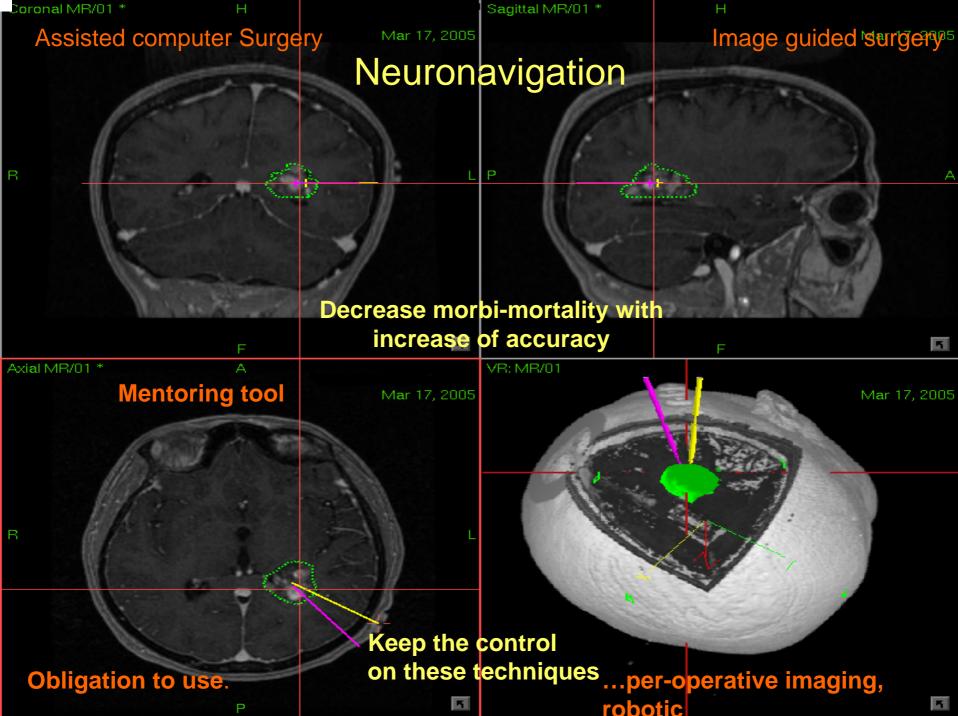
# ROBOTIC and NEUROSURGERY Present and Future

#### Cédric BERNARD

Neurosurgical Department, Armed Forces Hospital Sainte-Anne, 2 Bd. Sainte-Anne F83800 Toulon Armed Forces.

> 10 September 2007 Surgical Robotics, Montpellier 5-12 Sep 2007

MARINE NATIONALE - P.-A. "CHARLES DE GAULLE"



#### **INTRODUCTION:**

Robotic in Neurosurgery is one more step in our practice:

Microscope

CT-scan, MRI, MRA

Neuronavigation (MKM (Zeiss) Val de Grâce, Paris, 1994 : Pr. Michel DESGEORGES, Toulon NOVEMBER 1999). In 199.'s it looked like « Star Wars » in France

Endoscope

Minimal invasive neurosurgery

Robotic



Summer 2005: New system Stealth Station (Treon + Axiem) : MEDTRONIC







#### - Evolution of Knowledge

- Anatomical step

Middle of The XIX century with reports of cadaver dissections.

- Therapeutic step

First middle of the XX century

 $\rightarrow$  Mortality = 50 %





#### Simplified view of the surgeon: hand and knife



#### **Truth is elsewhere !!!!**



### In very old times, craniotomy, yet!





- Therapeutic step
- Development due to progresses of neuroradiology
  - •Air, and contrast enhanced Ventriculogaphy
  - Air Encephalography
  - •Carotid and Vertebral artery Angiography

Invasive investigations released at intracranial hypertension status.



With Internet Ward Anne, Toulon, France

- Microscope step

- 1970...

operative mortality < 10 %

Operative microscope

- 1980...

Earlier diagnosis

**CT-Scan and MRI** 



HIA Sainte-Anne, Toulon, France

- Image guided surgery step

- 1990...

#### Neuronavigation

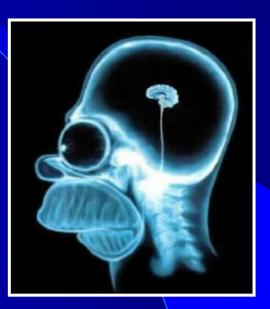
Aims: mortality 0% or accidental morbidity equal to pre-op.

<1970 Surgery to « stay alive » >1990
« preventive » surgery



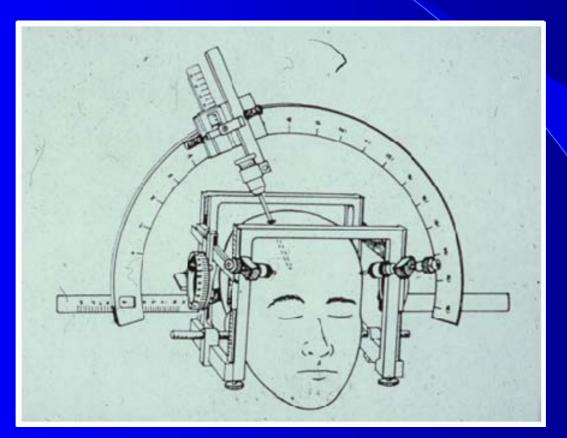
The challenges in neurosurgery

- To define the borders between tumour and brain
- Localize risks and functional area
- Confirmed the quality of resection
- To free from anatomical changes during surgery (brain shift)
- To have the better accuracy as possible (stereotactic procedures)
- To have guide-tools (biopsy-needle, DBS electrode,...)



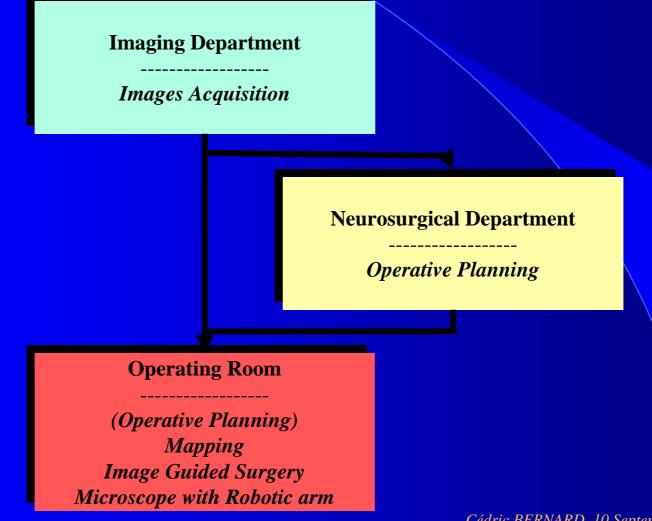


#### Integration of pioneers' Brain stereotatctic atlases in softwares.











#### Robotic and Neurosurgery







# TOOLS: MKM (ZEISS®)





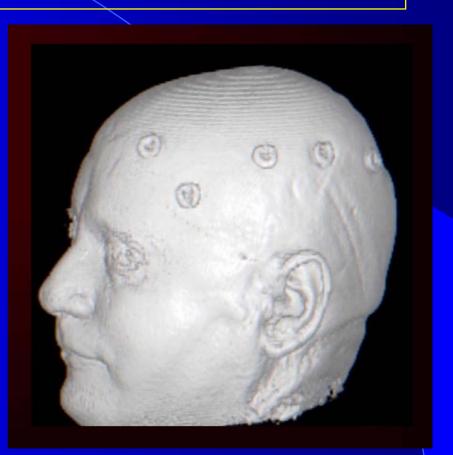
#### **TOOLS: Station Treon MEDTRONIC®**



HIA Sainte-Anne, Toulon, France

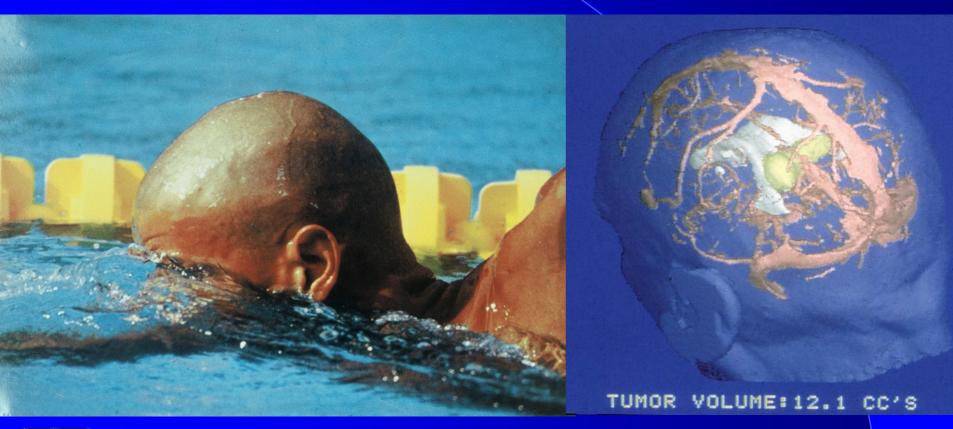
### Fiducials for mapping







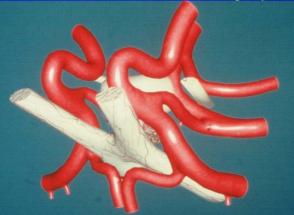
## The revolution around Neurosurgery: Neuroimaging

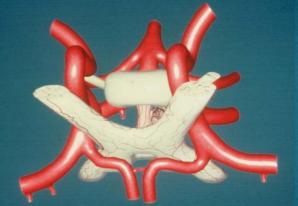


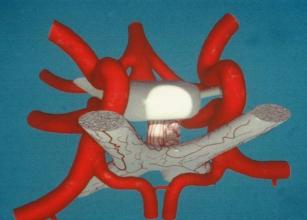


#### Robotic and Neurosurgery

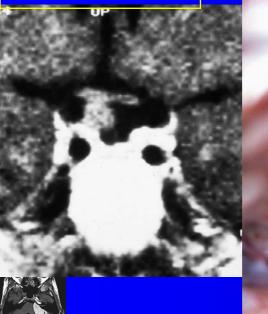
#### HIA Sainte-Anne, Toulon, France







# Planning



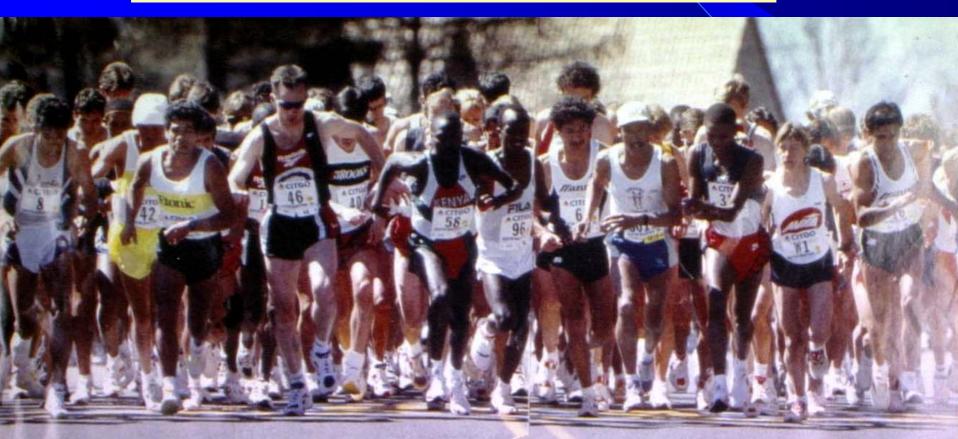




# Planning

Aim: find anatomically preformed spaces on the way to the pathology by preoperative Imaging:

## **INDIVIDUAL ANATOMY OF THE PATIENT**

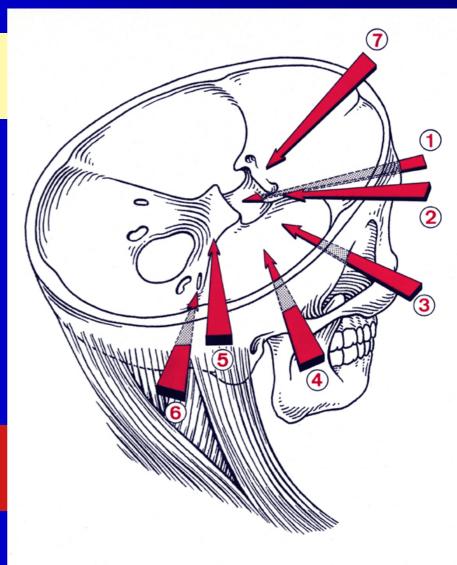




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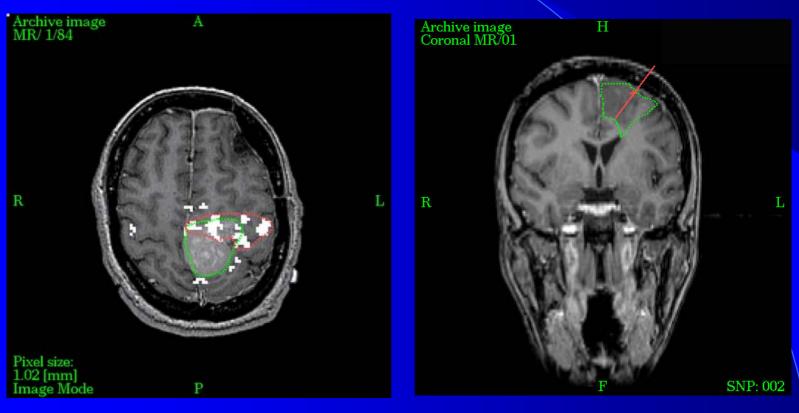
# **INDIVIDUAL ANATOMY**

# **INDIVIDUAL APPROACH**





### **Operative Planning**





### **Operative Planning**

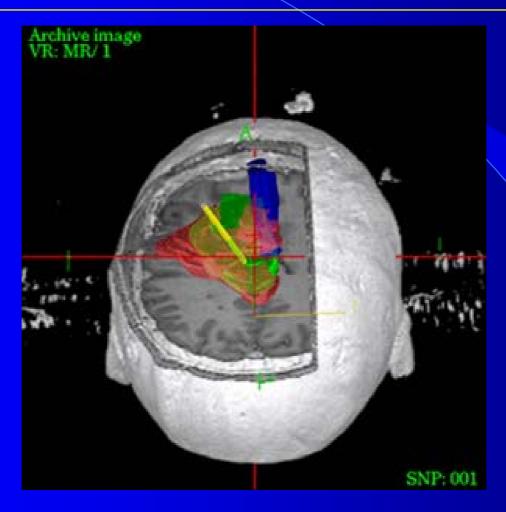
- Images fusion (fMRI, Brain scintigraphy, MRI, Pet-scan, CT-Scan, MRA, DTI sequences,...)
- Definition of tumour borders, risks areas, functional areas,...
- Three-dimensional reconstruction,
- Definition of a trajectory,
- Simulation of surgical access in different plans





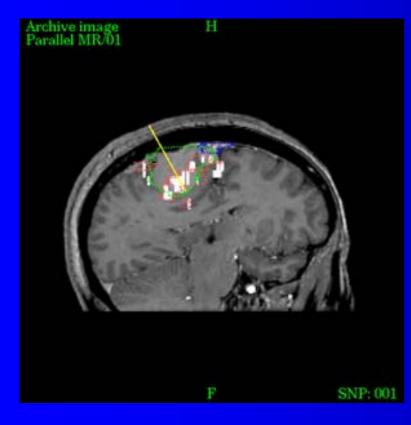
#### HIA Sainte-Anne, Toulon, France

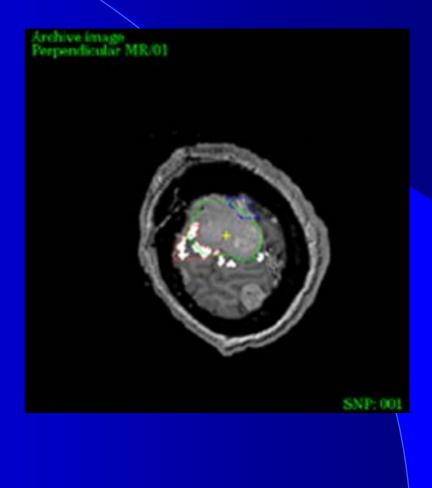
## **Operative Planning**





## **Operative Planning**

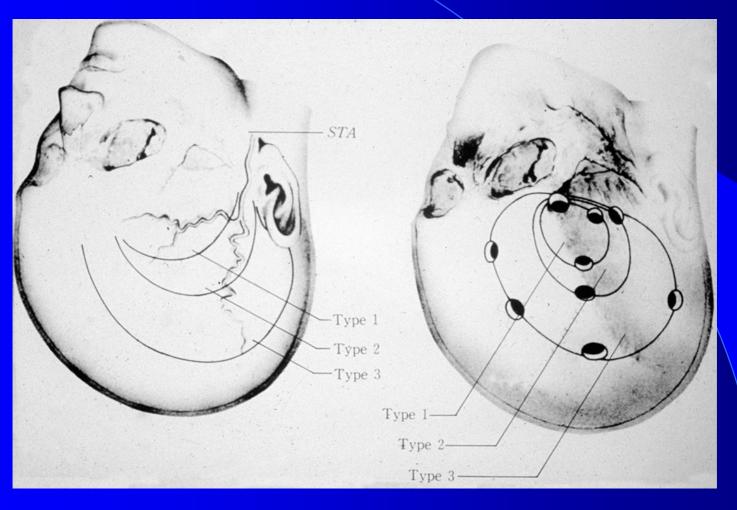








# Size of craniotomy: just what is needed





#### Robotic and Neurosurgery







#### Robotic and Neurosurgery





#### Volumes mapping « Patient head » and « MRI volume » Now: surface mapping with pointer





Mapping

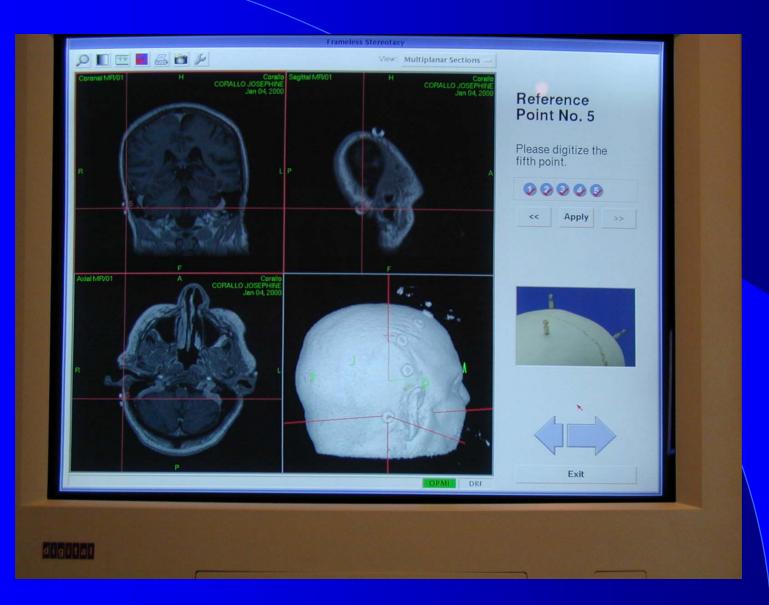
surface mapping
optical(laser) on microscope
Infra-red ou Electromagnetic

Notion of accuracy of correlation



#### Robotic and Neurosurgery

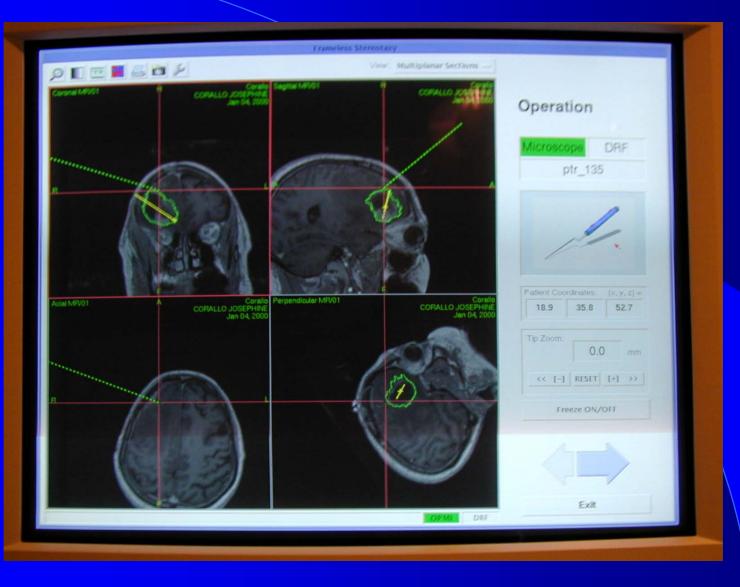






#### Robotic and Neurosurgery

#### HIA Sainte-Anne, Toulon, France

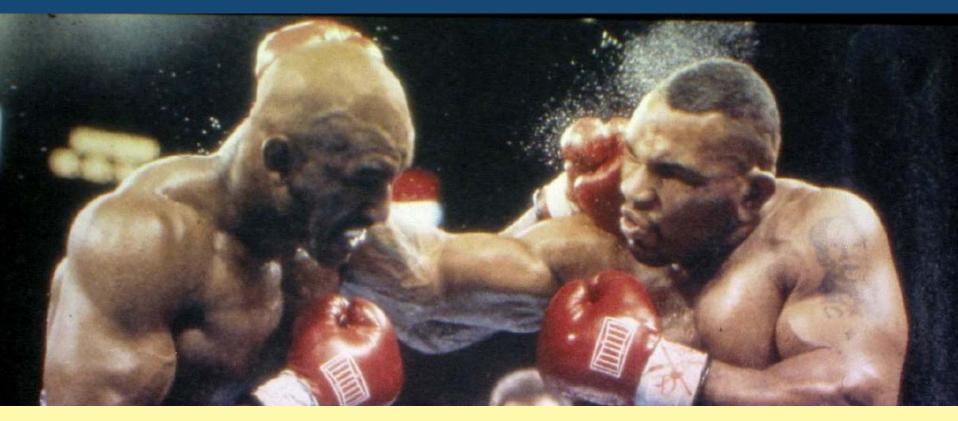




Concept of Minimally Invasive Neurosurgery

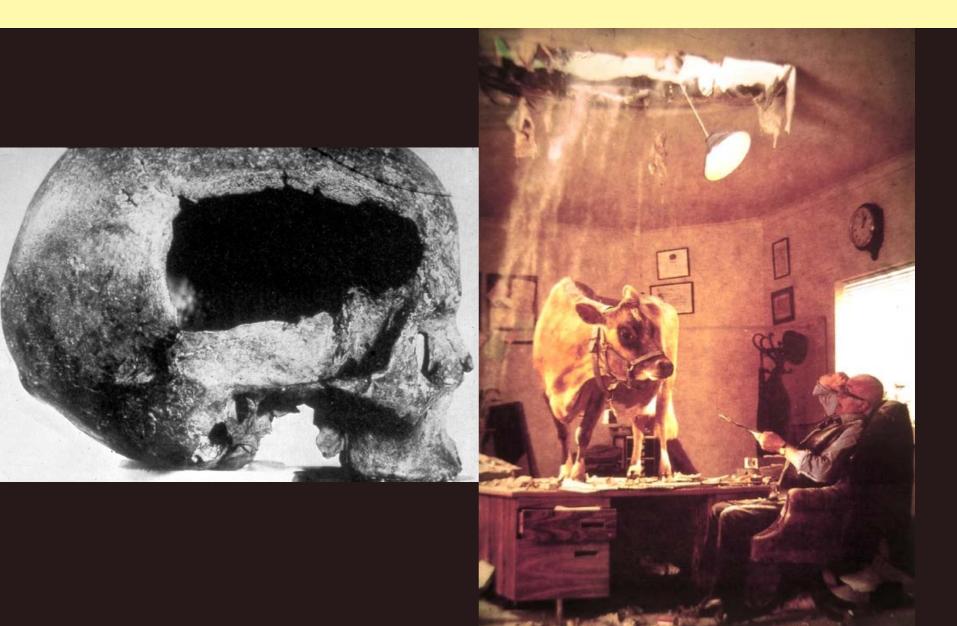
PRIMUM NON NOCERE ("Firstly, do not harm the patient") HIPPOCRATES

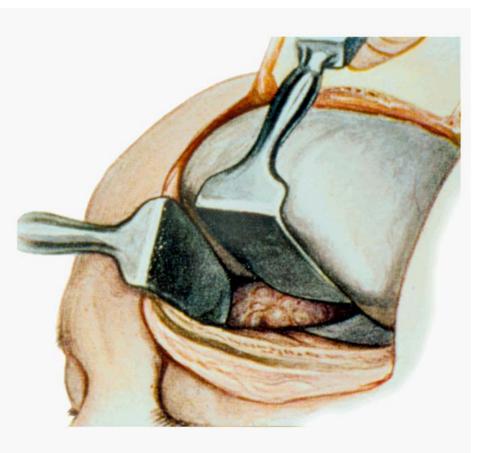
# **Definition of Minimally Invasive:**

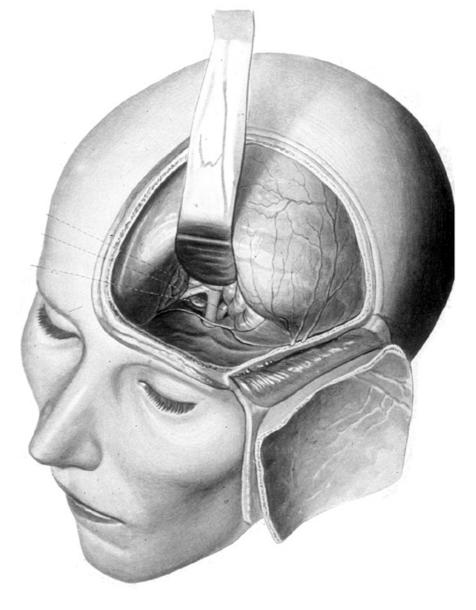


# The lowest medical traumatization combined with the highest therapeutic effect

# **Doors and Windows**



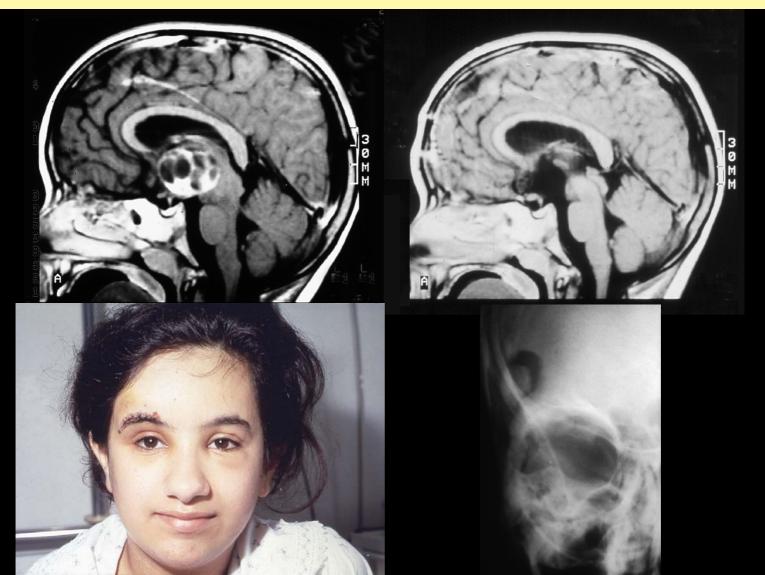




## F. Krause (1908)

## Tandler - Ranzi (1932)

# Craniopharyngioma Supraorbital Approach



## **Visualisation and Light**

#### Neurosurgery in Darkness

by Paul C. Bucy



#### P. Bucy, O. Foerster



#### MKM: Microscope + Navigation + Robotic Arm

Le A

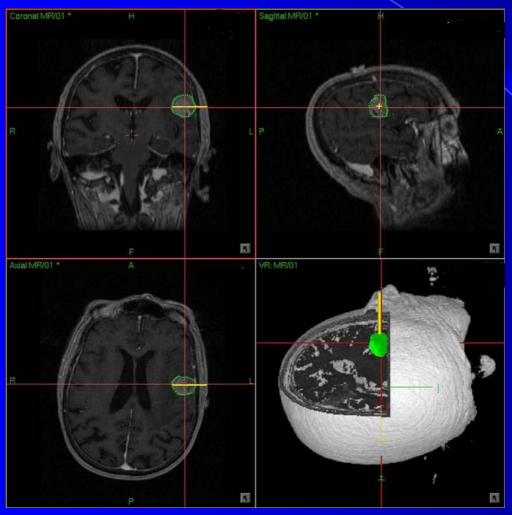
CONTRACTOR

Continue.

Hillion

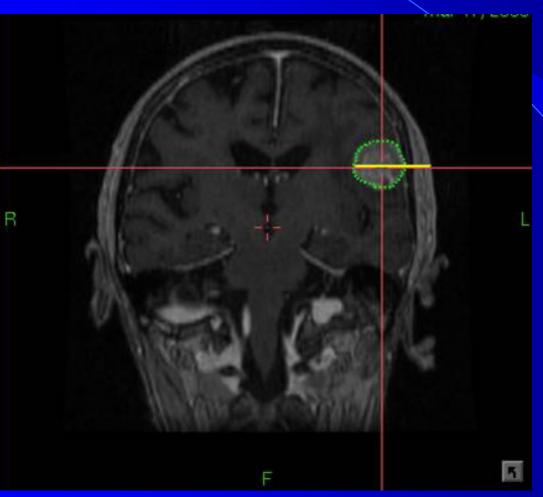
OPN

#### Frontal metastasis February 2001





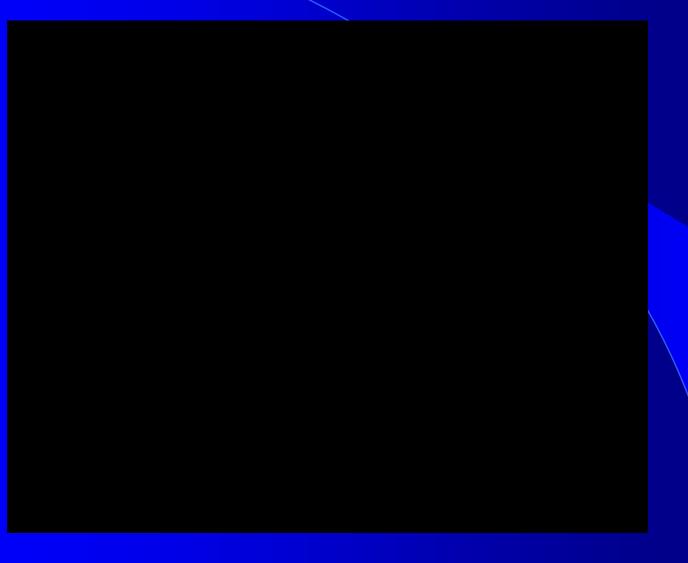
#### Frontal metastasis February 2001





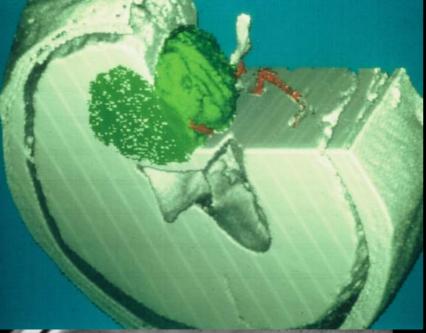


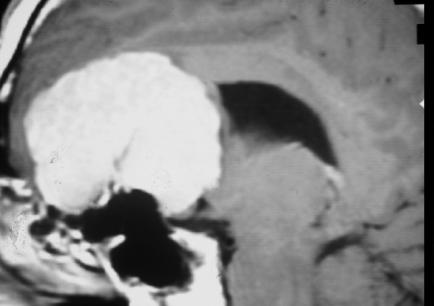






## Frontobasal meningioma



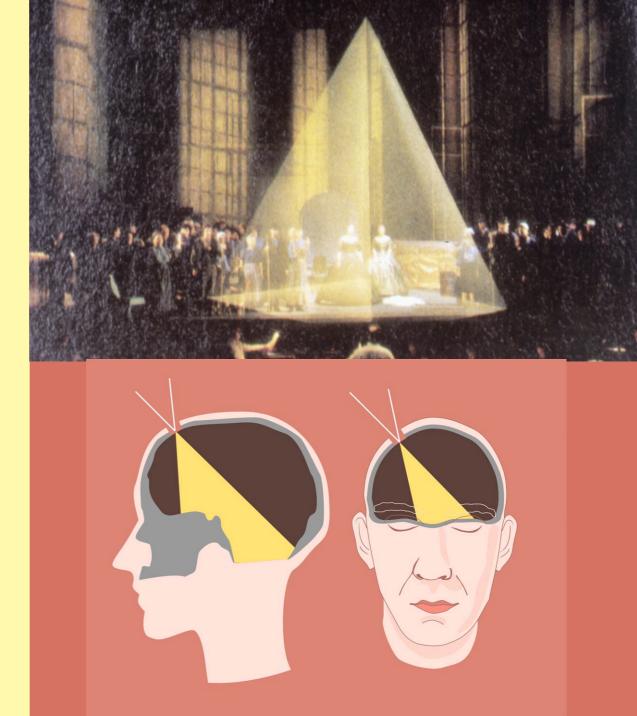






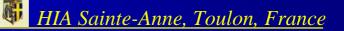


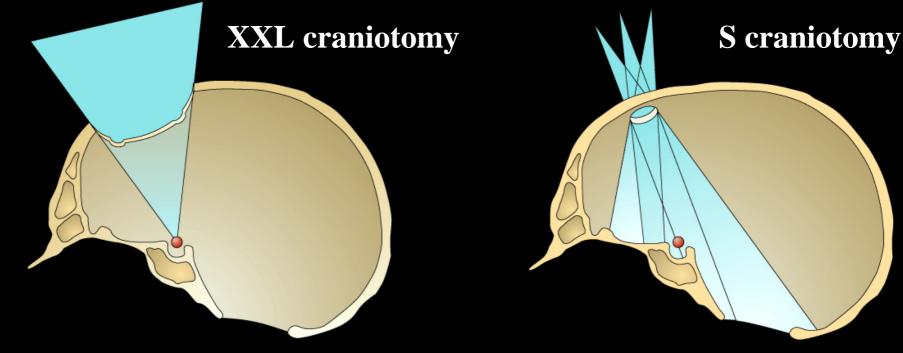
# The Key-hole Concept in Neurosurgery



Sector-like widening of the visual field







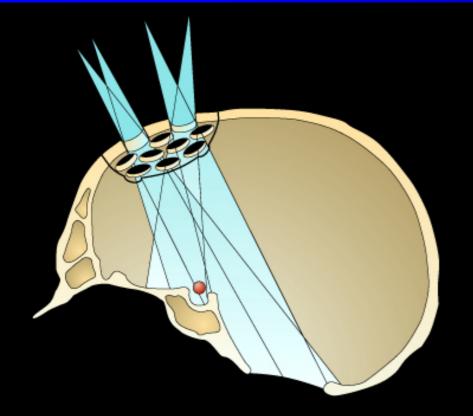
old surgical concept

keyhole concept





#### Standard approach = collection of keyhole approaches

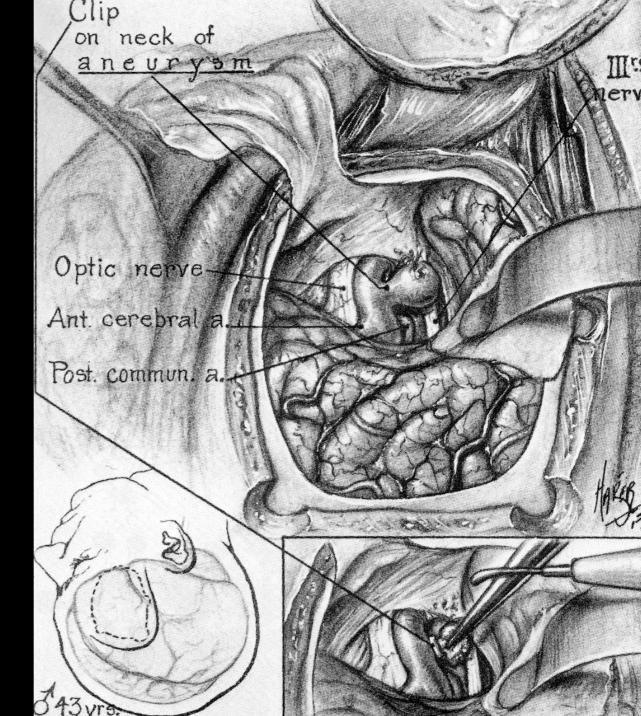


Individual choice of combination of keyholes according to the individual planning.



#### The depth of the tumour Is very important to consider

Which part was needed for the exposure?



Which part was needed for the exposure?





## **Contra lateral approaches**



#### Most important part of keyhole surgery

## Surgical-anatomical PLANNING



## Macrosurgery

## Microsurgery

Key-holesurgery development of light and visualisation

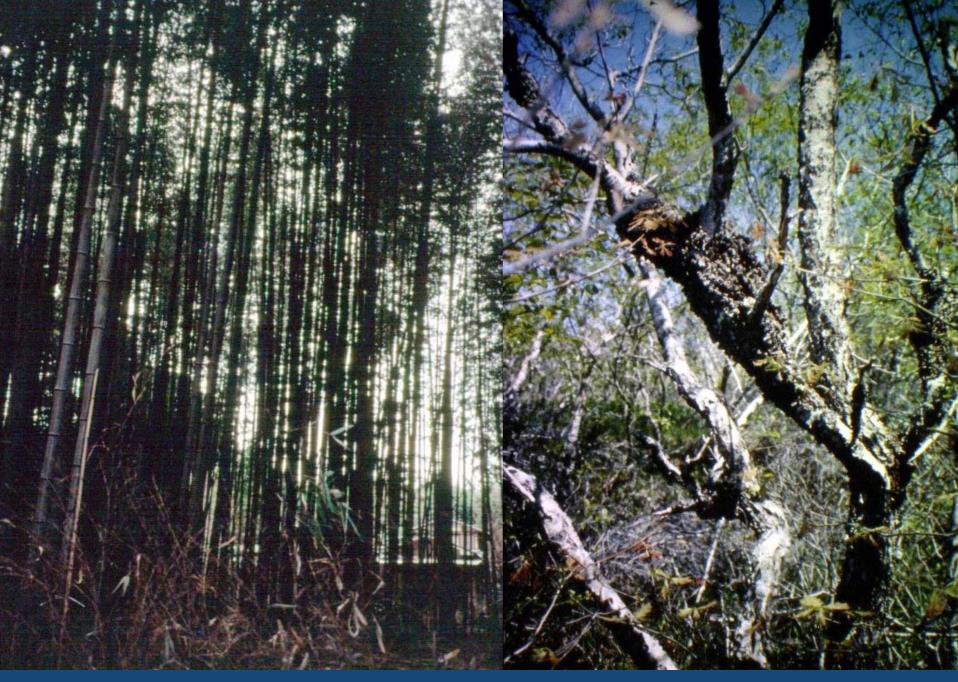
+ Robotic

Endoscopy

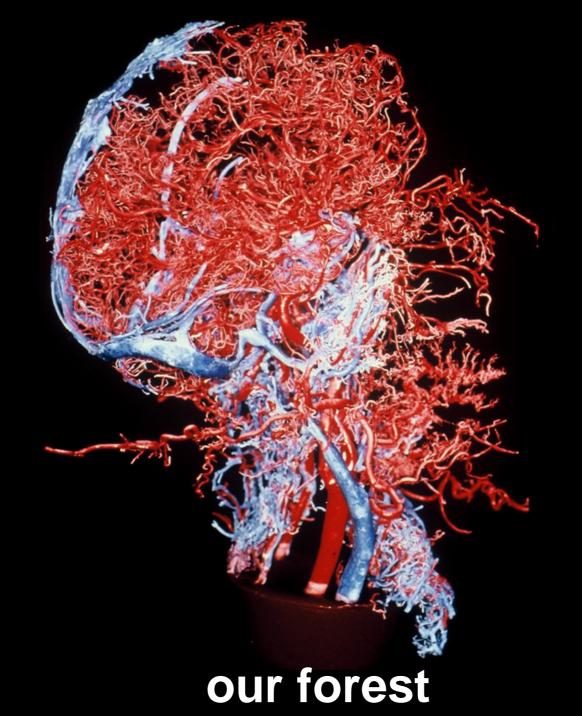
### Neuroendoscopy new dimension

Neuroendoscope Can be hold and guided In the trajectory By robot.

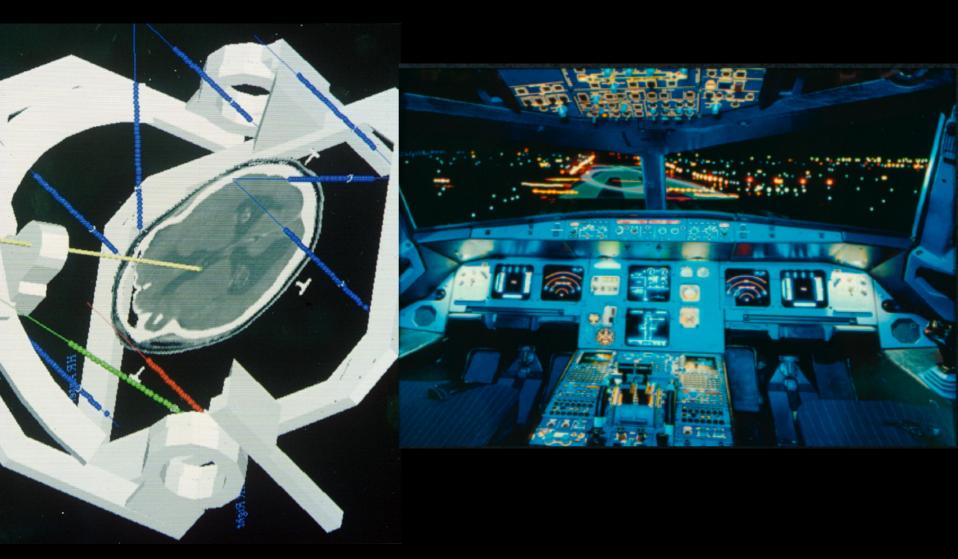
### New topographic anatomy



Approach the sick tree without touching the healthy one



## Neuronavigation





"real navigation" needs "real time imaging"

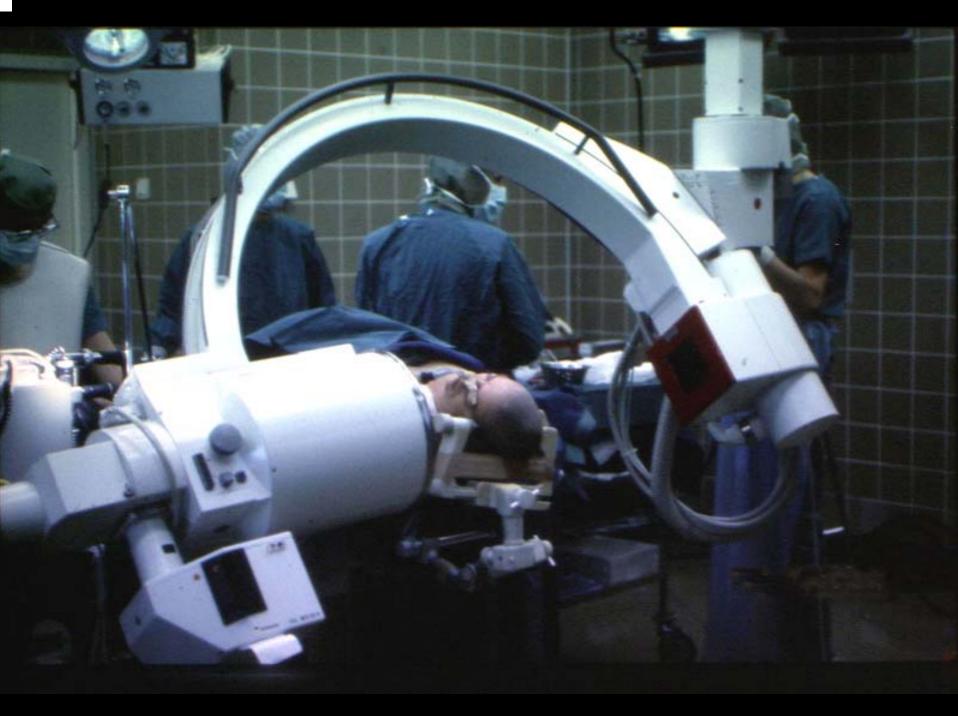
## Intraoperative imaging

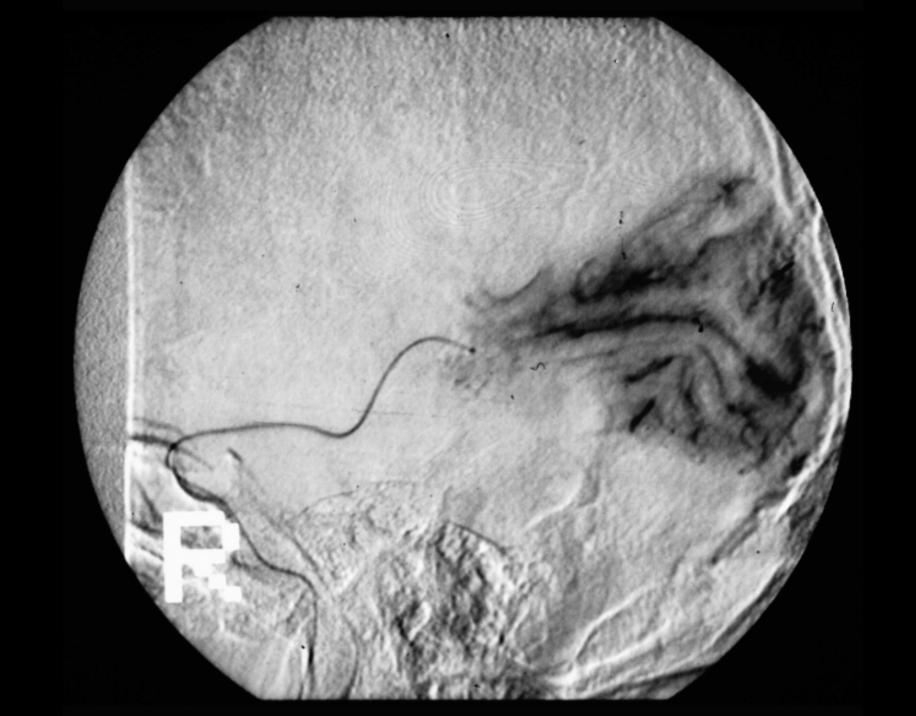
# fluoroscopy ultrasound CT MR

## **Intraoperative Imaging**

#### X-ray

- simple
- no special construction needed
- traditional, standard
- everywhere possible
- real time imaging
- contrast medium: intra-operative angiography
- mobile: intra-operative cavity presentation
- navigation, traditional stereotaxy

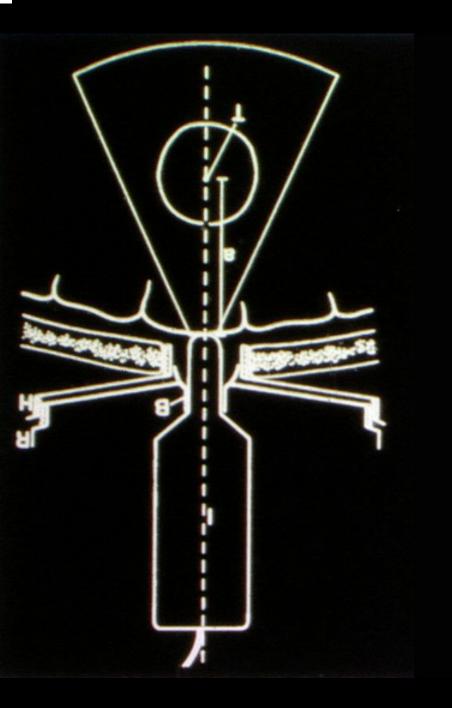




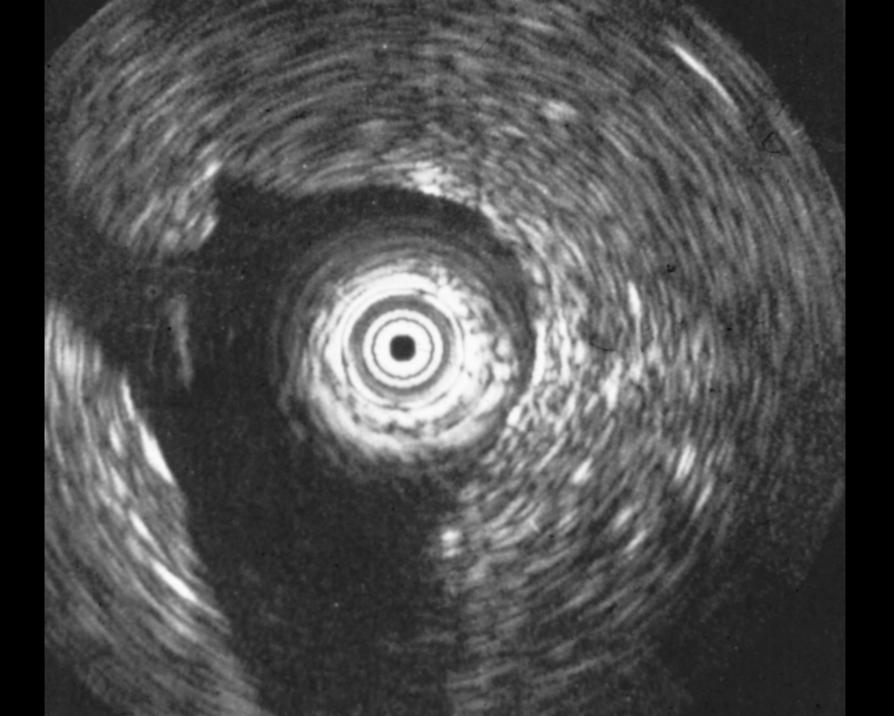
## **Intra-operative Imaging**

#### Ultrasound

- simple
- everywhere possible
- no special construction needed
- Doppler
- 3-D imaging
- navigation
- mobile
- real time imaging



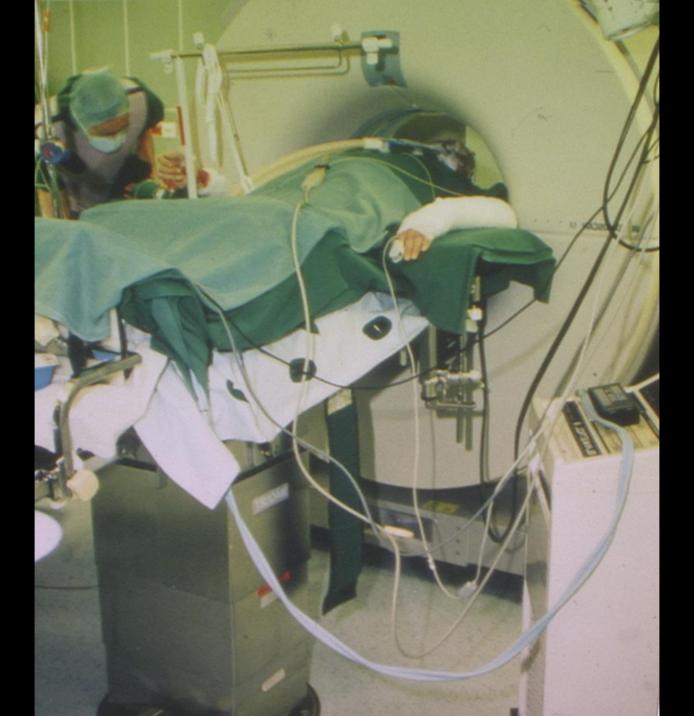


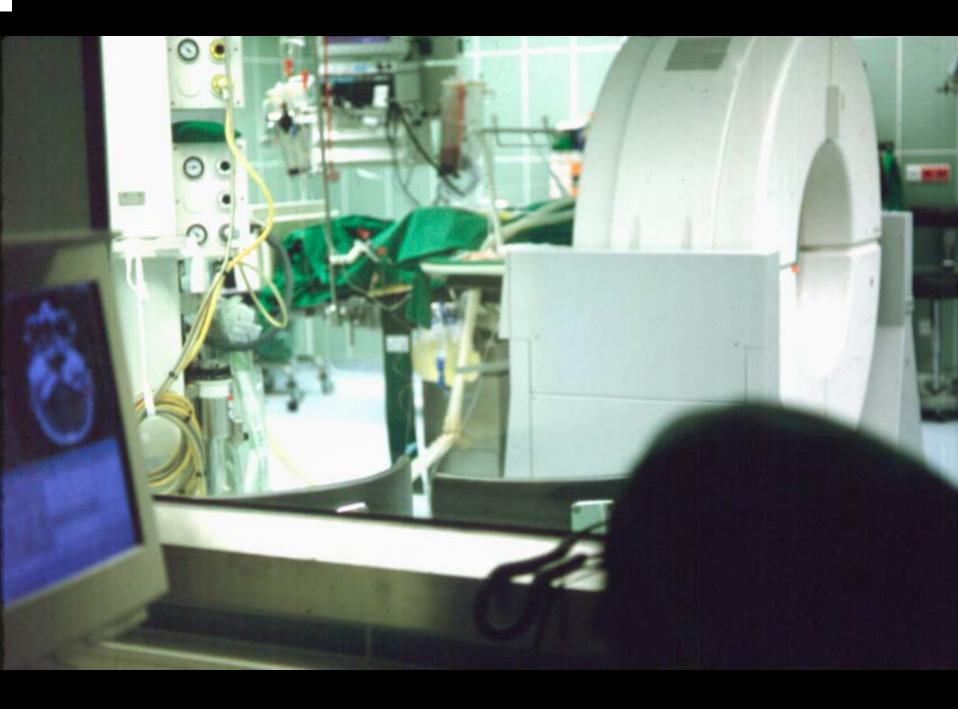


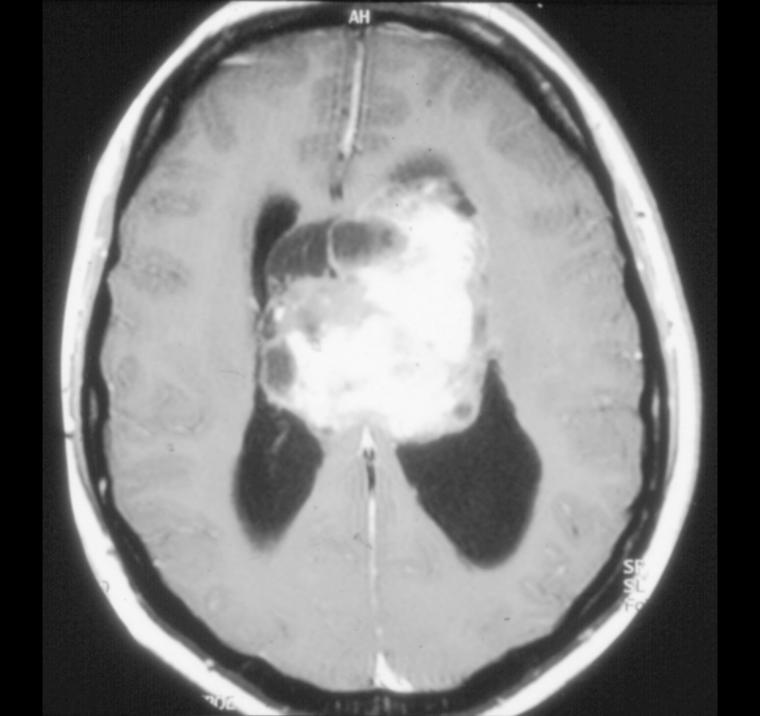
## **Intra-operative Imaging**

#### CT

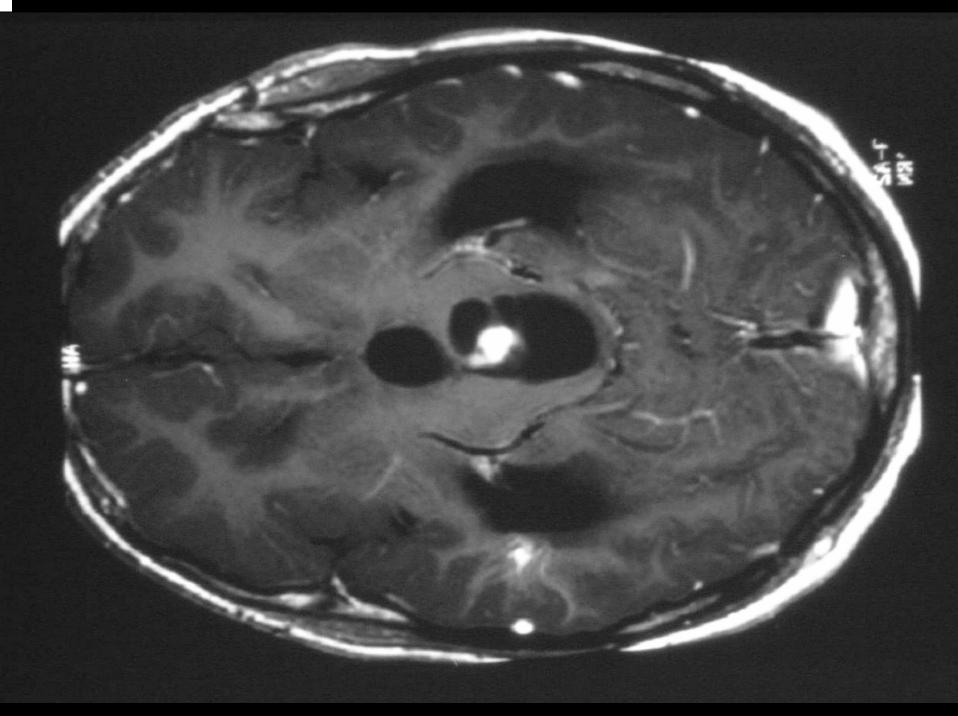
- mobile
- no special construction needed
- no special isolation needed
- spinal mode
- CT angiography intra-operatively
- navigation
- stereotaxy
- no real time imaging

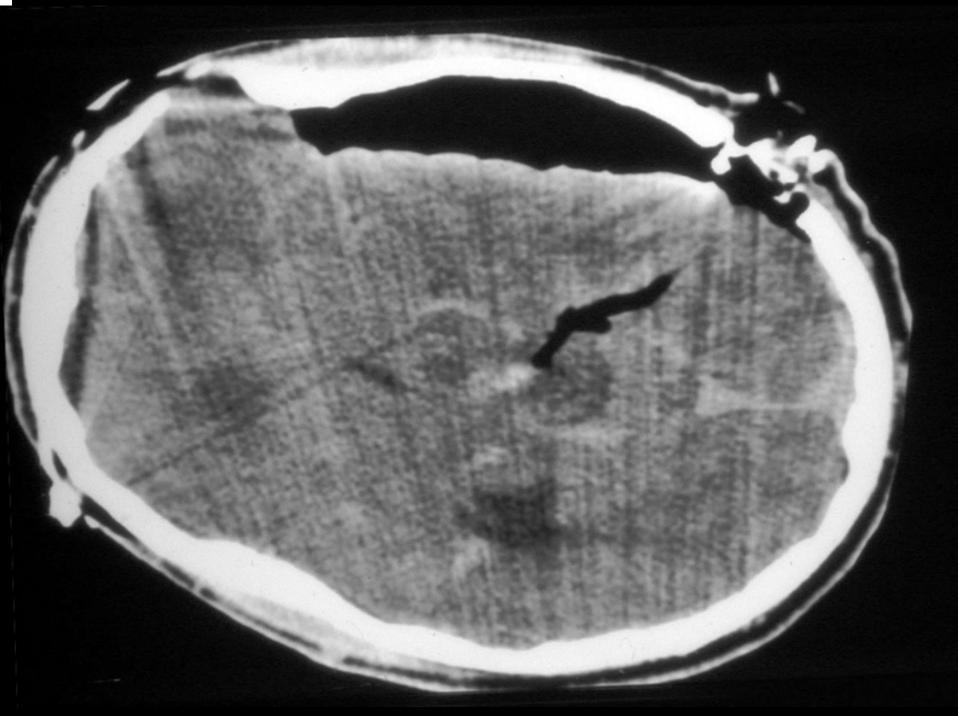












- special construction needed
- special isolation needed
- new instruments, new OR-equipment needed
- best quality of imaging
- no real time imaging navigation
- functional imaging time consuming space occupying

## **Operative time**

• Put in trajectory, Point to point localisation, • Following of trajectory, • Virtual tip, Images injection in the binocular.



Objective advantages of navigation benefit for the patient

• Safety and comfort :

# Decrease of the time of hospitalisation +++ Mean: 5 to 6 days

Operative time equal or increased of 20 mn.Morbidity decreased.



Subjective advantages of navigation : Its technical capacities

 Safety and comfort for the neurosurgeon

Accuracy



Disadvantages of robotic navigation with MKM

- The bulk and weight, (MKM)
- Mind to placement of referential and infra-red camera/ advantage with Axiem
- Incidents: necessity of maintenance contract and to form all kinds of users (operating room nurses, surgeons, anaesthesiologists,...)

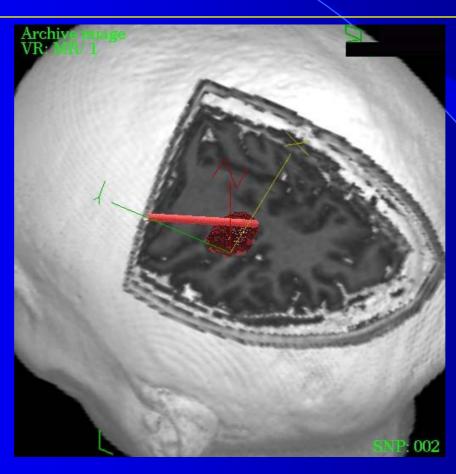


## Imperative indications

- Small deep lesion: cavernoma of the insula,...
- « Invisible » lesion: Low grade glioma,...
- Proximity of risk area: meningioma closed to skull-base arteries,...



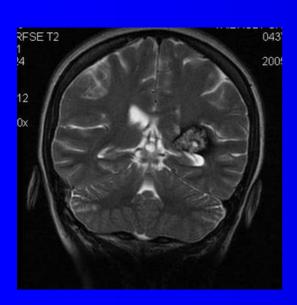
### Small deep lesion ex : parietal cavernoma

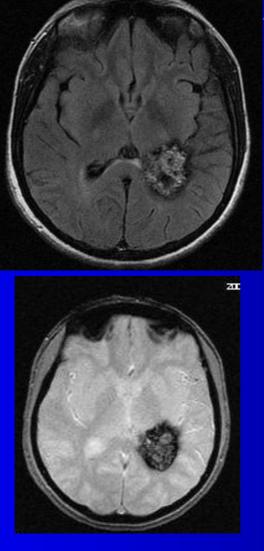


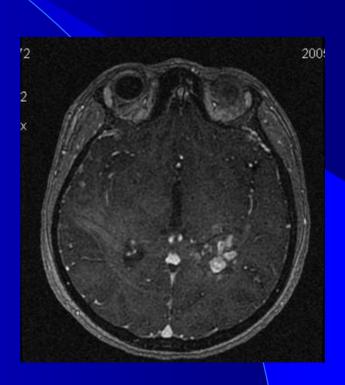


#### Robotic and Neurosurgery

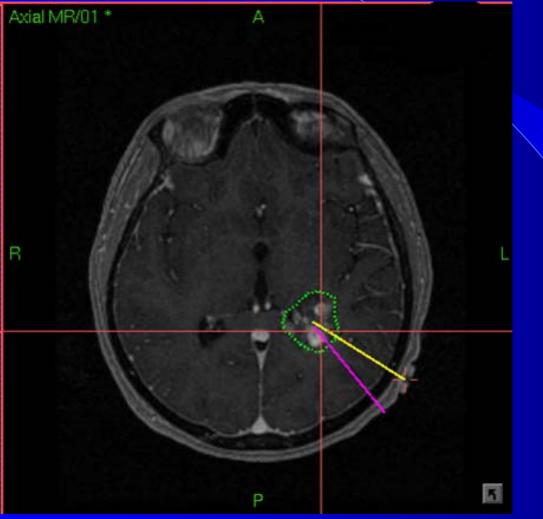
#### Giant cavernoma of left anatomical crossroads 11 march 2005







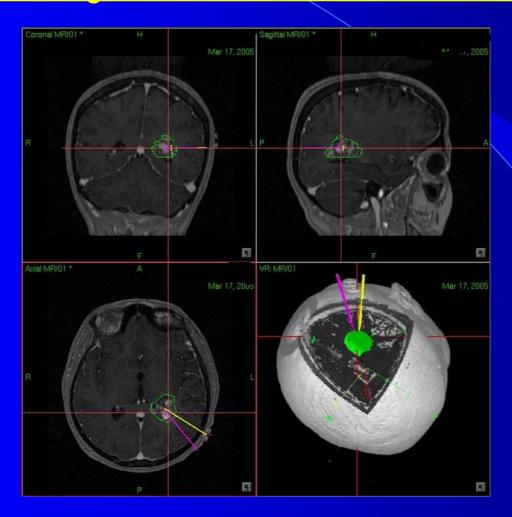
# Giant cavernoma of left anatomical crossroads 11 march 2005 Planning





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# Giant cavernoma of left anatomical crossroads 11 march 2005 Planning



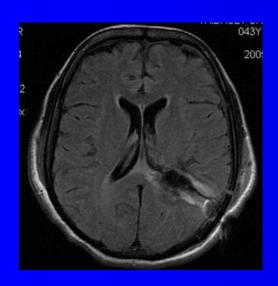


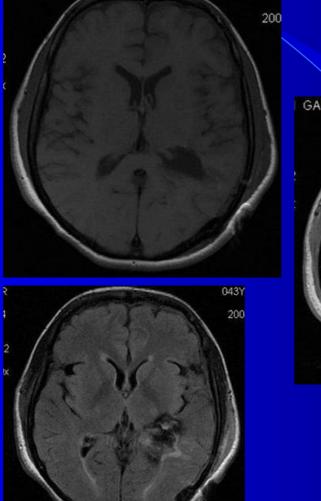
#### Robotic and Neurosurgery

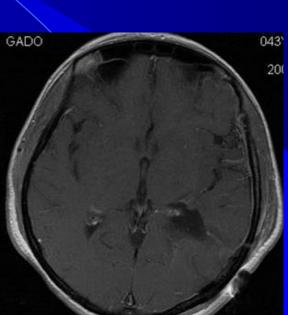
HIA Sainte-Anne, Toulon, France

Giant cavernoma of left anatomical crossroads 11 march 2005, post-op MRI at D1 Back Home at D5.

043Y



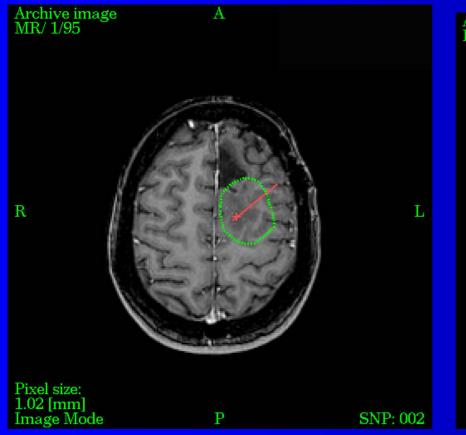


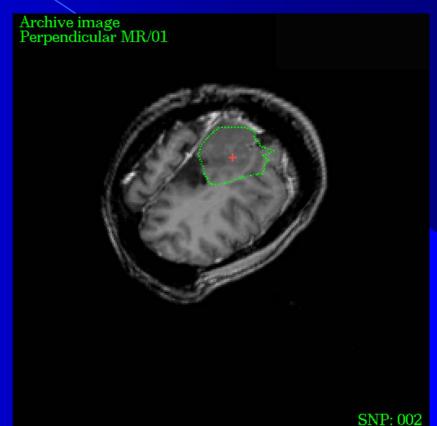




## Invisible lesion

#### ex : oligodendroglioma of Rolando area

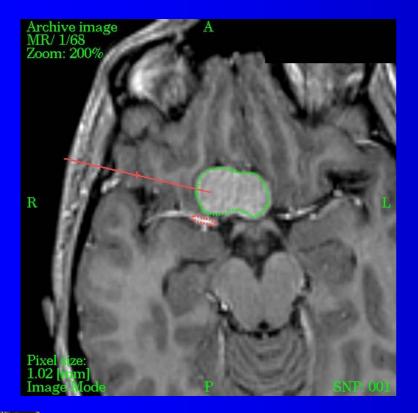


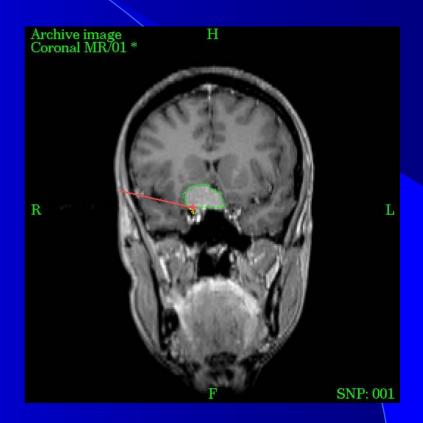




Risk area

ex : meningioma of the du tuberculum sellae







## Non imperative indications

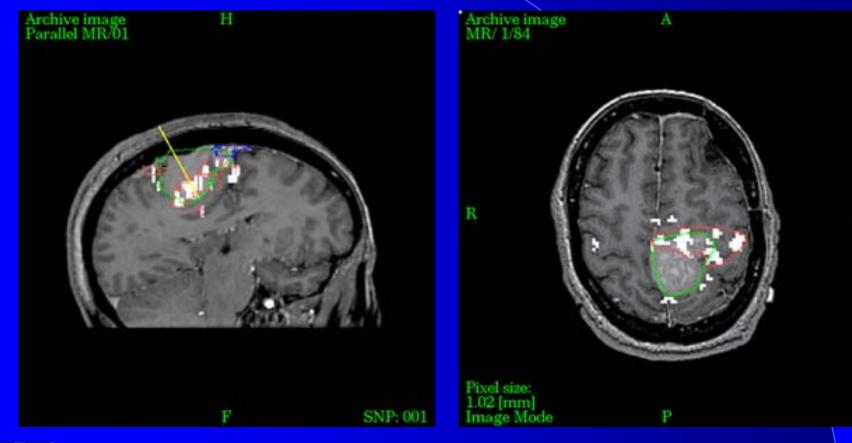
## • Superficial tumour

- Extra-parenchymatous tumour
- Big tumour
- Second look



#### Robotic and Neurosurgery

Superficial Tumour: Important interest for study of the venous drainage before craniotomy ex : meningioma of Rolando

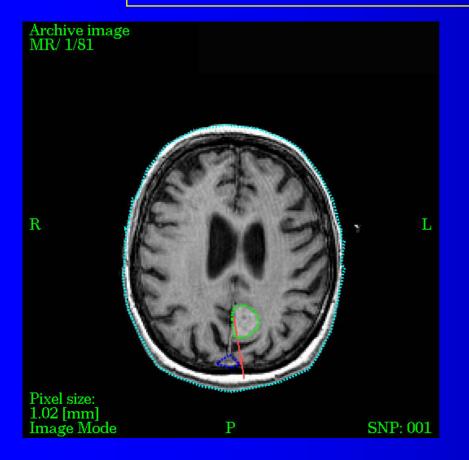


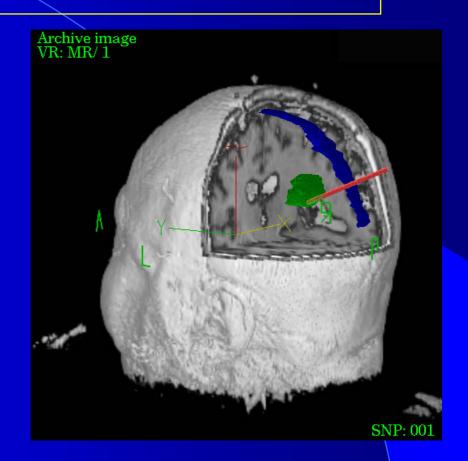




## Deep Tumour

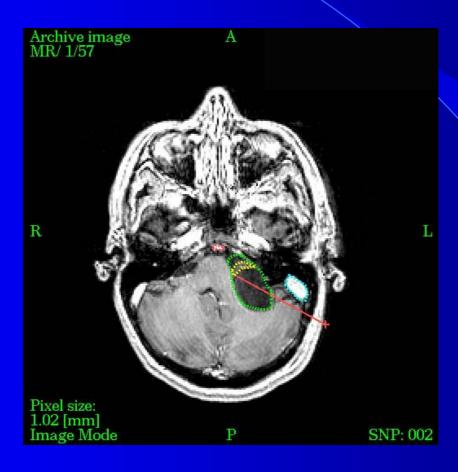
ex : Falx cerebri meningioma







### Extra-parenchymatous tumour ex : cholesteatoma of CPA



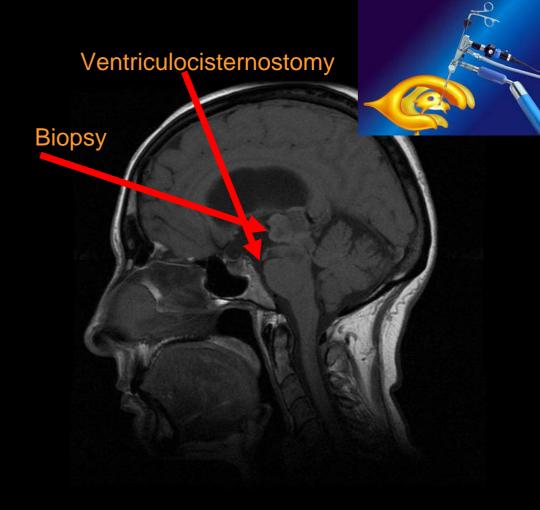


## - Stereotactic Biopsies frameless with MKM or TREON

- Navigation for Spine.
- -Images fusion with fMRI, cerebral Thallium scintigraphy, sequences of DTi FiberTract, PETscan.
- -Coupled with CO2 laser, per-operative Neuroendoscopy
- -Robotic Microsurgery assisted by endoscope and image guidance
- -Interstitial per-operative radiotherapy : Acubeam.
- -Awaked surgery for functional area tumours, coupled with per-operative brain stimulation.
- ENT applications.



## Neuroendoscopy and microsurgery assisted by endoscopy



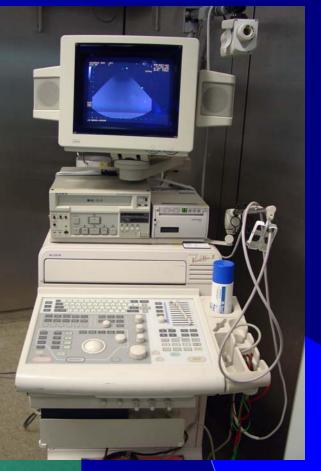
For intra-ventricular or pineal tumours.

Robotic arm can help to guide, fix and micro-movement of endoscope, or biopsy-needle Robotic and Neurosurgery

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**Biopsy coupled with ultra-sounds** Robotic arm can hold and guide US probe and biopsy needle







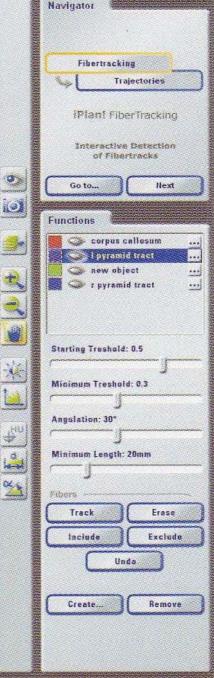
### Biopsy coupled with ultra-sound: real time per-operative control. -05-'03 0:24:00 0M SMSL NEUROCH. BWK IDI 10 DVA: 100% 42 RØ8 G86 CØ4 SONDE 2: TEE NEUROCH. BWK IDC 44. RØ8 G86 CØ4 *Cédric BERNARD, 10 September 2007* SONDE

## Spinal and cranial navigation

## Integration of DTI sequences (Diffusion Tensor Imaging) MR #1 (Axial

Coronal

## Hope in few years to come back in rebotic coupled with navigation



MR #1 (Axial

MR #1 (Axial

Sagittal

d

1 Slice

Plane View

**3D View** 

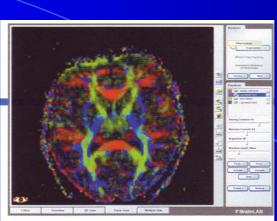
Overview

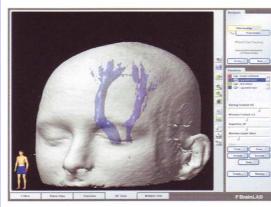
**Multiple Sets** 

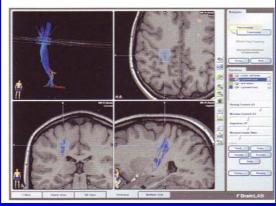
#### Robotic and Neurosurgery

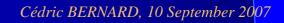












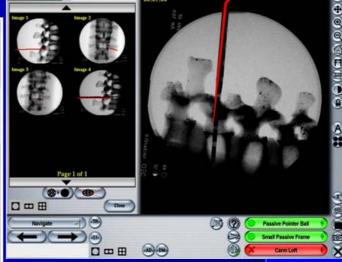


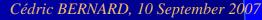
## Spine surgery: 2D Fluoronav

- Easy positioning of screws
- Visualisation of perpendicular plans to screws (Verification of right positioning of the screws)
- Definition of screw size
- Robotic arm can help to put the guide in the right trajectory define by navigation
- 15 % of wrong positioning





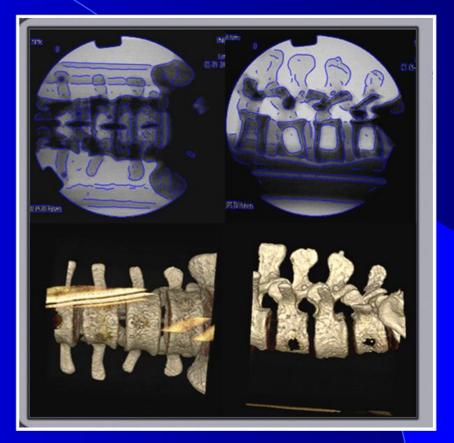






## Spine surgery: 3D FluoroMerge

- Accuracy of pedicles screw positioning
  Definition of areas to drill (Vertebral
  - tumours, arthrosis...)
- Help to put discprosthesis





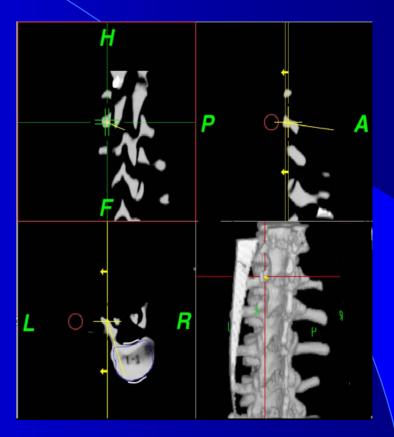
## Pedicles screw positioning





## per-operative

## Guidance mode to help for positioning the screw



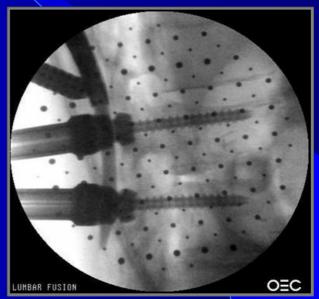


# Spine surgery: Percutaneous technique under navigation- Sextan -











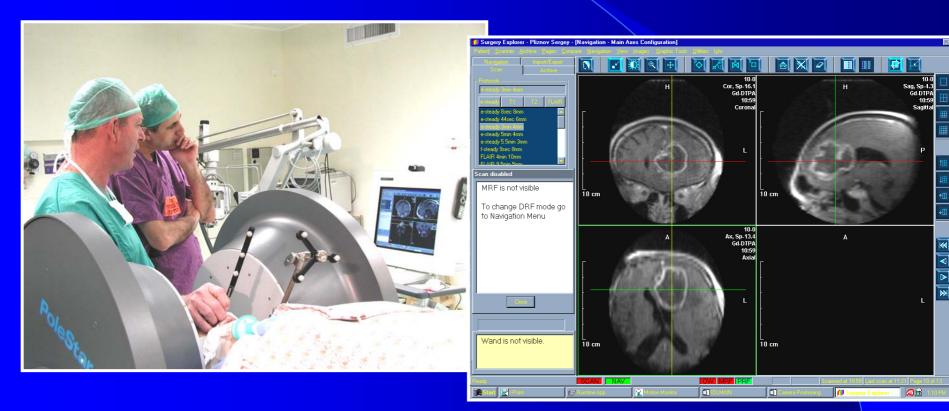
## Low field intra-operative MRI: 0,12 T and 0,20 T







## Per-operative low field MRI coupled with neuronavigation





To update navigated images ( actually SonoNav) To verify per-operatively the quality of tumour resection

### Per-operative low field MRI

## Mobile Faraday cage





HIA Sainte-Anne, Toulon, France

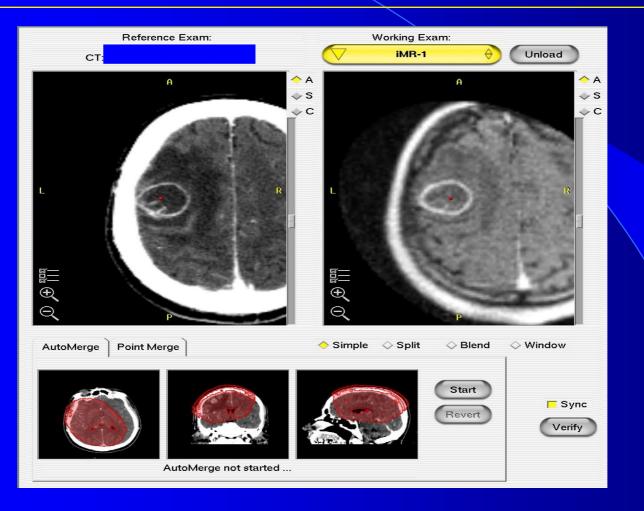
## Per-operative low field MRI « OR » Faraday cage





### Per-operative low field MRI

## images quality

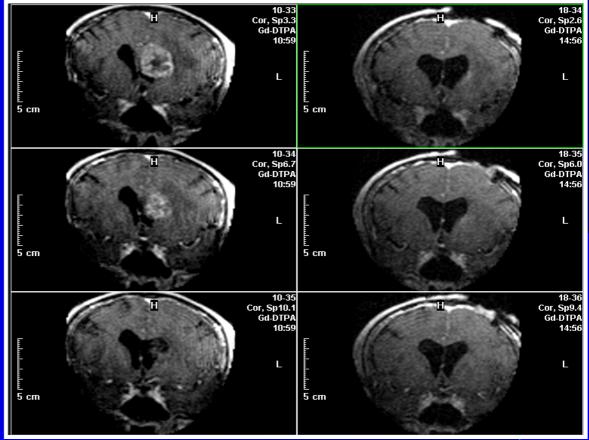




HIA Sainte-Anne, Toulon, France

## Per-operative low field MRI images quality







Another application of robotic: DBS Deep Brain Stimulation

• Neuromate robot:

## For positioning the electrodes in Parkinson's disease surgical treatment



## Now, the future !!!

- Tele-assisted Neurosurgery
- Tele-mentoring

## • Robotic can be useful.

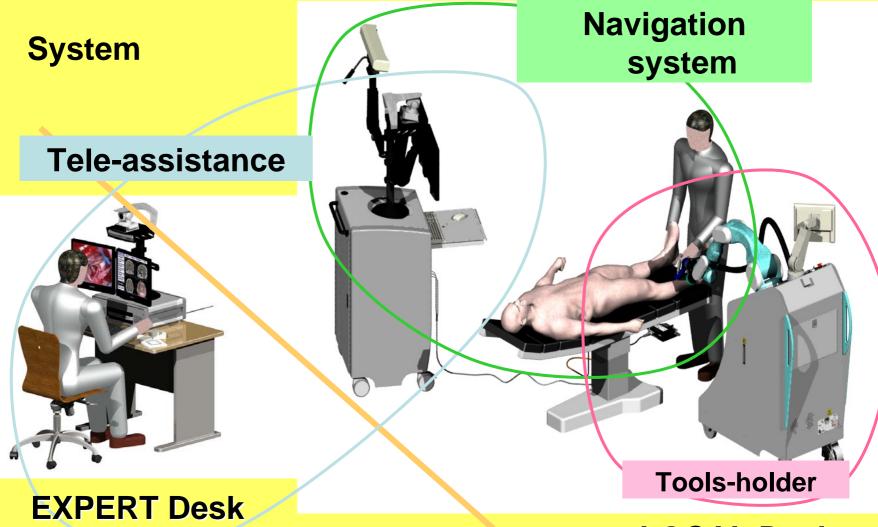


## What can we do?

- To access the operating field in the trajectory defined by the "expert" surgeon
- To define restricted areas: the robot blocks you when you want to go outside the authorized areas
- Guide-tools: endoscope, needle, electrode, drill,...
- To define drill zone, particularly for skull base ( petrous bone...)
- Voice control couple to navigation, to tell you that you arrive on a risk zone, or at the end of resection,...



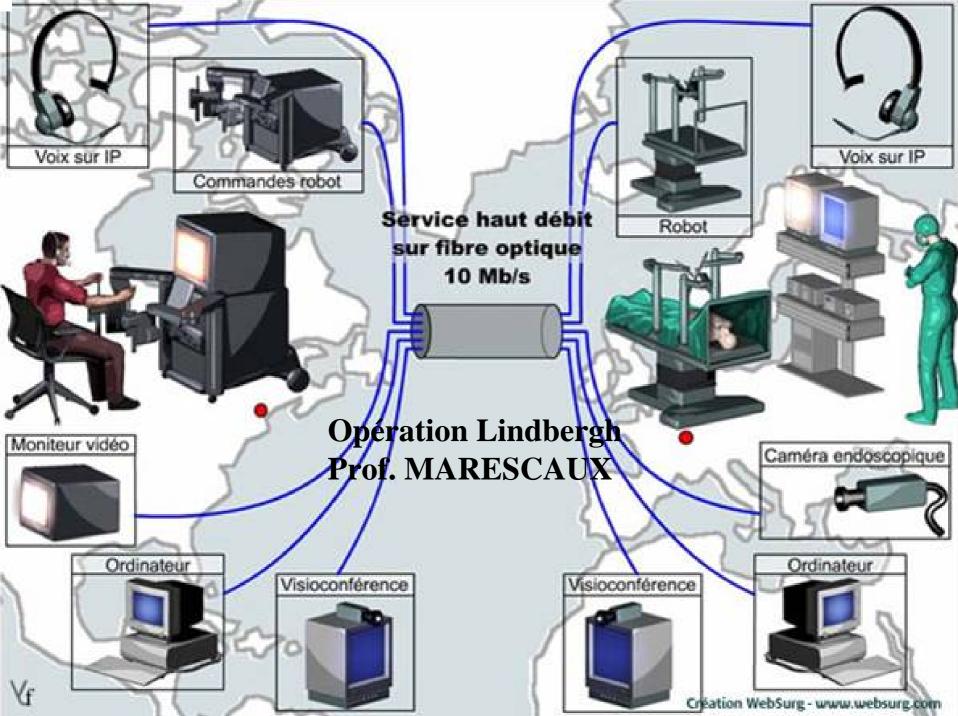
#### Robotic surgical Tele-assistance



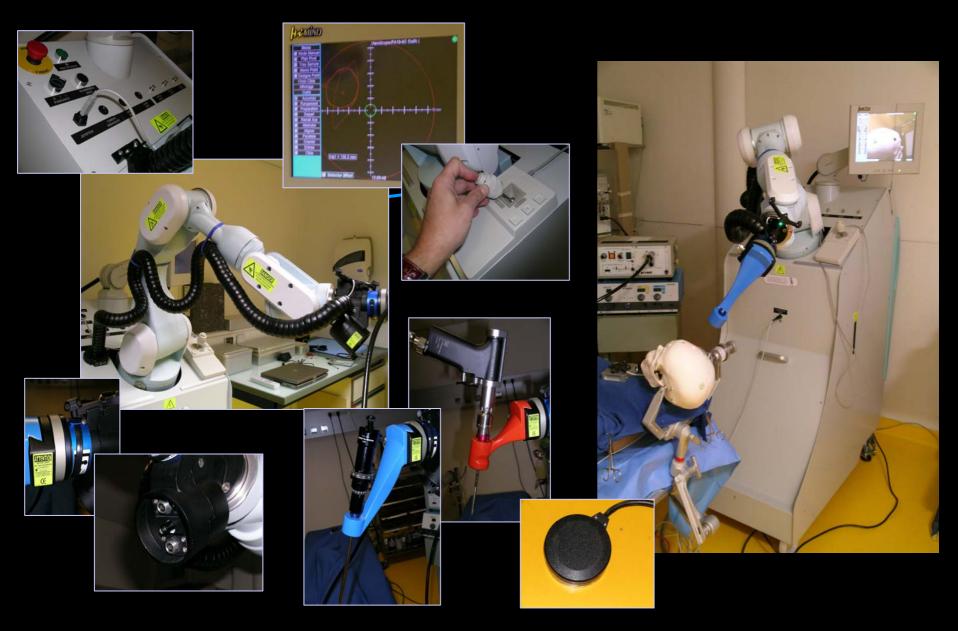
#### **LOCAL Desk**

# Demonstrator of robotic surgical tele-assistance

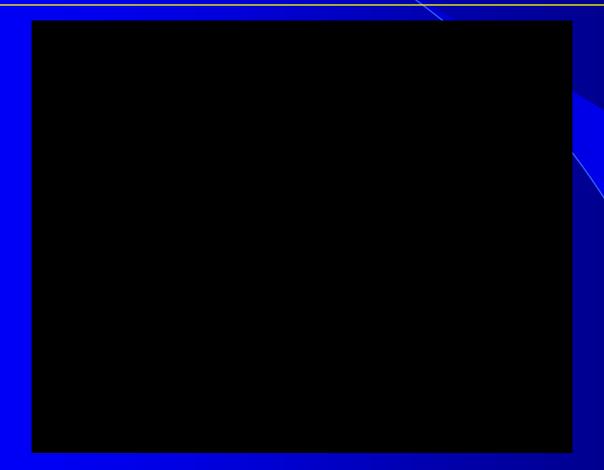
- The one-year tests are finished
- Lindbergh operation demonstrated that it's possible, but not easily and not daily
- The Armed Forces have an important interest with these techniques: we have to give the same quality of matment to soldiers who are over seas, as if they are in France.
  We have to do animals trials and to miniaturize
  - the system.



#### Tools-holder unit Operative Mode



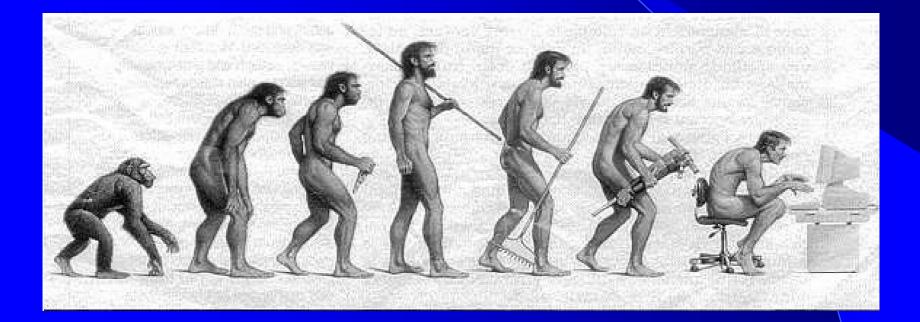
## Trial of visioconference by satellite





Cédric BERNARD, 10 September 2007

#### From barber to surgeon





*Cédric BERNARD*, 10 September 2007

# ADVANTAGES

- Accuracy
- Repeat the same movement frequently
- Stability of the guide-tool
- Mentoring on virtual procedures
- Tele-assisted surgery, for surgeons who are in foreign countries, or on hospital boat







Control the robot from the beach!!! "I had a dream"; a joke? May be, but why not?

### DISADVANTAGES

- The cost
- The learning-curve
- Durability: to deal with the sellers
- Increase the pre-operative time
- Miniaturisation is needed



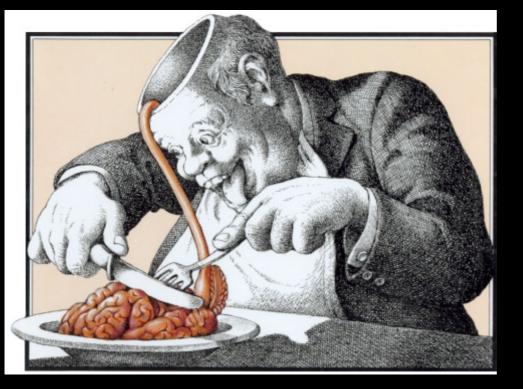
## DISADVANTAGES

The most important one and the most difficult to eliminate:

To open the minds, before opening the skull for neurosurgeons; to convince surgeon to use it and that it's only a tool. Most of neurosurgeons think is useless at that time. We heard same thing 15 years ago with neuronavigation, minimal invasive surgery, keyhole concept, and 40 years ago with the microscope,...



# Open the minds







# WHAT TO DO?

Progresses at the begins afraid:

We have to explain, convince, to change ours habits: that's the challenge and also the difficulties... ...and to keep always the control on ours tools:

That means to dominate the technique and not the opposite.



#### **CONCLUSION**

- •Primum non nocere
- •Very exciting challenge
- •Keep in mind we have to deal with good post-operative status and total removal
- •Keep humble faces a surgery that continues to be dangerous, despite the important technological progresses

Imaging progresses

Future..





•Robotic tools coupled with neuronavigation, per-operative MRI, FiberTracking,... *Cédric BERNARD, 10 September 2007* 



#### CONCLUSION

- -We use daily neuronavigation
- -Robotic surgery will be the next step
- -Star Wars, it's today, with a journey in the depth of the brain

It would be a step to develop a neurosurgical simulator To teach the young neurosurgeons.



*Cédric BERNARD*, 10 September 2007

## **CLINIQUE DES JOYEUX CHIRURGIENS**

La Vasectomie Facile...

"In the end no tool is better than the hands which hold it."

Lars Leksell 1982

Learn of the past and acquired experience to go forward future to give, always the best to ours patients.

« We are only on the way, and tenants »

62. TOULON - Hopital Sainte-Anne



Our future in 2 months, but the past for the future generations; we have to do the maintenance and upgrading of materials to give them the best at their time.



#### « Mari transve mare hominibus semper prodesse ».

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