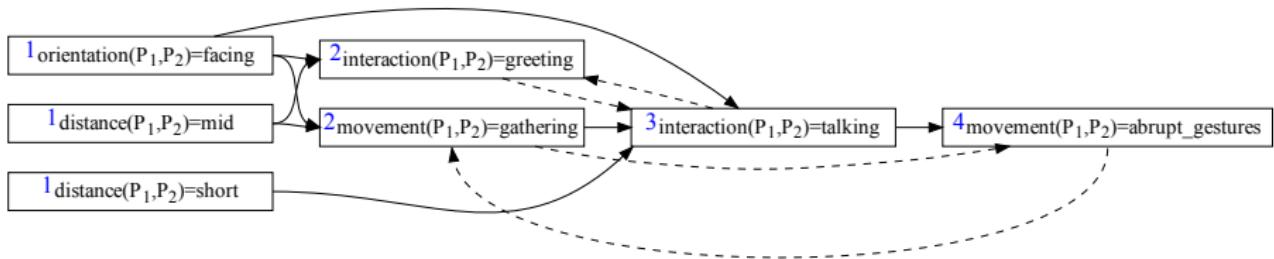


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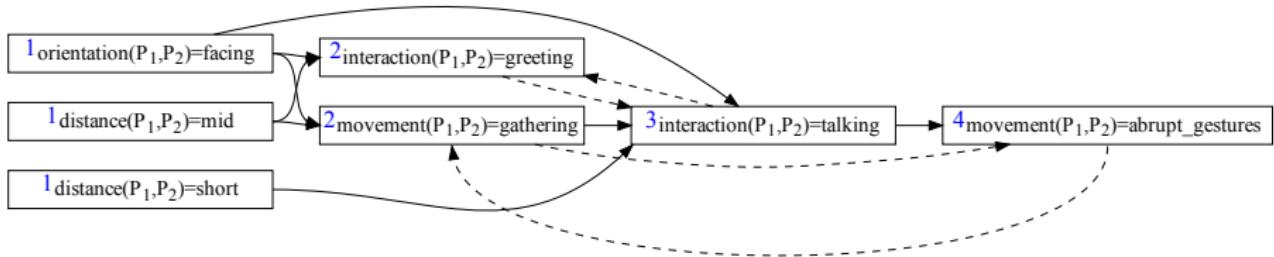
- We can have arbitrary implicit relations.

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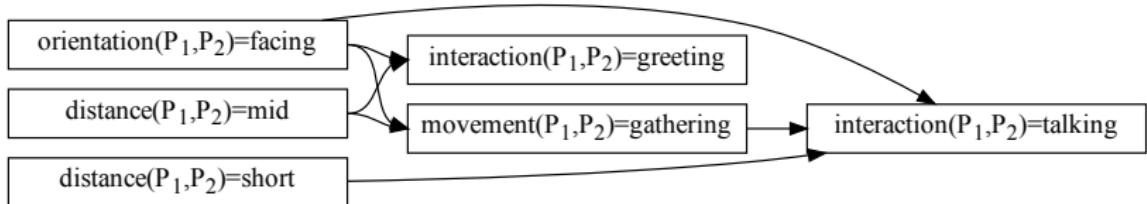
- ▶ We can have arbitrary implicit relations.
- ▶ Solution: assign to fluent-value pairs of  $interaction(P_1, P_2)$  and  $movement(P_1, P_2)$  the same level.

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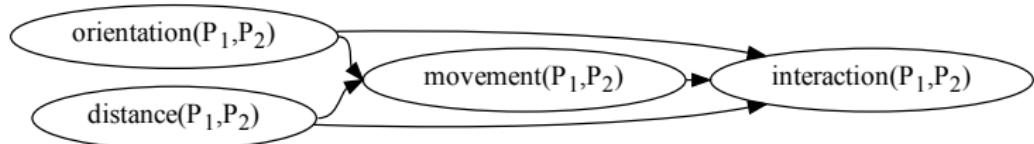
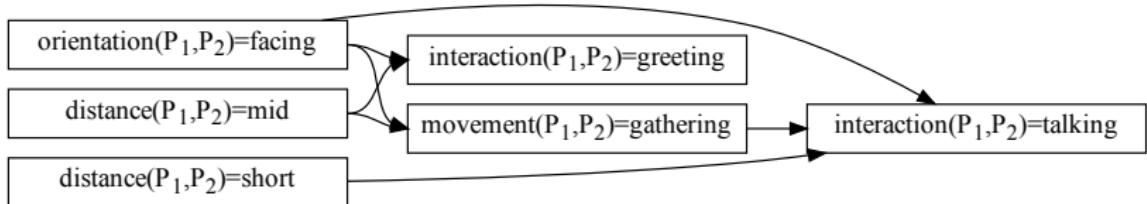


- We can have **arbitrary implicit relations**.
- **Solution:** assign to fluent-value pairs of  $\text{interaction}(P_1, P_2)$  and  $\text{movement}(P_1, P_2)$  the **same level**.
- **RTEC<sub>fl</sub>**: An extension of RTEC that **supports every possible dependency graph**.

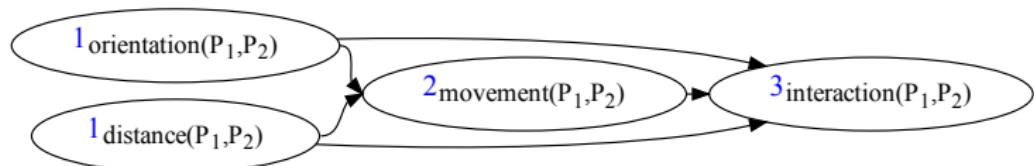
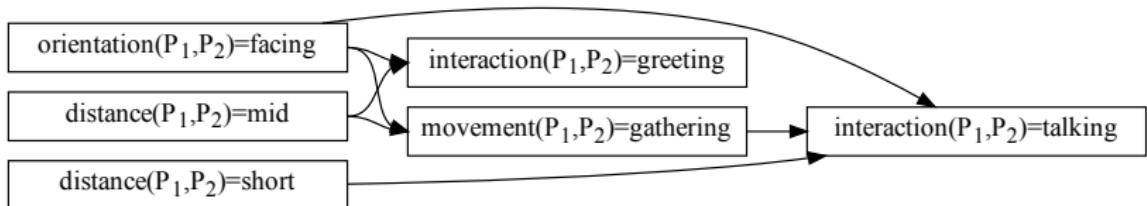
## RTEC<sub>fl</sub>: Fluent Dependency Graph



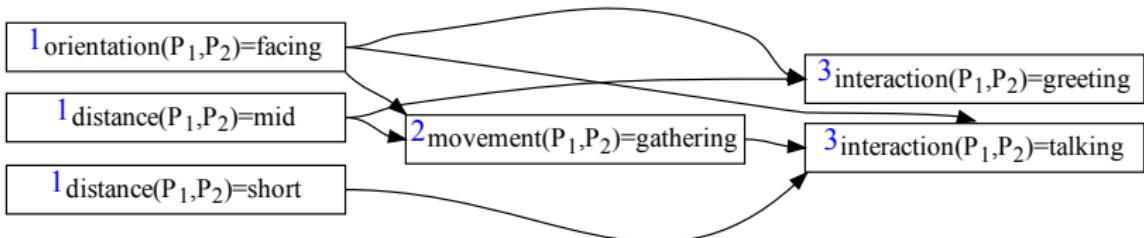
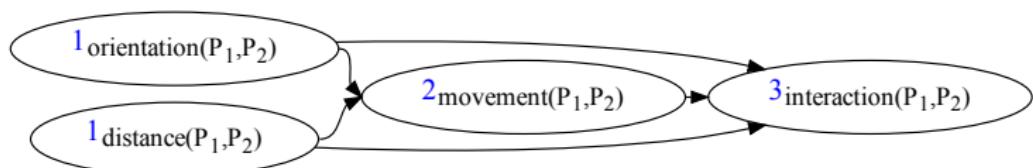
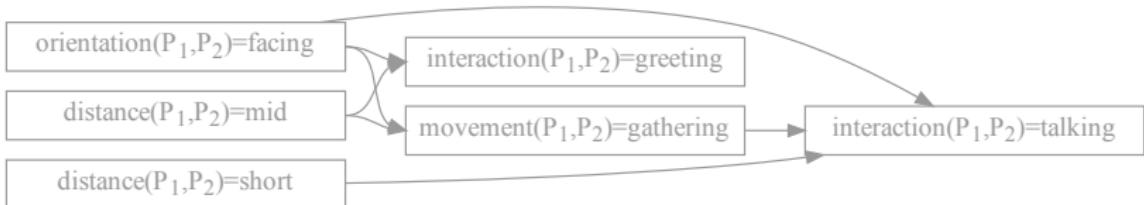
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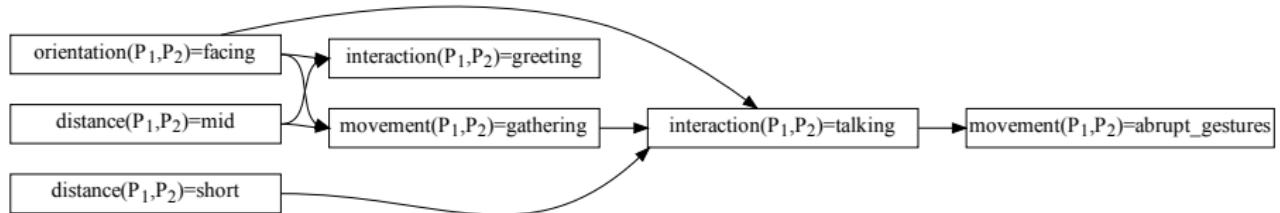
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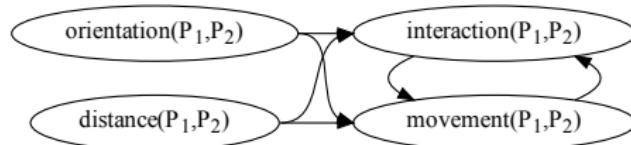
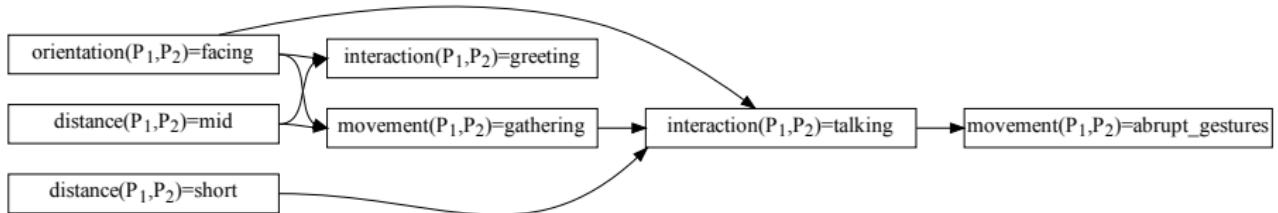
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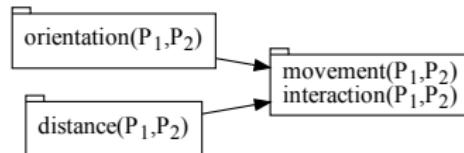
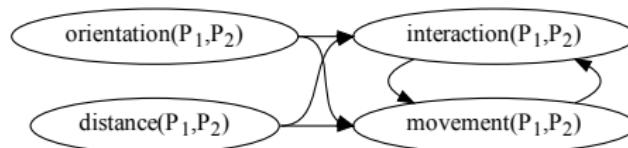
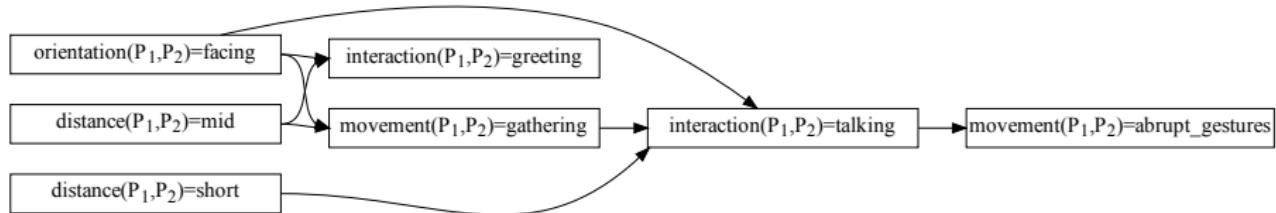
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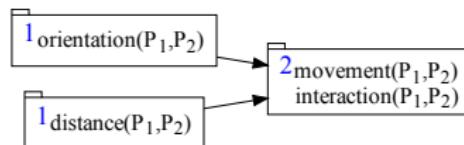
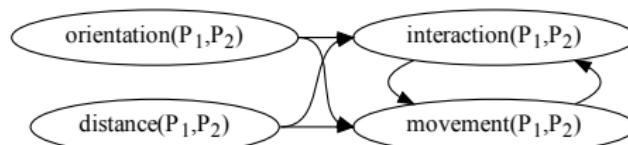
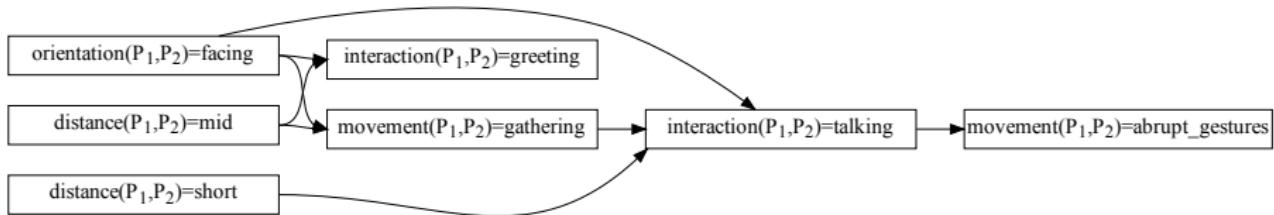
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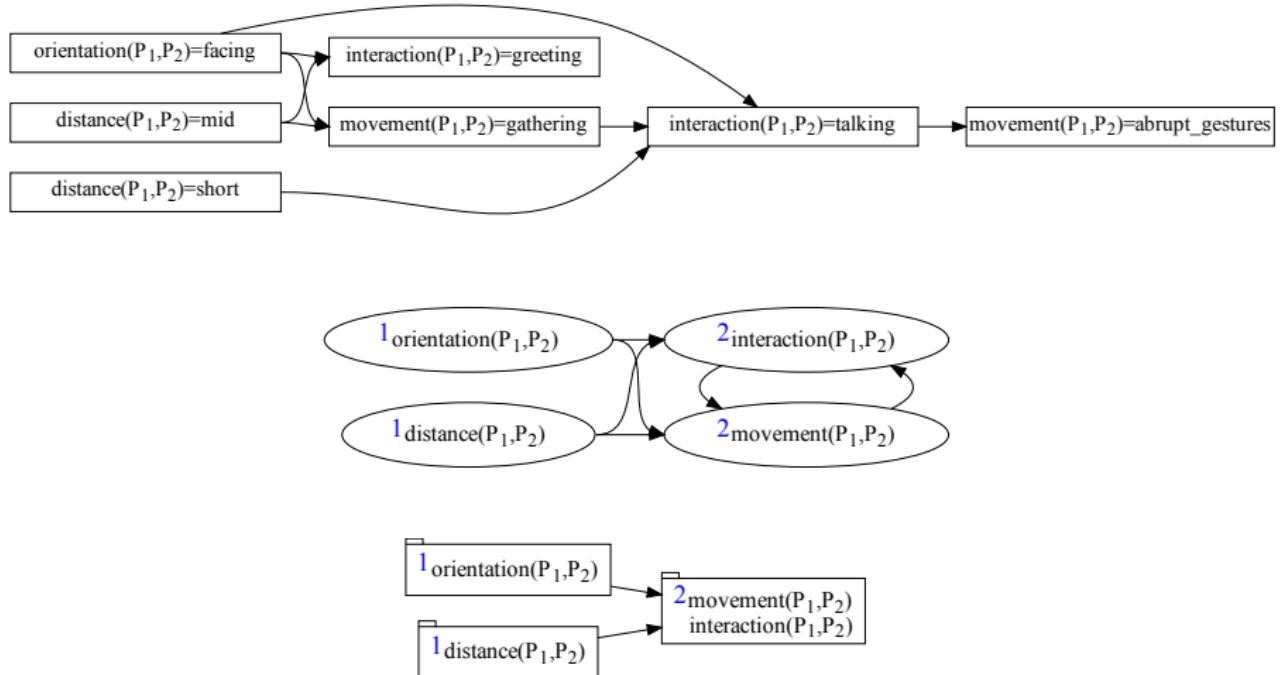
## RTEC<sub>fl</sub>: Contracted Dependency Graph



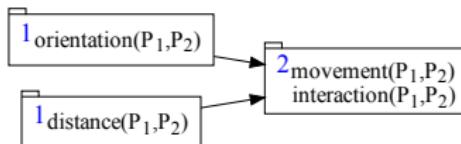
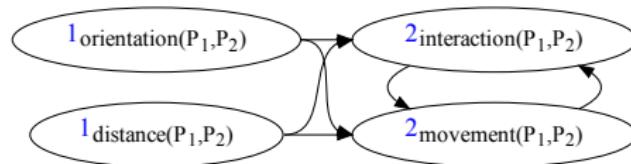
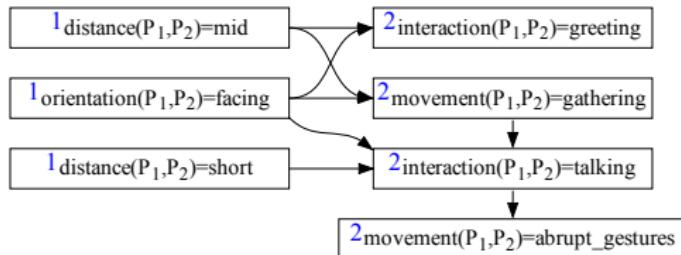
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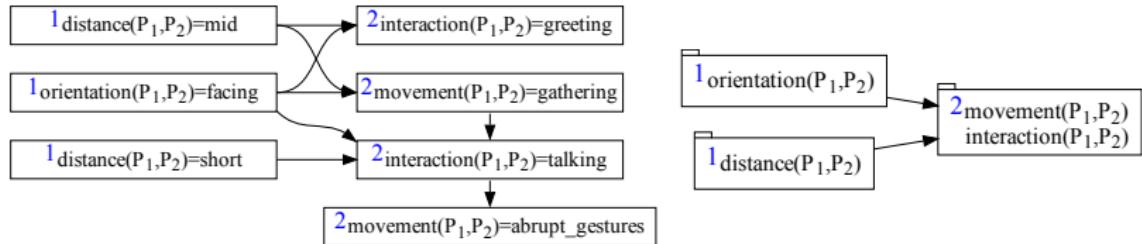
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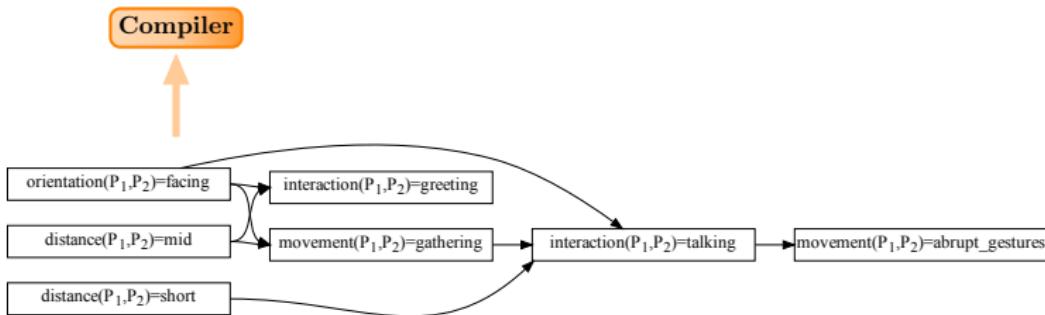
# RTEC<sub>fl</sub>: Semantics



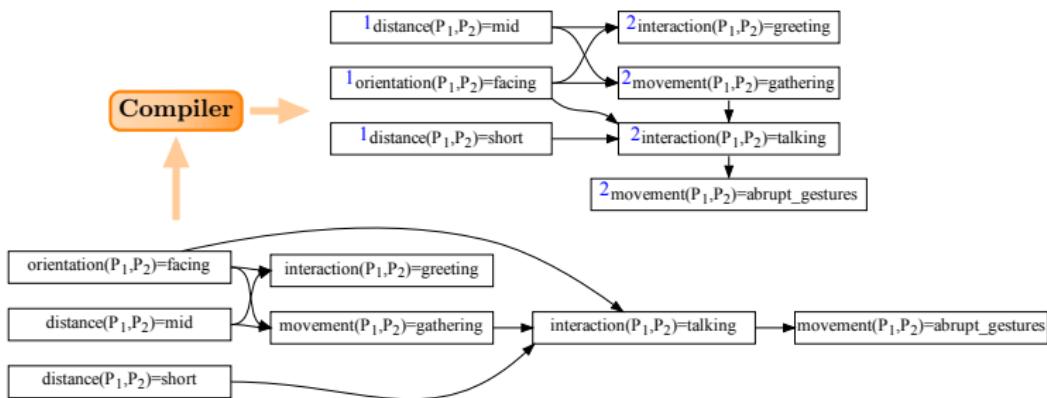
## Semantics

An event description of RTEC<sub>fl</sub> is a **locally stratified logic program**.

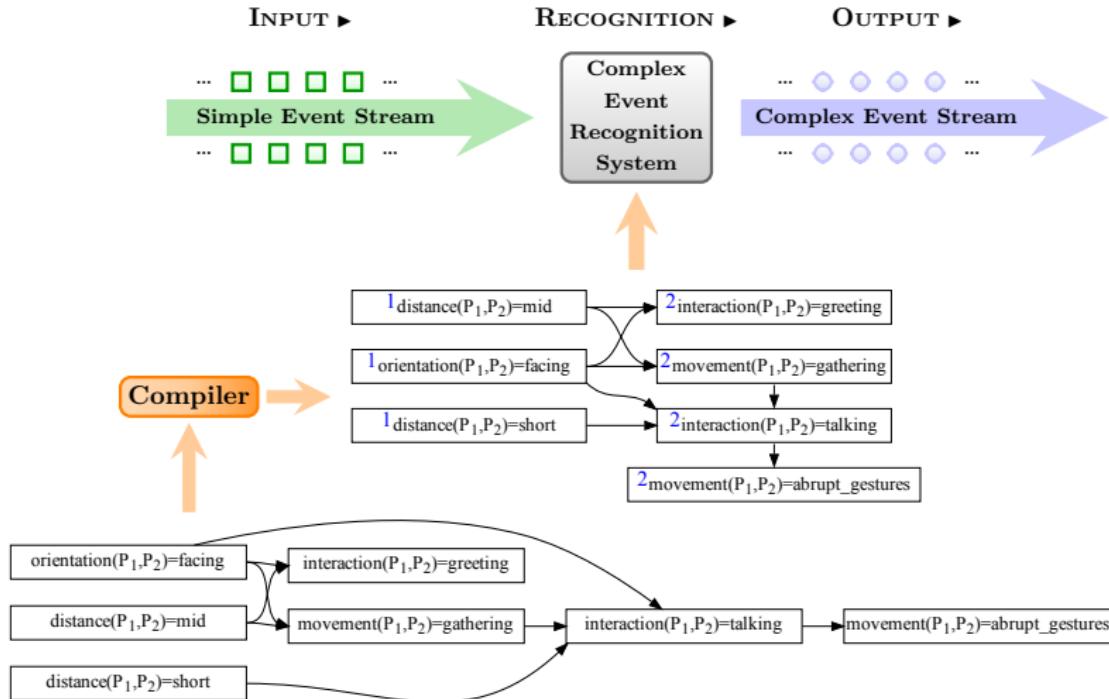
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- ▶ Same worst-case time complexity as RTEC.
- ▶ Semantics: Locally stratified specifications.
- ▶ Compiler: Support for any dependency graph.

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- ▶ Same worst-case time complexity as RTEC.
- ▶ Semantics: Locally stratified specifications.
- ▶ Compiler: Support for any dependency graph.
- ▶ Applications:
  - ▶ human activity recognition.
  - ▶ city transport management.
  - ▶ maritime situational awareness.
  - ▶ multi-agent systems monitoring.

## Summary & Further Work

RTEC<sub>fl</sub>:

- ▶ An open-source framework for composite event recognition.
- ▶ Wider range of specifications than RTEC.
- ▶ Same worst-case time complexity as RTEC.
- ▶ Semantics: Locally stratified specifications.
- ▶ Compiler: Support for any dependency graph.
- ▶ Applications:
  - ▶ human activity recognition.
  - ▶ city transport management.
  - ▶ maritime situational awareness.
  - ▶ multi-agent systems monitoring.

Further Work:

- ▶ Capture sequencing phenomena.
- ▶ Neuro-symbolic framework for composite event recognition.