

Twin-width and polynomial kernels

Amadeus Reinald
ENS de Lyon

joint work with
Édouard Bonnet¹, Eun Jung Kim,
Stéphan Thomassé, Rémi Watrigant

Séminaire COATI
May 3rd, 2022, INRIA Sophia-Antipolis

¹some slides have been recklessly stolen from Édouard



Overview

Twin-width:



Overview

Twin-width:

- graph invariant giving a "**structural complexity**" measure.



Overview

Twin-width:

- graph invariant giving a "**structural complexity**" measure.
- classes of small twin-width \Rightarrow efficient algorithms.



Overview

Twin-width:

- graph invariant giving a "**structural complexity**" measure.
- classes of small twin-width \Rightarrow efficient algorithms.

Polynomial kernels:



Overview

Twin-width:

- graph invariant giving a "**structural complexity**" measure.
- classes of small twin-width \Rightarrow efficient algorithms.

Polynomial kernels:

- Even **more efficient** algorithms based on pre-processing.



Overview

Twin-width:

- graph invariant giving a "**structural complexity**" measure.
- classes of small twin-width \Rightarrow efficient algorithms.

Polynomial kernels:

- Even **more efficient** algorithms based on pre-processing.

Question: What problems admit polynomial kernels for classes of small twin-width ?



Our results

Theorem (Bonnet, Kim, R., Thomassé, Watrigant '21)

On classes of bounded twin-width, CONNECTED k -VERTEX COVER admits kernels with $O(k^{1.5})$ vertices.



Our results

Theorem (Bonnet, Kim, R., Thomassé, Watrigant '21)

On classes of bounded twin-width, CONNECTED k -VERTEX COVER admits kernels with $O(k^{1.5})$ vertices.

In this talk:

Theorem (Bonnet, Kim, R., Thomassé, Watrigant '21)

Unless $\text{coNP} \subseteq \text{NP}/\text{poly}$, k -DOMINATING SET does not admit a polynomial kernel on graphs of twin-width at most 4.



- 1 Introduction
- 2 FPT
- 3 Twin-width
- 4 k -DS has no polykernels
- 5 Conclusion



Parameters for decision problems

Decision problems:

- "Does instance I admit a solution of size k ?",



Parameters for decision problems

Decision problems:

- "Does instance I admit a solution of size k ?",

For NP-hard problems, complexity exponential in $|I|$ (ETH)...



Parameters for decision problems

Decision problems:

- "Does instance I admit a solution of size k ?",

For NP-hard problems, complexity exponential in $|I|$ (ETH)...

↪ Is large $|I|$ really what makes a hard instance ?



Parameters for decision problems

Decision problems:

- "Does instance I admit a solution of size k ?",

For NP-hard problems, complexity exponential in $|I|$ (ETH)...

↪ Is large $|I|$ really what makes a hard instance ?

Goal: **Parameters** k capturing "complexity" better than $|I|$.



Parameters for decision problems

Decision problems:

- "Does instance I admit a solution of size k ?",

For NP-hard problems, complexity exponential in $|I|$ (ETH)...

↪ Is large $|I|$ really what makes a hard instance ?

Goal: **Parameters** k capturing "complexity" better than $|I|$.

- **Solution size,**



Parameters for decision problems

Decision problems:

- "Does instance I admit a solution of size k ?",

For NP-hard problems, complexity exponential in $|I|$ (ETH)...

↪ Is large $|I|$ really what makes a hard instance ?

Goal: **Parameters** k capturing "complexity" better than $|I|$.

- **Solution size,**
- Measures of "structural complexity" for graphs: diameter, genus, treewidth...



Fixed-Parameter Tractability (FPT)

Goal: small parameter instances \Rightarrow polytime algorithms.



Fixed-Parameter Tractability (FPT)

Goal: small parameter instances \Rightarrow polytime algorithms.

A **parameterized problem** has instances (I, k) with parameter k .



Fixed-Parameter Tractability (FPT)

Goal: small parameter instances \Rightarrow polytime algorithms.

A **parameterized problem** has instances (I, k) with parameter k .

Definition A parameterized problem \mathcal{Q} is **fixed-parameter tractable (FPT)** with respects to k if there is an algorithm deciding (I, k) in time $f(k)|I|^{O(1)}$, for some computable f .

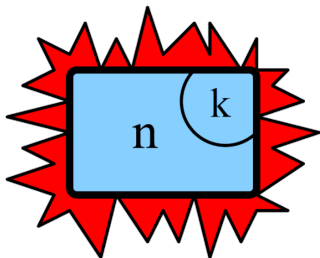


Fixed-Parameter Tractability (FPT)

Goal: small parameter instances \Rightarrow polytime algorithms.

A **parameterized problem** has instances (I, k) with parameter k .

Definition A parameterized problem \mathcal{Q} is **fixed-parameter tractable (FPT)** with respects to k if there is an algorithm deciding (I, k) in time $f(k)|I|^{O(1)}$, for some computable f .

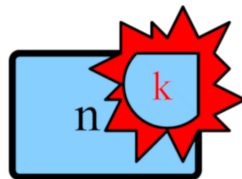
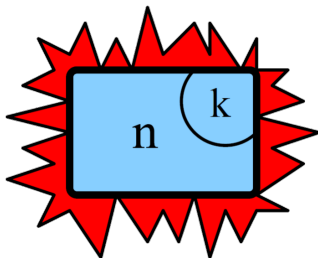


Fixed-Parameter Tractability (FPT)

Goal: small parameter instances \Rightarrow polytime algorithms.

A **parameterized problem** has instances (I, k) with parameter k .

Definition A parameterized problem \mathcal{Q} is **fixed-parameter tractable (FPT)** with respects to k if there is an algorithm deciding (I, k) in time $f(k)|I|^{O(1)}$, for some computable f .



FPT Examples

Examples of FPT problems:

- k -VERTEX COVER parameterized by solution size k :
 \hookrightarrow instance (G, k) solvable in time $O(f(k)|G|^3)$.



FPT Examples

Examples of FPT problems:

- k -VERTEX COVER parameterized by solution size k :
 \hookrightarrow instance (G, k) solvable in time $O(f(k)|G|^3)$.
- HAMILTONIAN CYCLE parameterized by treewidth tw :
 \hookrightarrow instance (G, tw) solvable in time $O(tw^{tw}|G|)$



Kernels

How to devise an FPT algorithm? One strategy:



Kernels

How to devise an FPT algorithm? One strategy:

- Pre-process input to get rid of "useless" information,



Kernels

How to devise an FPT algorithm? One strategy:

- Pre-process input to get rid of "useless" information,
- obtain "small" sized instance dependent only on k ,



Kernels

How to devise an FPT algorithm? One strategy:

- Pre-process input to get rid of "useless" information,
- obtain "small" sized instance dependent only on k ,
- Run bruteforce \rightarrow complexity explosion only in k .



Kernels

How to devise an FPT algorithm? One strategy:

- Pre-process input to get rid of "useless" information,
- obtain "small" sized instance dependent only on k ,
- Run bruteforce \rightarrow complexity explosion only in k .

Definition *Kernel* for parameterized problem \mathcal{Q} :

- Polytime reduction from instance (I, k) for \mathcal{Q} to equivalent instance (I', k') for \mathcal{Q} .
- output instance has size $|I'| = h(k)$, and k' is bounded by a function of k .



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.

For FPT problems, can we get even **more efficient**?



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.

For FPT problems, can we get even **more efficient**?

- $\text{FPT} \Rightarrow \text{Kernel}$, but the kernel size can be very large...



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.

For FPT problems, can we get even **more efficient**?

- $\text{FPT} \Rightarrow \text{Kernel}$, but the kernel size can be very large...
- A kernel for parameter k is **polynomial** if $|I'| = O(k^p)$.



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.

For FPT problems, can we get even **more efficient**?

- $\text{FPT} \Rightarrow \text{Kernel}$, but the kernel size can be very large...
- A kernel for parameter k is **polynomial** if $|I'| = O(k^p)$.

Problems with polynomial kernels:



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.

For FPT problems, can we get even **more efficient**?

- $\text{FPT} \Rightarrow \text{Kernel}$, but the kernel size can be very large...
- A kernel for parameter k is **polynomial** if $|I'| = O(k^p)$.

Problems with polynomial kernels:

- k -VERTEX-COVER, k -DOMINATING-SET on sparse graphs ($K_{t,t}$ -free).



Better than FPT: polynomial kernels

Theorem

A parameterized problem is FPT iff it admits a kernel.

For FPT problems, can we get even **more efficient**?

- $\text{FPT} \Rightarrow \text{Kernel}$, but the kernel size can be very large...
- A kernel for parameter k is **polynomial** if $|I'| = O(k^p)$.

Problems with polynomial kernels:

- k -VERTEX-COVER, k -DOMINATING-SET on sparse graphs ($K_{t,t}$ -free).

↪ can we prove that a problem has no polykernel?



Example: k -LONGEST PATH

LONGEST PATH

Parameter: k

Input: Graph G , integer k

Question: Does G have a simple path of length k ?



Example: k -LONGEST PATH

LONGEST PATH

Parameter: k

Input: Graph G , integer k

Question: Does G have a simple path of length k ?

- NP-hard, but FPT: admits a $2^k n^c$ algorithm, thus a kernel,



Example: k -LONGEST PATH

LONGEST PATH

Parameter: k

Input: Graph G , integer k

Question: Does G have a simple path of length k ?

- NP-hard, but FPT: admits a $2^k n^c$ algorithm, thus a kernel,
- what about a polynomial kernel?



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,
- Take $G = \bigcup_{i=1}^t G_i$, and consider instance (G, k) ,



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,
- Take $G = \bigcup_{i=1}^t G_i$, and consider instance (G, k) ,
- Polykernel returns (G', k') from (G, k) in $\text{poly}(n)$.



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,
- Take $G = \bigcup_{i=1}^t G_i$, and consider instance (G, k) ,
- Polykernel returns (G', k') from (G, k) in $\text{poly}(n)$.

(G, k) is positive $\Leftrightarrow (G', k')$ is positive $\Leftrightarrow \exists i : (G_i, k)$ is positive.



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,
- Take $G = \bigcup_{i=1}^t G_i$, and consider instance (G, k) ,
- Polykernel returns (G', k') from (G, k) in $\text{poly}(n)$.

(G, k) is positive $\Leftrightarrow (G', k')$ is positive $\Leftrightarrow \exists i : (G_i, k)$ is positive.

- G' is computed in polytime,



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,
- Take $G = \bigcup_{i=1}^t G_i$, and consider instance (G, k) ,
- Polykernel returns (G', k') from (G, k) in $\text{poly}(n)$.

(G, k) is positive $\Leftrightarrow (G', k')$ is positive $\Leftrightarrow \exists i : (G_i, k)$ is positive.

- G' is computed in polytime,
- G' is (very) small: $|G'| \leq k^c \leq n^c < t$: **less than one bit per initial instance**,



k -LONGEST PATH has no polykernels (morally)

Assume polykernel of size k^c .

- Consider $t = n^c + 1$ instances $(G_1, k), \dots, (G_t, k)$, with $n = |G_i|$,
- Take $G = \bigcup_{i=1}^t G_i$, and consider instance (G, k) ,
- Polykernel returns (G', k') from (G, k) in $\text{poly}(n)$.

(G, k) is positive $\Leftrightarrow (G', k')$ is positive $\Leftrightarrow \exists i : (G_i, k)$ is positive.

- G' is computed in polytime,
- G' is (very) small: $|G'| \leq k^c \leq n^c < t$: **less than one bit per initial instance**,
- kernelization must have dismissed / "solved" one G_i entirely... in polynomial time \rightarrow absurd.



Ruling out polynomial kernels

Formalization: given problem \mathcal{L} , and parameterized problem \mathcal{Q} .

Definition 2.1 (OR-composition) Polytime reduction:



Ruling out polynomial kernels

Formalization: given problem \mathcal{L} , and parameterized problem \mathcal{Q} .

Definition 2.2 (OR-composition) Polytime reduction:

- Input: Instances I_1, \dots, I_t for \mathcal{L} ,



Ruling out polynomial kernels

Formalization: given problem \mathcal{L} , and parameterized problem \mathcal{Q} .

Definition 2.3 (OR-composition) Polytime reduction:

- Input: Instances I_1, \dots, I_t for \mathcal{L} ,
- Output: Instance J for \mathcal{Q} .



Ruling out polynomial kernels

Formalization: given problem \mathcal{L} , and parameterized problem \mathcal{Q} .

Definition 2.4 (OR-composition) Polytime reduction:

- Input: Instances I_1, \dots, I_t for \mathcal{L} ,
- Output: Instance J for \mathcal{Q} .

J is positive for $\mathcal{Q} \Leftrightarrow \exists i$ s.t. I_i is positive for \mathcal{L} .



Ruling out polynomial kernels

Formalization: given problem \mathcal{L} , and parameterized problem \mathcal{Q} .

Definition 2.5 (OR-composition) Polytime reduction:

- Input: Instances I_1, \dots, I_t for \mathcal{L} ,
- Output: Instance J for \mathcal{Q} .

J is positive for $\mathcal{Q} \Leftrightarrow \exists i$ s.t. I_i is positive for \mathcal{L} .

Theorem (Bodlaender, Jansen, Kratsch '12)

If an NP-hard problem \mathcal{L} admits an OR-composition into a parameterized problem \mathcal{Q} , then \mathcal{Q} does not admit a polynomial kernel unless $\text{coNP} \subseteq \text{NP}/\text{poly}$.



Graph invariants and FPT

"Meta-theorems" for problems expressible by logic formulas:

²given a tree decomposition



Graph invariants and FPT

"Meta-theorems" for problems expressible by logic formulas:

Theorem 1 (Courcelle '90) *Given a **MSO formula** ϕ on a graph G , deciding whether ϕ is satisfied by G is **FPT** in $|\phi|$ on graphs of **bounded tree-width**².*

²given a tree decomposition



Graph invariants and FPT

"Meta-theorems" for problems expressible by logic formulas:

Theorem 1 (Courcelle '90) *Given a **MSO formula** ϕ on a graph G , deciding whether ϕ is satisfied by G is **FPT** in $|\phi|$ on graphs of **bounded tree-width**².*

Lot of **FO** problems are FPT on some classes of unbounded tw, goal:

- Analogue of Courcelle for FO logic ?
- With some **broader** parameter than tw

²given a tree decomposition



Graph invariants and FPT

"Meta-theorems" for problems expressible by logic formulas:

Theorem 1 (Courcelle '90) *Given a **MSO formula** ϕ on a graph G , deciding whether ϕ is satisfied by G is **FPT** in $|\phi|$ on graphs of **bounded tree-width**².*

Lot of **FO** problems are FPT on some classes of unbounded tw, goal:

- Analogue of Courcelle for FO logic ?
- With some **broader** parameter than tw **twin-width**

²given a tree decomposition



Motivation

Definition In graph G , $u, v \in V(G)$ are **twins** if $N(u) = N(v)$.



Motivation

Definition In graph G , $u, v \in V(G)$ are **twins** if $N(u) = N(v)$.

- Twins "behave the same" w.r.t the rest of the graph,



Motivation

Definition In graph G , $u, v \in V(G)$ are **twins** if $N(u) = N(v)$.

- Twins "behave the same" w.r.t the rest of the graph,
- exploitable algorithmically: modular decomposition, cographs...



Motivation

Definition In graph G , $u, v \in V(G)$ are **twins** if $N(u) = N(v)$.

- Twins "behave the same" w.r.t the rest of the graph,
- exploitable algorithmically: modular decomposition, cographs...



Motivation

Definition In graph G , $u, v \in V(G)$ are **twins** if $N(u) = N(v)$.

- Twins "behave the same" w.r.t the rest of the graph,
- exploitable algorithmically: modular decomposition, cographs...

Idea:

- Obtain efficient algorithms by leveraging "**near-twins**",



Motivation

Definition In graph G , $u, v \in V(G)$ are **twins** if $N(u) = N(v)$.

- Twins "behave the same" w.r.t the rest of the graph,
- exploitable algorithmically: modular decomposition, cographs...

Idea:

- Obtain efficient algorithms by leveraging "**near-twins**",
- Efficiency depends on how "**near**" vertices are to being twins
→ twin-**width**.



Graphs and trigraphs

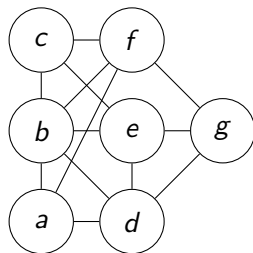


Fig. Graph: edges, non-edges



Graphs and trigraphs

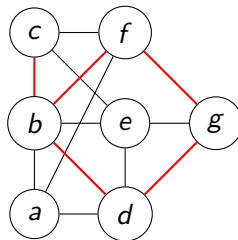
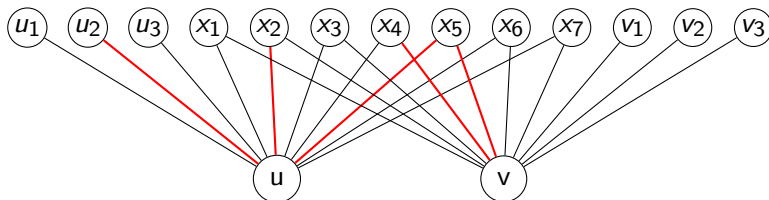


Fig. Trigraph: edges, non-edges, or **red** edges



Contractions in trigraphs

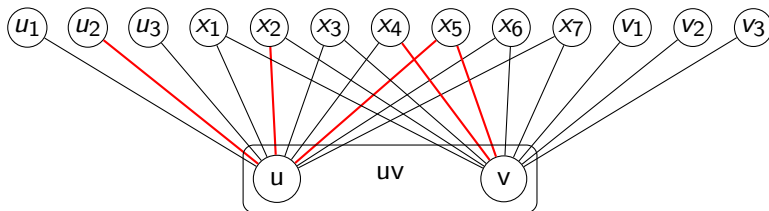
Intuitive goal: group near-twins together.



Contractions in trigraphs

Intuitive goal: group near-twins together.

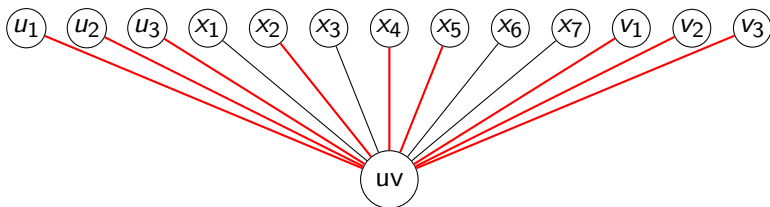
Contraction of u and v : record "twin" errors with red edges.



Contractions in trigraphs

Intuitive goal: group near-twins together.

Contraction of u and v : record "twin" errors with red edges.

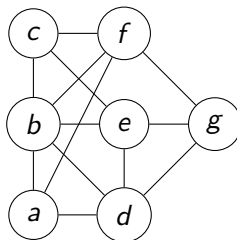


edges to $N(u) \Delta N(v)$ turn red, for $N(u) \cap N(v)$ red is absorbing



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .

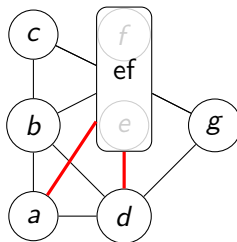


Maximum red degree = 0
overall maximum red degree = 0



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .

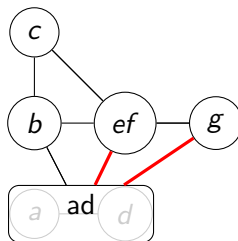


Maximum red degree = 2
overall maximum red degree = 2



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .

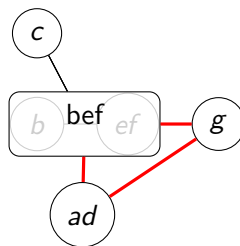


Maximum red degree = 2
overall maximum red degree = 2



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .

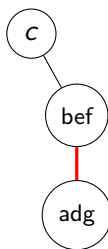


Maximum red degree = 2
overall maximum red degree = 2



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .

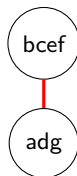


Maximum red degree = 1
overall maximum red degree = 2



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .



Maximum red degree = 1
overall maximum red degree = 2



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .



Maximum red degree = 0
overall maximum red degree = 2 .



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .



Maximum red degree = 0

overall maximum red degree = 2 $\rightarrow tww(G) \leq 2$.



Twin-width

Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree** at most d .

- Contraction sequences \rightarrow dynamic programming
-



Twin-width

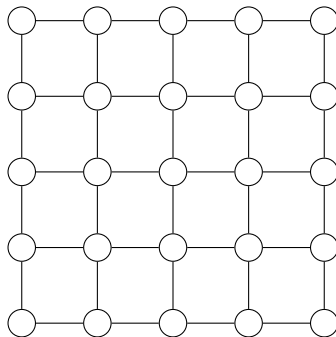
Definition (Twin-width) $tww(G)$: minimal d such that G admits a **contraction sequence** where all trigraphs have **maximum red degree at most d** .

- Contraction sequences \rightarrow dynamic programming
- bounded red degree \rightarrow few "complicated" updates.



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



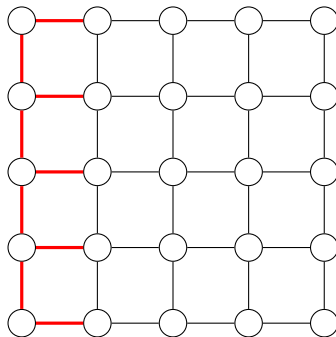
Maximum red degree = 0

overall maximum red degree = 0



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



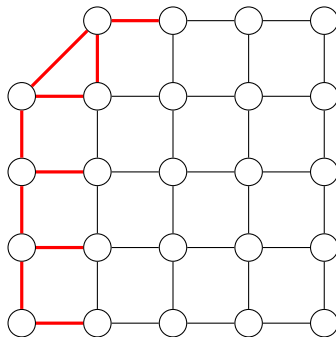
Maximum red degree = 3

overall maximum red degree = 3



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



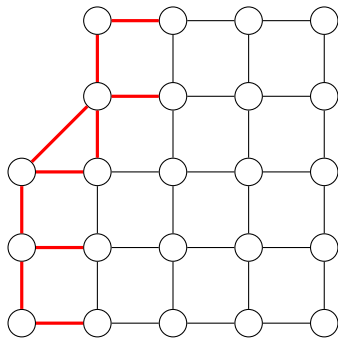
Maximum red degree = 4

overall maximum red degree = 4



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



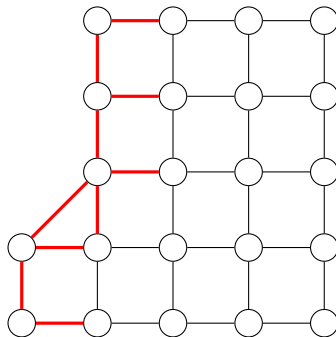
Maximum red degree = 4

overall maximum red degree = 4



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



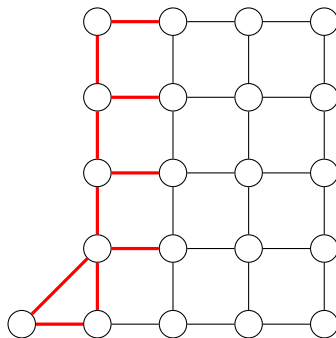
Maximum red degree = 4

overall maximum red degree = 4



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



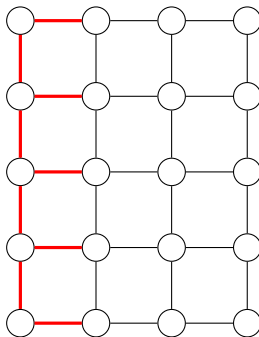
Maximum red degree = 4

overall maximum red degree = 4



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



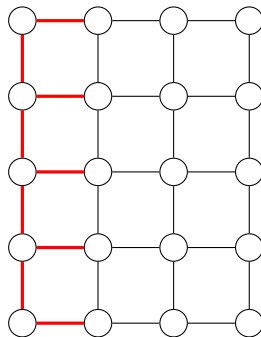
Maximum red degree = 3

overall maximum red degree = 4



Example: twin-width of grids

Grids have unbounded tree-width... what about twin-width?



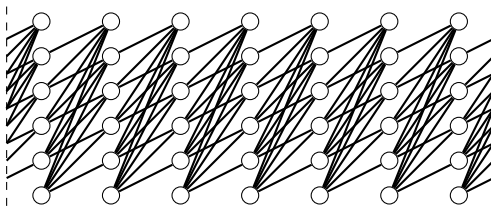
Maximum red degree = 3

overall maximum red degree = 4 \Rightarrow twin-width ≤ 4



Example: Half-Graph Cycles

A dense graph with bounded twin-width:



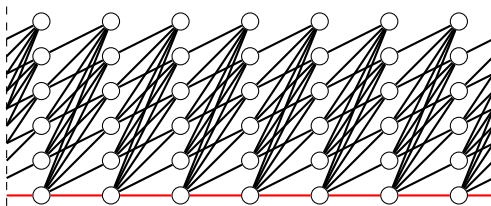
Maximum red degree = 0

overall maximum red degree = 0



Example: Half-Graph Cycles

A dense graph with bounded twin-width:



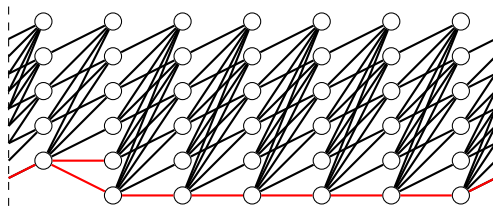
Maximum red degree = 2

overall maximum red degree = 2



Example: Half-Graph Cycles

A dense graph with bounded twin-width:



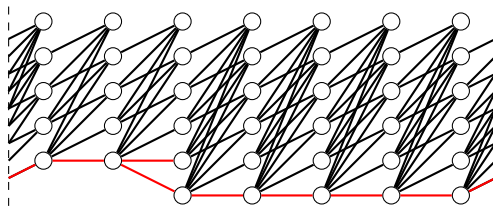
Maximum red degree = 3

overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:

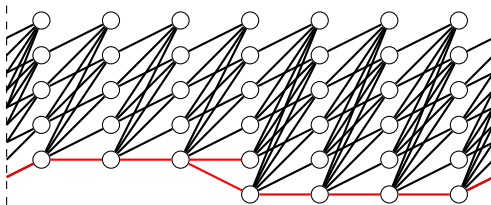


Maximum red degree = 3
overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:

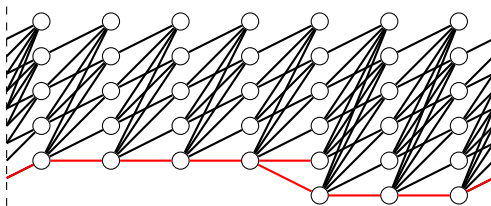


Maximum red degree = 3
overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:

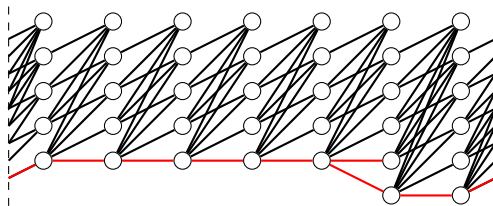


Maximum red degree = 3
overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:

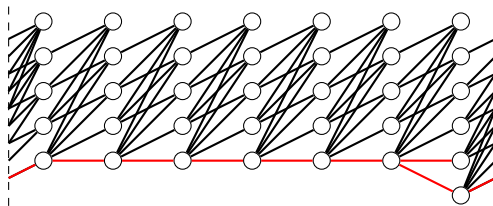


Maximum red degree = 3
overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:

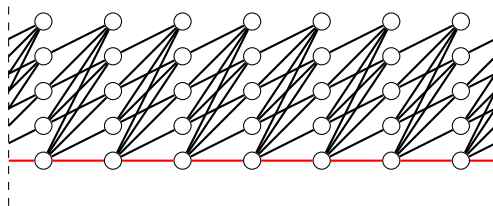


Maximum red degree = 3
overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:



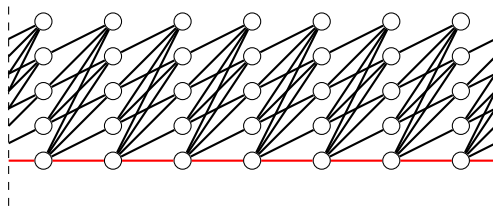
Maximum red degree = 2

overall maximum red degree = 3



Example: Half-Graph Cycles

A dense graph with bounded twin-width:



Maximum red degree = 2

overall maximum red degree = 3 \Rightarrow twin-width ≤ 3



Twin-width : FPT first order problems

Recall Courcelle for MSO and tree-width:

-
- ³given a tree decomposition
 - ⁴given a contraction sequence



Twin-width : FPT first order problems

Recall Courcelle for MSO and tree-width:

Theorem (Courcelle '90)

Given a **MSO formula** ϕ on a graph G , deciding ϕ on G is **FPT** in $|\phi|$ on graphs of **bounded tree-width**³.

³given a tree decomposition

⁴given a contraction sequence



Twin-width : FPT first order problems

Recall Courcelle for MSO and tree-width:

Theorem (Courcelle '90)

Given a **MSO formula** ϕ on a graph G , deciding ϕ on G is **FPT** in $|\phi|$ on graphs of **bounded tree-width**³.

Analogue: FO and twin-width:

³given a tree decomposition

⁴given a contraction sequence



Twin-width : FPT first order problems

Recall Courcelle for MSO and tree-width:

Theorem (Courcelle '90)

Given a **MSO formula** ϕ on a graph G , deciding ϕ on G is **FPT** in $|\phi|$ on graphs of **bounded tree-width**³.

Analogue: FO and twin-width:

Theorem (Bonnet, Kim, Thomassé, Watrigant '20)

Given a **FO formula** ϕ on a graph G , deciding ϕ on G is **FPT** with respects to $|\phi|$ on classes of **bounded twin-width**⁴.

³given a tree decomposition

⁴given a contraction sequence



Consequences

Some **problems** expressible in FO:



Consequences

Some **problems** expressible in FO:

- k -IS : $\exists x_1 \dots \exists x_k \wedge_{1 \leq i \leq j \leq k} \neg(x_i = x_j \vee E(x_i, x_j))$,



Consequences

Some **problems** expressible in FO:

- k -IS : $\exists x_1 \dots \exists x_k \bigwedge_{1 \leq i \leq j \leq k} \neg(x_i = x_j \vee E(x_i, x_j))$,
- k -DS : $\exists x_1 \dots \exists x_k \forall x \bigvee_{1 \leq i \leq k} (x = x_i) \vee \bigvee_{1 \leq i \leq k} E(x, x_i)$.

are **FPT in solution size k** for bounded tww.



Consequences

Some **problems** expressible in FO:

- k -IS : $\exists x_1 \dots \exists x_k \bigwedge_{1 \leq i \leq j \leq k} \neg(x_i = x_j \vee E(x_i, x_j))$,
- k -DS : $\exists x_1 \dots \exists x_k \forall x \bigvee_{1 \leq i \leq k} (x = x_i) \vee \bigvee_{1 \leq i \leq k} E(x, x_i)$.

are **FPT in solution size** k for bounded tww.

Some **classes** of bounded twin-width:



Consequences

Some **problems** expressible in FO:

- k -IS : $\exists x_1 \dots \exists x_k \bigwedge_{1 \leq i \leq j \leq k} \neg(x_i = x_j \vee E(x_i, x_j))$,
- k -DS : $\exists x_1 \dots \exists x_k \forall x \bigvee_{1 \leq i \leq k} (x = x_i) \vee \bigvee_{1 \leq i \leq k} E(x, x_i)$.

are **FPT in solution size** k for bounded tww.

Some **classes** of bounded twin-width:

- Bounded tree-width, rank-width, queue number...



Consequences

Some **problems** expressible in FO:

- k -IS : $\exists x_1 \dots \exists x_k \bigwedge_{1 \leq i \leq j \leq k} \neg(x_i = x_j \vee E(x_i, x_j))$,
- k -DS : $\exists x_1 \dots \exists x_k \forall x \bigvee_{1 \leq i \leq k} (x = x_i) \vee \bigvee_{1 \leq i \leq k} E(x, x_i)$.

are **FPT in solution size** k for bounded tww.

Some **classes** of bounded twin-width:

- Bounded tree-width, rank-width, queue number...
- Proper minor closed \rightarrow planar graphs.



Consequences

Some **problems** expressible in FO:

- k -IS : $\exists x_1 \dots \exists x_k \bigwedge_{1 \leq i \leq j \leq k} \neg(x_i = x_j \vee E(x_i, x_j))$,
- k -DS : $\exists x_1 \dots \exists x_k \forall x \bigvee_{1 \leq i \leq k} (x = x_i) \vee \bigvee_{1 \leq i \leq k} E(x, x_i)$.

are **FPT in solution size** k for bounded tww.

Some **classes** of bounded twin-width:

- Bounded tree-width, rank-width, queue number...
- Proper minor closed \rightarrow planar graphs.

\hookrightarrow very broad !



Twin-width and polykernels

On classes of bounded twin-width:



Twin-width and polykernels

On classes of bounded twin-width:

- Connected k -VC admits a $O(k^2)$ kernel,



Twin-width and polykernels

On classes of bounded twin-width:

- Connected *k*-VC admits a $O(k^2)$ kernel,
- *k*-Independent Set admits no polykernel.



Twin-width and polykernels

On classes of bounded twin-width:

- Connected k -VC admits a $O(k^2)$ kernel,
- k -Independent Set admits no polykernel.

What about dominating set ?



Twin-width and polykernels

On classes of bounded twin-width:

- Connected k -VC admits a $O(k^2)$ kernel,
- k -Independent Set admits no polykernel.

What about dominating set ?

k -DOMINATING SET

Parameter: k

Input: Graph G , integer k

Question: Does G have a dominating set of size at most k ?



Twin-width and polykernels

On classes of bounded twin-width:

- Connected k -VC admits a $O(k^2)$ kernel,
- k -Independent Set admits no polykernel.

What about dominating set ?

k -DOMINATING SET

Parameter: k

Input: Graph G , integer k

Question: Does G have a dominating set of size at most k ?

Admits polykernels on sparse graphs... **but not on bounded twin-width.**



OR-composition for k -DS

Recall the tool to prove no polykernels:



OR-composition for k -DS

Recall the tool to prove no polykernels:

Theorem (Bodlaender, Jansen, Kratsch '12)

If an NP-hard problem \mathcal{L} admits an OR-composition into a parameterized problem \mathcal{Q} , then \mathcal{Q} does not admit a polynomial kernel unless $\text{coNP} \subseteq \text{NP/poly}$.



OR-composition for *k*-DS

Recall the tool to prove no polykernels:

Theorem (Bodlaender, Jansen, Kratsch '12)

If an NP-hard problem \mathcal{L} admits an OR-composition into a parameterized problem \mathcal{Q} , then \mathcal{Q} does not admit a polynomial kernel unless $\text{coNP} \subseteq \text{NP/poly}$.

Goal: rule out polynomial kernels for *k*-DS on classes of bounded twin-width.



OR-composition for *k*-DS

Recall the tool to prove no polykernels:

Theorem (Bodlaender, Jansen, Kratsch '12)

If an NP-hard problem \mathcal{L} admits an OR-composition into a parameterized problem \mathcal{Q} , then \mathcal{Q} does not admit a polynomial kernel unless $\text{coNP} \subseteq \text{NP/poly}$.

Goal: rule out polynomial kernels for *k*-DS on classes of bounded twin-width.

- \mathcal{Q} : *k*-DS on a class of bounded twin-width (≤ 4).



OR-composition for *k*-DS

Recall the tool to prove no polykernels:

Theorem (Bodlaender, Jansen, Kratsch '12)

If an NP-hard problem \mathcal{L} admits an OR-composition into a parameterized problem \mathcal{Q} , then \mathcal{Q} does not admit a polynomial kernel unless $\text{coNP} \subseteq \text{NP/poly}$.

Goal: rule out polynomial kernels for *k*-DS on classes of bounded twin-width.

- \mathcal{Q} : *k*-DS on a class of bounded twin-width (≤ 4).
- \mathcal{L} : NP-hard problem tailored to be "easily" composable into \mathcal{Q} . A version of *k*-DS on graphs of bounded twin-width.



Tailored k -DS on grid-like graphs

NP-hard \mathcal{L} : k -DS on instances $(G, k, \mathcal{B} = \{B_1, \dots, B_k\})$ s.t:

- \mathcal{B} partitions $V(G)$, G has 4-sequence $\rightarrow G/\mathcal{B}$,
- G/\mathcal{B} is a subgraph of a grid,



Tailored k-DS on grid-like graphs

NP-hard \mathcal{L} : k-DS on instances $(G, k, \mathcal{B} = \{B_1, \dots, B_k\})$ s.t:

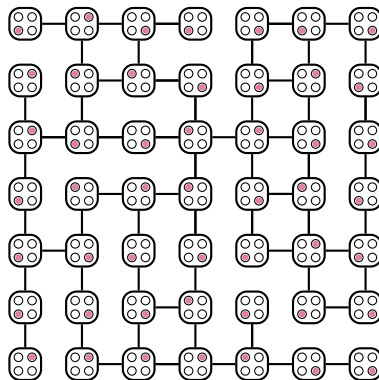
- \mathcal{B} partitions $V(G)$, G has 4-sequence $\rightarrow G/\mathcal{B}$,
- G/\mathcal{B} is a subgraph of a grid,
- every dominating set of G intersects each B_i .



Tailored k-DS on grid-like graphs

NP-hard \mathcal{L} : k-DS on instances $(G, k, \mathcal{B} = \{B_1, \dots, B_k\})$ s.t:

- \mathcal{B} partitions $V(G)$, G has 4-sequence $\rightarrow G/\mathcal{B}$,
- G/\mathcal{B} is a subgraph of a grid,
- every dominating set of G intersects each B_i .



OR-composition

Tailored *k*-DS, instances $(I_i)_{i \in [t]} \rightarrow k\text{-DS}$, $tw \leq 4$ instance (H, k)



OR-composition

Tailored k -DS, instances $(I_i)_{i \in [t]} \rightarrow k$ -DS, $tww \leq 4$ instance (H, k)

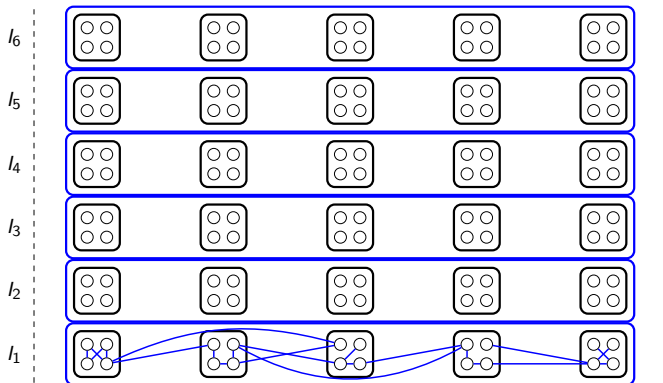


Fig. Instances \leftrightarrow layers, partition classes \leftrightarrow boxes.



OR-composition

Tailored k -DS, instances $(I_i)_{i \in [t]} \rightarrow k$ -DS, $tww \leq 4$ instance (H, k)

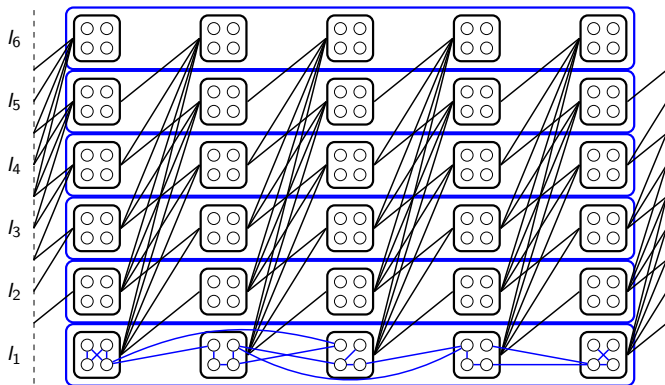


Fig. Instances \leftrightarrow layers, partition classes \leftrightarrow boxes.

In H : Top instance \leftrightarrow dummy, half graphs cycle between classes



Positive Tailored instance \Rightarrow Positive composition

Assume one instance (I_4 here) is positive, pick its solution in H :

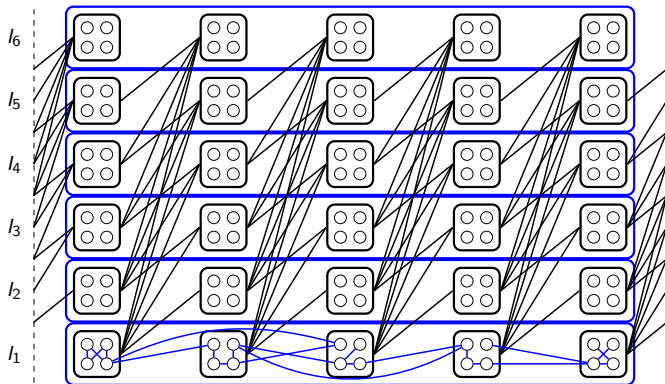


Fig. t Instances \leftrightarrow layers, k partition classes \leftrightarrow boxes



Assume one instance (I_4 here) is positive, pick its solution in H :

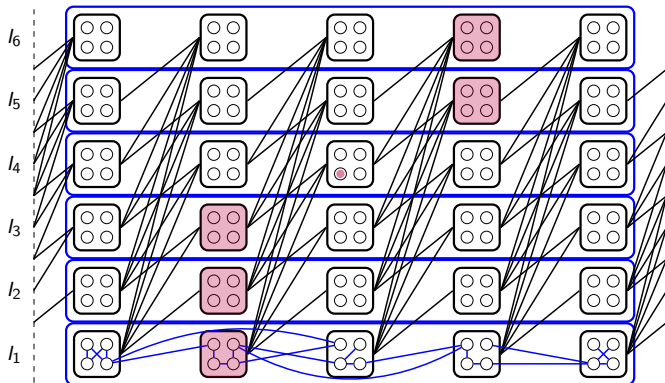


Fig. t Instances \leftrightarrow layers, k partition classes \leftrightarrow boxes



Positive Tailored instance \Rightarrow Positive composition

Assume one instance (I_4 here) is positive, pick its solution in H :

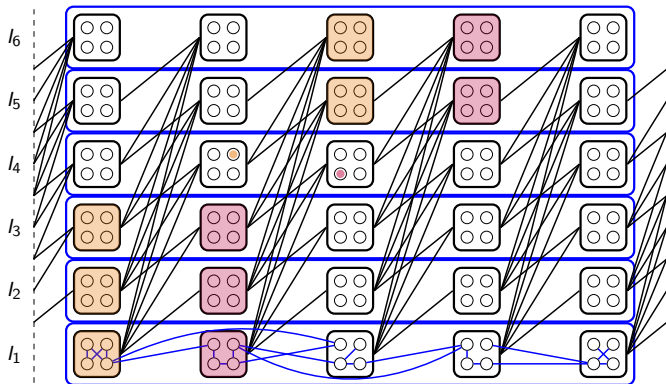


Fig. t Instances \leftrightarrow layers, k partition classes \leftrightarrow boxes



Positive Tailored instance \Rightarrow Positive composition

Assume one instance (I_4 here) is positive, pick its solution in H :

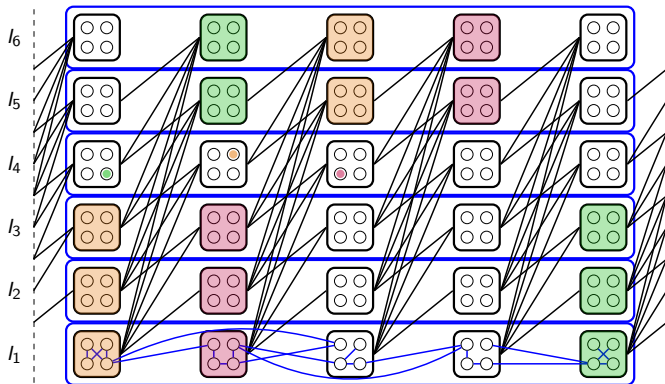


Fig. t Instances \leftrightarrow layers, k partition classes \leftrightarrow boxes



Positive Tailored instance \Rightarrow Positive composition

Assume one instance (I_4 here) is positive, pick its solution in H :

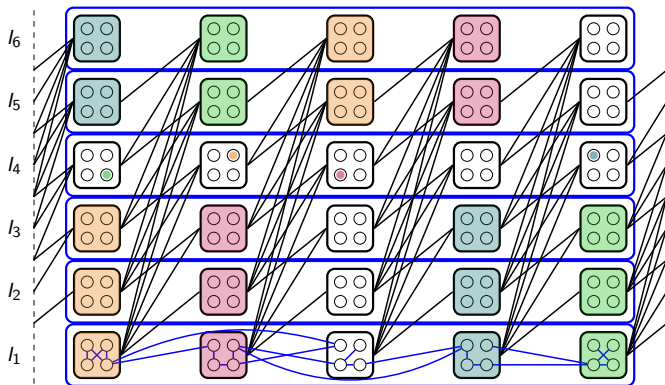


Fig. t Instances \leftrightarrow layers, k partition classes \leftrightarrow boxes



Positive Tailored instance \Rightarrow Positive composition

Assume one instance (I_4 here) is positive, pick its solution in H :

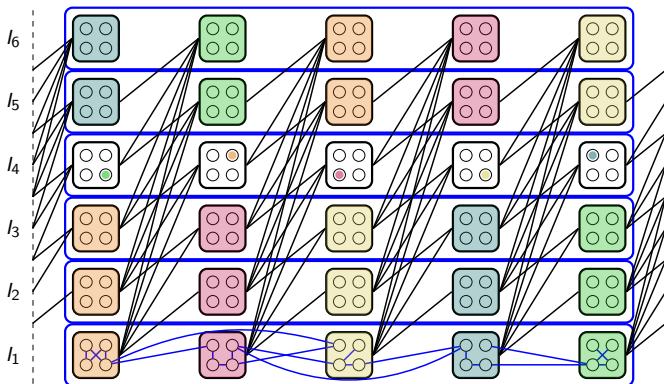


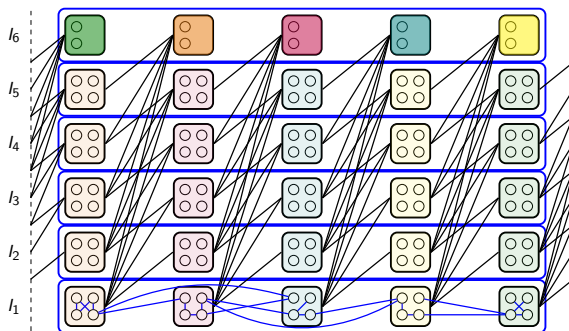
Fig. t Instances \leftrightarrow layers, k partition classes \leftrightarrow boxes



Positive composition \Rightarrow Positive tailored instance

Assume (H, k) is positive:

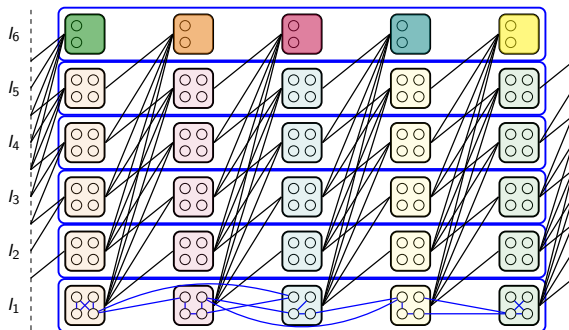
- Dummy instance I_6 forces one vertex per column,



Positive composition \Rightarrow Positive tailored instance

Assume (H, k) is positive:

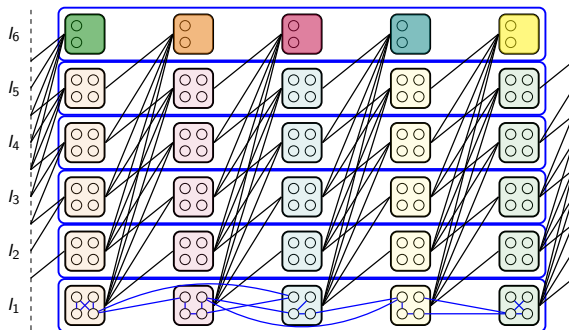
- Dummy instance I_6 forces one vertex per column,
- Ideally : all choices on a single layer $i \rightarrow$ positive I_i ,



Positive composition \Rightarrow Positive tailored instance

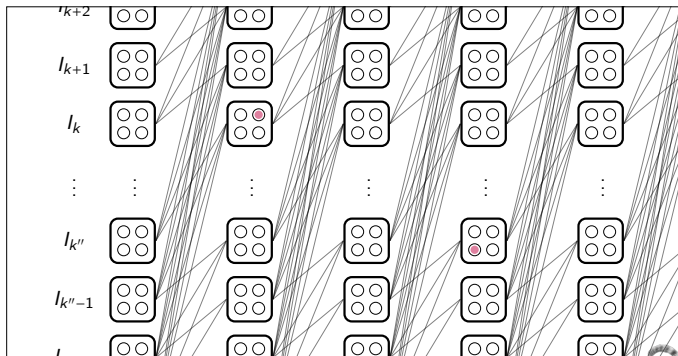
Assume (H, k) is positive:

- Dummy instance I_6 forces one vertex per column,
- Ideally : all choices on a single layer $i \rightarrow$ positive I_i ,
- Assume not...



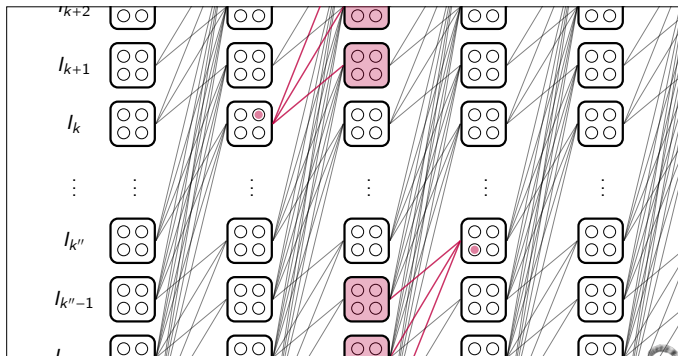
Positive composition \Rightarrow Positive tailored instance

- Non-identical layer choices \rightarrow domination "gap" on C_j ,



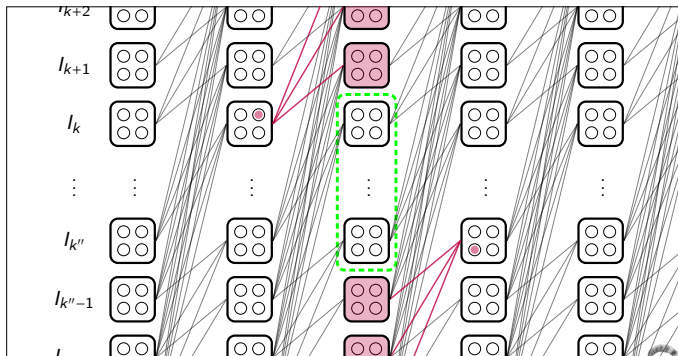
Positive composition \Rightarrow Positive tailored instance

- Non-identical layer choices \rightarrow domination "gap" on C_j ,



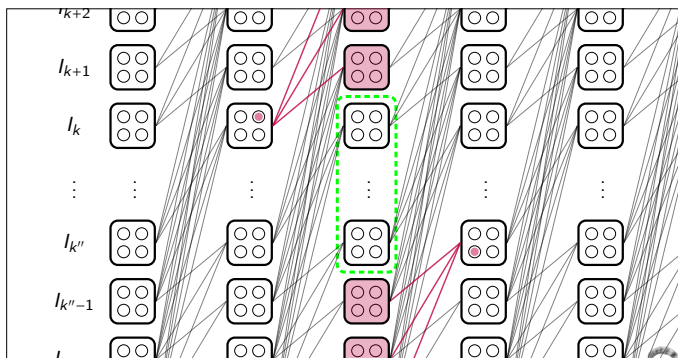
Positive composition \Rightarrow Positive tailored instance

- Non-identical layer choices \rightarrow domination "gap" on C_j ,
- At least two classes not dominated by C_{j-1}, C_{j+1} ,

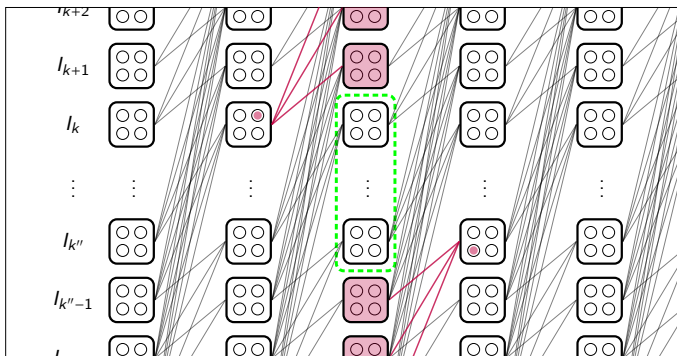


Positive composition \Rightarrow Positive tailored instance

- Non-identical layer choices \rightarrow domination "gap" on C_j ,
- At least two classes not dominated by C_{j-1}, C_{j+1} ,
- Only one choice left in $C_j \rightarrow$ absurd.



Positive composition \Rightarrow Positive tailored instance



Solution lies on a single layer \rightarrow corresponding instance is dominated.



Bounding tww: contracting partition classes

- For any I_i : each partition class has same neighbours in $H - I_i$,

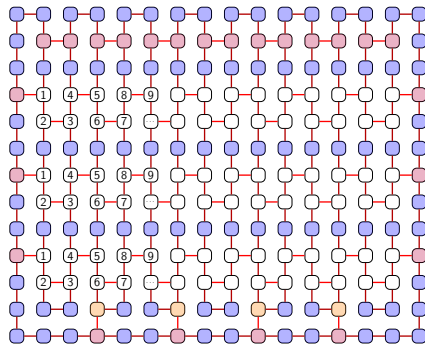


Fig. An instance after contracting classes.



- For any l_i : each partition class has same neighbours in $H - l_i$,
- Contract each class \rightarrow red edges created only in l_i

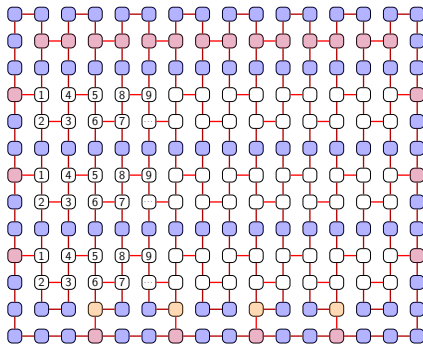


Fig. An instance after contracting classes.



Bounding tww: contracting partition classes

- For any I_i : each partition class has same neighbours in $H - I_i$,
- Contract each class \rightarrow red edges created only in I_i
- Result: red subgraph of grid (altered for *tww* 4).

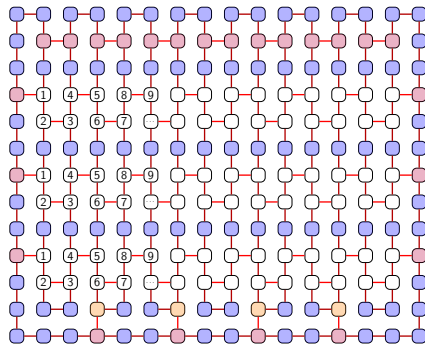


Fig. An instance after contracting classes.



Bounding tww: contracting instances together

- Between instances: half-graph cycle along vertices at the same position.

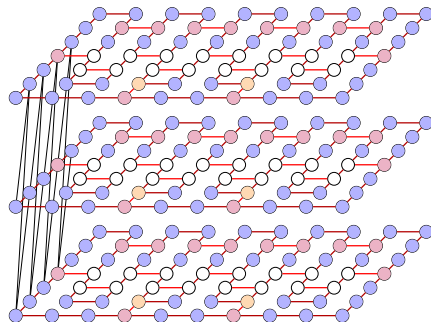


Fig. Instances and the half-graph cycle



Bounding tww: contracting instances together

- Between instances: half-graph cycle along vertices at the same position.
- Goal: Successively contract the bottommost two instances.

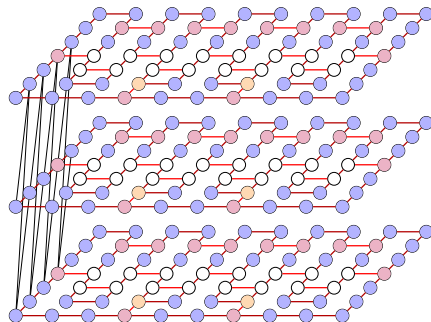


Fig. Instances and the half-graph cycle



Bounding tww: contracting instances together

- Between instances: half-graph cycle along vertices at the same position.
- Goal: Successively contract the bottommost two instances.
- Contracting two vertices at the **same position** creates red edges only **locally** → induction

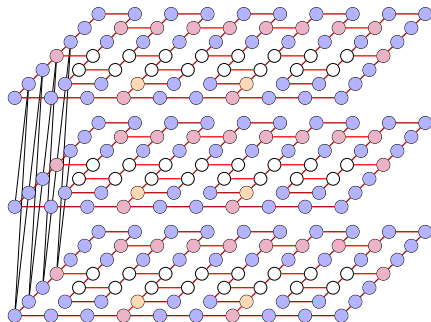


Fig. Instances and the half-graph cycle



Concluding

- NP-hard Tailored k -DS OR-composes into k -DS,

⁵even if a 4-sequence of the graph is given



Concluding

- NP-hard Tailored k -DS OR-composes into k -DS,
- The composed instance has tww at most four.

⁵even if a 4-sequence of the graph is given



Concluding

- NP-hard Tailored k -DS OR-composes into k -DS,
- The composed instance has tww at most four.

Theorem (Bonnet, Kim, R., Thomassé, Watrigant '21)
Unless $\text{coNP} \subseteq \text{NP}/\text{poly}$, k -DOMINATING SET on graphs of twin-width at most 4 does not admit a polynomial kernel⁵.

⁵even if a 4-sequence of the graph is given



Further Directions

- Does k -DS on $\text{tw} \leq 3$ admit polynomial kernels?



Further Directions

- Does k -DS on $\text{tw} \leq 3$ admit polynomial kernels?
- Is there a linear kernel for Connected-VC?



Further Directions

- Does k -DS on $\text{tw} \leq 3$ admit polynomial kernels?
- Is there a linear kernel for Connected-VC?

Thank you!



Bibliography

É. Bonnet, E. J. Kim, S. Thomassé, and R. Watrigant.

“Twin-width I: tractable FO model checking”. In: (2020). arXiv: 2004.14789 [cs.DS]

H. L. Bodlaender, B. M. P. Jansen, and S. Kratsch. “Kernelization Lower Bounds By Cross-Composition”. In: (2012). arXiv: 1206.5941 [cs.CC]

G. Philip, V. Raman, and S. Sikdar. “Polynomial Kernels for Dominating Set in Graphs of Bounded Degeneracy and Beyond”. In: *ACM Trans. Algorithms* 9.1 (Dec. 2012). ISSN: 1549-6325. DOI: 10.1145/2390176.2390187. URL:

<https://doi.org/10.1145/2390176.2390187>

É. Bonnet, E. J. Kim, A. Reinald, S. Thomassé, and R. Watrigant. “Twin-width and polynomial kernels”. In: (2021). arXiv: 2107.02882 [cs.DS]



A (sub)quadratic kernel for C-VC on VC-density 1

Lemma (Bonnet, Kim, R., Thomassé, Watrigant '21)

*There exists f s.t. for any G of $\text{tw}(d)$ and $X \subseteq V(G)$:
number of distinct neighborhoods in X is at most $f(d)|X|$.*



A (sub)quadratic kernel for C-VC on VC-density 1

Lemma (Bonnet, Kim, R., Thomassé, Watrigant '21)

*There exists f s.t. for any G of $\text{tw}(d)$ and $X \subseteq V(G)$:
number of distinct neighborhoods in X is at most $f(d)|X|$.*

Kernel pre-processing:

- Bounded tw G : take X 2-approx for VC,



A (sub)quadratic kernel for C-VC on VC-density 1

Lemma (Bonnet, Kim, R., Thomassé, Watrigant '21)

*There exists f s.t. for any G of $\text{tw}(d)$ and $X \subseteq V(G)$:
number of distinct neighborhoods in X is at most $f(d)|X|$.*

Kernel pre-processing:

- Bounded tw G : take X 2-approx for VC,
- if $|X| \geq 2k + 1$: no solution,



A (sub)quadratic kernel for C-VC on VC-density 1

Lemma (Bonnet, Kim, R., Thomassé, Watrigant '21)

*There exists f s.t. for any G of $\text{tw}(d)$ and $X \subseteq V(G)$:
number of distinct neighborhoods in X is at most $f(d)|X|$.*

Kernel pre-processing:

- Bounded tw G : take X 2-approx for VC,
- if $|X| \geq 2k + 1$: no solution,
- \rightarrow in X , number of distinct neighbourhoods $\leq f(d)k$



A (sub)quadratic kernel for C-VC on VC-density 1

Reduction rule: If there is $S \subseteq V(G) \setminus X$ with identical neighbourhood in X and $|S| > k$, delete a vertex of S .



A (sub)quadratic kernel for C-VC on VC-density 1

Reduction rule: If there is $S \subseteq V(G) \setminus X$ with identical neighbourhood in X and $|S| > k$, delete a vertex of S .

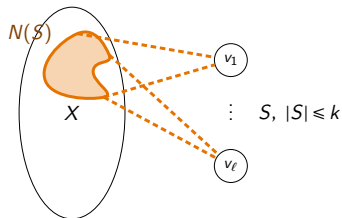


Fig. Resulting instance: (G', k)



A (sub)quadratic kernel for C-VC on VC-density 1

Reduction rule: If there is $S \subseteq V(G) \setminus X$ with identical neighbourhood in X and $|S| > k$, delete a vertex of S .

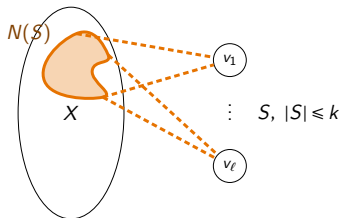


Fig. Resulting instance: (G', k)

If (G, k) has a solution, replace deletion with twin \rightarrow reconnects T



A (sub)quadratic kernel for C-VC on VC-density 1

Reduction rule: If there is $S \subseteq V(G) \setminus X$ with identical neighbourhood in X and $|S| > k$, delete a vertex of S .

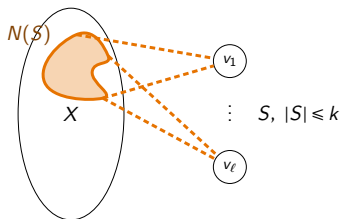


Fig. Resulting instance: (G', k)

If (G, k) has a solution, replace deletion with twin \rightarrow reconnects T
If (G', k) has a solution T , T is also a solution for (G, k) ,



A (sub)quadratic kernel for C-VC on VC-density 1

Reduction rule: If there is $S \subseteq V(G) \setminus X$ with identical neighbourhood in X and $|S| > k$, delete a vertex of S .

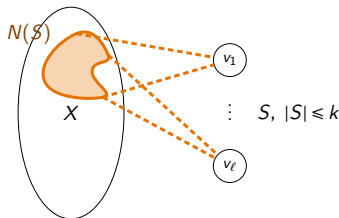


Fig. Resulting instance: (G', k)

If (G, k) has a solution, replace deletion with twin \rightarrow reconnects T
If (G', k) has a solution T , T is also a solution for (G, k) ,

- Take deleted s , $S \setminus s \not\subseteq T$ as ind. set with $|S| \geq k$,
- Therefore $N(S) \subseteq T$, and s is covered by T in G .



Concluding

- Applying the reduction yields an equivalent instance,



Concluding

- Applying the reduction yields an equivalent instance,
- The kernel has size at most $f(d) * k^2$,



Concluding

- Applying the reduction yields an equivalent instance,
- The kernel has size at most $f(d) * k^2$,



Concluding

- Applying the reduction yields an equivalent instance,
- The kernel has size at most $f(d) * k^2$,

Theorem (Bonnet, Kim, R., Thomassé, Watrigant '21)
On classes of VC-density 1, CONNECTED k -VERTEX COVER admits kernels with $O(k^2)$ vertices (and even $O(k^{1.5})$).

